

# Ray of hope for electric paratransit: solar PV charging of sub-Saharan Africa’s urban minibus taxis

C.J. Abraham <sup>a</sup>, A.J. Rix <sup>a</sup>, I. Ndibatya <sup>a,b</sup>, M.J. Booysen<sup>a,\*</sup>

<sup>a</sup>Department of E&E Engineering, Stellenbosch University, South Africa

<sup>b</sup>College of Computing and Information Sciences, Makerere University, Uganda

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## Abstract

Minibus taxi public transport is a seemingly chaotic phenomenon in the developing cities of the Global South with unique mobility and operational characteristics. Eventually this ubiquitous fleet of minibus taxis will have to transition to electric vehicles. This paper examines the impact of this inevitable evolution. We present a generic simulation environment to assess the grid impact and charging opportunities, given the unique paratransit mobility patterns. We used floating car data to assess the energy requirements of electric minibus taxis, which will have a knock-on effect on Africa’s already fragile electrical grids. We used spatio-temporal and solar photovoltaic analyses to assess the informal and formal stops that would be needed for the taxis to recharge from solar PV in the region’s abundant sunshine. The results showed energy demand from a median of 215 kWh/d to a maximum of 490 kWh/d, with a median charging potential (stationary time) across taxis of 7.7 h/d to 10.6 h/d. The potential for charging from solar PV was 0.38 kWh/m<sup>2</sup> to 0.90 kWh/m<sup>2</sup>. Our simulator and results will allow traffic planners and grid operators to assess and plan for looming electric vehicle roll-outs, and could lead to a new funding model for transport in Africa.

*Keywords:* Electric vehicle; paratransit; Minibus taxi; Demand management; Renewable energy

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## 1. Introduction

2 Paratransit plays a vital role as the primary form of transport in sub-Saharan Africa’s public transit  
system. It transports more than 70% of the daily commuters and is a source of livelihood for many fami-  
4 lies (Behrens et al., 2015a). Paratransit in the region takes various forms, such as minibus taxis, motorcycle  
taxis and bicycle taxis (Ehebrecht et al., 2018), with minibus taxis carrying the largest daily share of pas-  
6 sengers (Behrens et al., 2017). Powered by internal combustion engines, the taxis contribute to the emission  
of greenhouse gases and a general decline of air quality in African cities (Collett and Hirmer, 2021).

8 Paratransit in Africa’s developing countries differs substantially from that of developed countries, from  
its inception to its vehicle types to its operations. In developed countries, paratransit usually means a point-  
10 to-point flexible demand-responsive transport service customised with special requirements for the elderly  
and the disabled (Behrens et al., 2017; Askari et al., 2021). The Americans with Disabilities Act of 1990, for  
12 example, requires paratransit drivers to be trained and paratransit vehicles to be equipped with specialised  
lifts, doors, seating, a global positioning system (GPS) and dispatch systems (ADA, 1990). For Africa’s  
14 developing countries, paratransit means an organically evolved, informal, market-oriented, self-organising ur-  
ban transport service that operates somewhere between private passenger transport and conventional public  
16 transport in terms of cost, scheduling, routes and quality of service (Ndibatya and Booysen, 2021; Neumann  
and Joubert, 2016). Here the paratransit system consists of shared-ride, demand-responsive privately owned  
18 vehicles, such as the minibus taxis in Lagos, Johannesburg, Nairobi and Kampala, or the single-passenger mo-  
torcycle taxis (“boda bodas”) in Kampala, or the tricycle taxis (“tuk-tuks”) in Nairobi (Mutiso and Behrens,  
20 2011; Booysen et al., 2013; Diaz Olvera et al., 2019). Travel by paratransit accounts for approximately 70%,  
90%, 91%, and 98% of the road-based public trips in Johannesburg, Lagos, Kampala and Dar es Salaam,

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\*Corresponding author

Email address: [mjbooyesen@sun.ac.za](mailto:mjbooyesen@sun.ac.za) (M.J. Booysen )

22 respectively (Behrens et al., 2015b; Evans et al., 2018). Of these paratransit passenger trips, 83% are by  
minibus taxi (Dorothy et al., 2016; KCCA, 2016; Evans et al., 2018).

### 24 1.1. *The revolution in sub-Saharan Africa's paratransit*

In sub-Saharan Africa, the public transport industry experienced two fundamental organic changes in the  
26 last quarter of the nineteenth century. The first was the shift of transport services proprietorship, from public  
to private, most often sole proprietorship, as a result of the World Bank's structural adjustment policies of the  
28 1990s that restricted financing to state-owned entities, leading to their eventual collapse (Kumar, 2011; Ajay  
Mahaputra Kumar et al., 2008; Cervero and Golub, 2007). The second was the gradual introduction of low-  
30 capacity (five- to twenty-seater) passenger-carrying vehicles to fill the public transport vacuum (Diaz Olvera  
et al., 2019; Mutiso and Behrens, 2011; Behrens et al., 2015a; Jennings and Behrens, 2017). From the five  
32 seater Anglia (Ford cars of the 1970s), to the 10-seater Peugeot 204 (1980s), to the current 16-seater Toyota  
HiAce, paratransit service vehicles have been of many types in many countries. Since the 1990s, the fourth  
34 and fifth generations (H100 1989-model and H200 2004-model) of the Japanese Toyota HiAce have dominated  
the paratransit market in Africa. The Toyota HiAce trades under several names depending on the country of  
36 assembly, such as Toyota Quantum in South Africa and Toyota Ventury in Thailand. Originating simply as  
a complementary transport service, the minibus taxis have become a way of life for the urban poor in several  
38 African cities.

Two competing views have broadly shaped discourse on the minibus taxis as part of the paratransit  
40 system in Africa. The predominant view is that minibus taxis and paratransit in general are the most extreme  
example of public transport failure in the developing world (Lucas et al., 2019). To support this view, terms  
42 such as "chaotic", "unsustainable", "unsafe" and "pollutants" are common in the literature in reference to  
the minibus taxis (Venter et al., 2019; Pojani and Stead, 2017, 2018; Agbiboa, 2016). In fact, the contribution  
44 of minibus taxis to urban air pollution is significant, partly because they are old (often older than 20 years)  
and they stand idling their engines for long hours, thus hugely contributing to greenhouse gas emissions and  
46 the deteriorating air quality in African cities. The World Health Organisation classifies exposure to ambient  
air pollution (AAP) as a major threat to human health in sub-Saharan Africa, linking it to the increase in  
48 cardiovascular and cardiopulmonary diseases and lung cancer and respiratory infections (Dalal et al., 2011;  
Amegah and Agyei-Mensah, 2017). Consequently, proponents of this view advocate for a total overhaul of the  
50 minibus taxi industry and its replacement with the western idea of orderly transport, the bus rapid transit  
(BRT) system.

52 Proponents of the second view advocate for a hybrid future, with paratransit complementary to the sched-  
uled BRT. However, the adoption of this view is very slow and facing much resistance from the paratransit  
54 operators. Although several benefits would accrue to them (such as job security for the drivers, proper regu-  
lation, and government subsidies) they would lose their autonomy and the elements of self-organisation that  
56 formed the core of the original paratransit in Africa.

An alternative third view is emerging, which imagines Africa's paratransit system as a complex adaptive  
58 system, composed of many interdependent components that interact non-linearly, often operating between  
"chaotic" and semi-orderly states (Behrens et al., 2015b; Goodfellow, 2017). This view acknowledges the  
60 coping mechanisms and innovative forms of self-organisation exhibited by paratransit and how the system  
adapts to serve the population's mobility needs with little or no centralised control. Actually paratransit  
62 "chaos" reveals to some degree the hidden order described by Hecht as the "invisible governance ... that  
maintains competing agendas and aspirations in some kind of functional and parallel existence" (Hecht, 2007).

64 The minibus taxi paratransit came into being to suit the mobile lifestyle of the urban poor in sub-  
Saharan Africa. It is unlikely that the minibus taxis will be phased out of Africa's cities any time soon.  
66 They are ubiquitous and will continue for many reasons: their schedule flexibility, the urban sprawl, the  
irregular commuter movement patterns in urban spaces due to informal employment and the socio-cultural  
68 lifestyles of the urban poor in developing cities. However, the environmental cost of running these old internal  
combustion engine vehicles is worrying. It has triggered discussions about the possibility of transitioning to  
70 electric minibus taxis as part of the global electrification and sustainability agenda (Collett and Hirmer,  
2021).

### 72 1.2. *The transition to electric vehicles and the electric minibus taxi*

The development of low-carbon transport in cities is crucial to the global agenda to combat climate  
74 change's various effects sustainably. The Intergovernmental Panel on Climate Change (IPCC) estimates that

76 the transport sector generates 23% of the global energy-related greenhouse emissions. In sub-Saharan Africa  
77 the deteriorating air quality resulting from ambient air pollution and a high concentration of particulate  
78 matter (PM<sub>2.5</sub>) is partly attributed to vehicle emissions (Lozano Gracia et al., 2021; Singh et al., 2020;  
79 Rajé et al., 2018). The WHO estimated that 712,000 deaths in Africa in 2012 were due to air pollution,  
80 though the figure may be higher than reported because air pollution epidemiological data is limited (Cohen  
81 Aaron J et al., 2017). Akumu estimates the cost of air pollution in African cities to be as high as 2.7% of  
82 GDP (Akumu, 2014). Three of the seventeen United Nations Sustainable Development Goals, one, eleven  
83 and thirteen, are clean energy, sustainable cities and climate action (Zinkernagel et al., 2018).

84 Consequently, electrification is promoted as a low-carbon transport strategy to reduce combustion emis-  
85 sions and slow down the possibly damaging effects of climate change. In the same spirit, the transition to  
86 electric vehicles is gradually picking up in developing countries to the extent that some vehicle manufacturers  
87 are planning to phase out internal combustion engines. Sub-Saharan Africa is seeing a few isolated pilot elec-  
88 tric vehicle projects, mainly focusing on micro-mobility (as motorcycles and tricycles), as well as buses and  
89 private cars (Black et al., 2018). At present, there is no known electric vehicle transition initiative targeting  
90 the paratransit industry, let alone the minibus taxis that are responsible for more than 80% of the public  
91 transport trips in the region.

92 This paper builds a foundation for evaluating the eventual impact of the transition to electric minibus  
93 taxis on cities’ electrical grids, localised pollution, carbon footprint and taxi owners’ profitability. Specific  
94 attention is given to the energy requirements of these vehicles, the potential distribution of charging stations  
95 and the potential electricity generation capacity from renewable sources.

### 96 *1.3. Overview of earlier studies and approaches*

97 Initiatives to achieve sustainable urban mobility often follow a three-pronged transport decarbonisation  
98 approach, the “Avoid-Shift-Improve” paradigm (Galuszka et al., 2021; Lah, 2017). This approach aims  
99 to reduce trips, shift towards public transport and non-motorised modes and improve vehicle efficiency  
100 coupled with electrification (Le and Trinh, 2016; Osei et al., 2021). In sub-Saharan Africa, the avoid and  
101 shift approaches have not been intensively studied (Krüger et al., 2021). The focus has been primarily on  
102 improvements: urban traffic management strategies such as widening roads, optimising road signalling and  
103 encouraging multi-modal transport (developing mass transit systems such as BRT and promoting walking  
104 and cycling) (Sietchiping et al., 2012; Shams and Zlatkovic, 2020; Krüger et al., 2021; Venter et al., 2018).  
105 Ironically, evidence from other world cities suggests that building freeways and roads around cities only  
106 increases car dependence and thus intensifies congestion and pollution (Sietchiping et al., 2012). Improving  
107 vehicle efficiency, particularly by introducing electric vehicles in public transport and paratransit, is an  
108 approach that has been neglected. The literature on paratransit in sub-Saharan Africa focuses on aspects  
109 of sector governance (Goodfellow, 2017) and regulation and reforms (Jennings and Behrens, 2017; Lucas  
110 et al., 2019), but seldom on operations (Ndibatya and Booysen, 2020), mobility characteristics (Ndibatya  
111 and Booysen, 2021) and the prospects of electric mobility integration (Galuszka et al., 2021).

112 Research from outside the region shows that electric vehicles are three times more efficient than internal  
113 combustion engine vehicles and twice as efficient as hybrid vehicles (Du et al., 2017; Weiss et al., 2020). This  
114 efficiency is achieved partly by the efficient braking systems and elimination of idling losses and the consequent  
115 saving of energy for the vehicle’s actual movement (Weiss et al., 2020). Although debate continues on the  
116 economic and environmental trade-offs associated with electric vehicles (Li et al., 2016), there is evidence of  
117 sustainable electric vehicle deployment. Some researchers argue that deploying electric vehicles shifts gasoline  
118 usage to coal-fired power generation, which exacerbates CO<sub>2</sub> emissions by the power systems (Li et al., 2016).  
119 However, electric vehicle proponents counter-argue that, on a macro-scale, these vehicles’ impact in terms of  
120 CO<sub>2</sub> emissions depends mainly on the charging strategy and that the emissions can be reduced by optimising  
121 the use of renewable energy sources such as solar power (Schücking et al., 2017; Buresh et al., 2020). In one of  
122 the scarce and isolated publications on electric vehicles in sub-Saharan Africa, Buresh et al. (2020) note that  
123 South Africa (like many countries in the region) has high levels of insolation (the measure of solar energy at a  
124 place over a specified time), from between 4.5 and 6.5 kWh/m<sup>2</sup> per day, with annual sunshine averaging more  
125 than 2500 hours. This implies that the region has an excellent chance of harnessing this renewable energy  
126 source to power electric vehicles. Indeed, projects researching alternative renewable energy have taken shape  
127 in the region (Jadhav et al., 2017), though not targeting electric vehicles for public transport services.

Two main research gaps remain in the literature on sub-Saharan Africa’s transition to electric minibus taxis. One is the mobility characteristics of minibus taxis. As Quirós-Tortós et al. (2018) observe, to estimate the charging requirements and vehicle performance of an electric vehicle we need to know its mobility patterns, such as distance, travelling time and idle time (or stopping time and duration). In other words, the vehicle’s mobility has spatio-temporal dimensions. Apart from the findings of isolated studies on minibus taxi mobility, such as those by Ndibatya and Booysen (2021), the general mobility dynamics of paratransit in sub-Saharan Africa are unknown. The other is the region’s potential for renewable energy from different sources such as solar PV, wind and bio-fuel as part of this transition (Sawadogo et al., 2020; Jadhav et al., 2017; Soares et al., 2019).

From the sparseness of the work, it is clear that we lack information on the mobility of minibus taxis in sub-Saharan Africa and specifically the requirements of these minibus taxi fleets if they are converted to electric vehicles (Collett and Hirmer, 2021). Our reproducible method for determining their mobility and analysing the generated data will fill the gap and help city planners as well as fleet owners to improve their future operations.

#### 1.4. Contribution

This paper explores the energy requirements of electric minibus taxis in an urban paratransit system, on journeys within and between towns and cities. Over a year’s worth of floating car data was analysed to assess the energy demand of minibus taxis. The paper explores the potential charging opportunities at the formal and informal organically formed taxi stops during the daytime when charging with solar PV is feasible. Our method is applied to a case study in an urban scenario near Cape Town in South Africa, and we contribute our integration and stop extraction software, which can be used to perform similar evaluations. Finally, we assess the impact on the struggling South African grid of converting all the minibus taxis in South Africa to electric vehicles, with and without solar augmentation.

## 2. Method

This section describes the dataset and the three models used for the research: the minibus taxi (MBT) mobility model, the photovoltaic (PV) model and the electric minibus taxi (eMBT) electric vehicle (EV) model. It describes the pre-experimental collection and analysis of the floating car data from a fleet of nine internal combustion engine minibus taxis. Inter-town MBT mobility modelling involved spatial clustering of floating car data to identify stopping events and generate routes between stops in preparation for PV and eMBT modelling. We present two model simulation setups for the EV and PV models and discuss their application to our urban paratransit context. The PV model was based on the System Advisor Model (SAM) developed by the National Renewable Energy Laboratory (Blair et al., 2014). We ran the PV and the EV models independently in a micro-transport simulator (SUMO) (Lopez et al., 2018; Kurczveil et al., 2014), then recorded and analysed the eMBT energy and PV requirements for each simulated context.

### 2.1. Mobility

The dataset consisted of floating car data obtained by tracking urban minibus taxis operating on bi-directional routes connecting Stellenbosch, Brackenfell and Somerset West in the Western Cape Province of South Africa. The area under study is defined by coordinates are (34.229224, 18.656884) and (-33.786222, 18.969438) as shown in Figure 1a. The data obtained from Mix Telematics (a local fleet management service provider), consisted of timestamped geo-locations (latitude and longitude), speed and direction, logged at a frequency of one minute from onboard tracking devices for over two years. After cleaning, filtering and performing pre-data loading preparations, we had an average of 201 days’ worth of floating car data per minibus taxi for use in EV and PV modelling.

#### 2.1.1. Spatial clustering and analysis

An overlay heatmap showing the intensity variation of minibus taxi activity (based on the count of GPS data points) was plotted as shown in Figure 1a. Three high-intensity areas were visible in the heatmap: Stellenbosch, Brackenfell (west of Stellenbosch) and Somerset West (south of Stellenbosch). We interpreted these three areas as the epicentres of minibus taxi activity, a view that closely matches that of Ebot Eno Akpa et al. (2016).

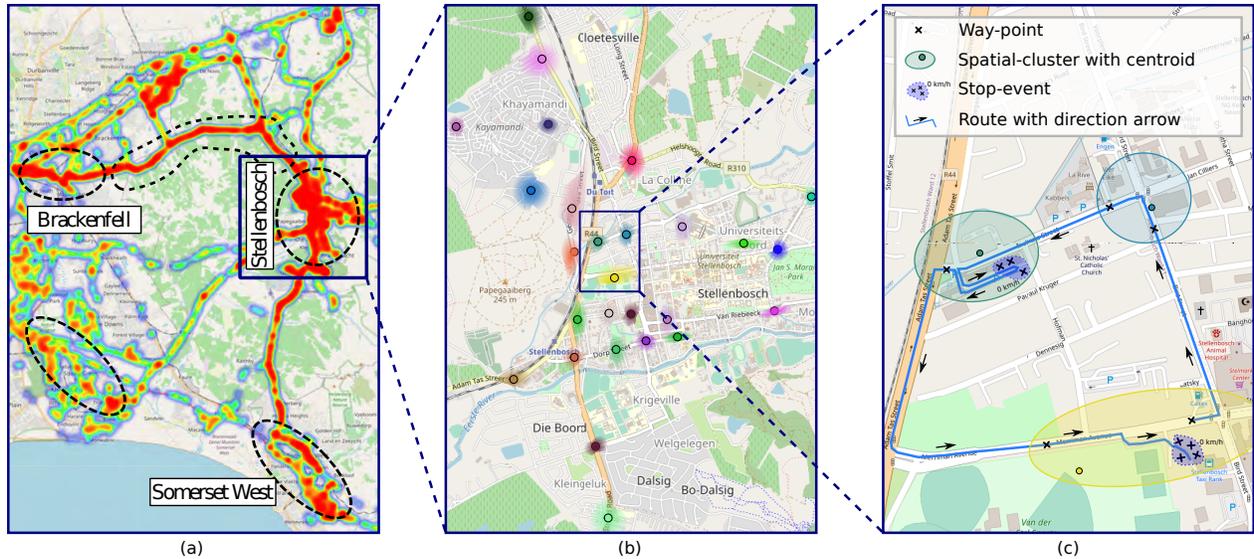


Figure 1: (a) Heat map showing the variation (by density) of floating car data; (b) Distribution of spatial-clusters in Stellenbosch as determined by the clustering process; (c) Illustration of *way points*, *stop events* and route generation process.

176 We used the density-based spatial clustering of applications with noise (DBSCAN) algorithm to group  
 178 high-density closely related data points (or geo-locations), forming spatial clusters of data points that rep-  
 180 resented significant events (such as stopping and movement ) during normal minibus taxi operations. We  
 182 chose the DBSCAN algorithm because of its robustness to outlier detection, its ability to discover clusters  
 184 with uneven densities and arbitrary shapes, and the fact that it does not need prior knowledge of the number  
 of clusters (Liu et al., 2012; Renjith et al., 2020). For cluster analysis we used a Python implementation  
 of the DBSCAN algorithm from the Scikit-Learn package (Pedregosa et al., 2011). The minimum cluster  
 size (`min_samples`) was 70, and the maximum distance between neighbouring points in a cluster (`max_eps`)  
 was  $0.0002^\circ$  (Ndibatya et al., 2014). Figure 1b shows the spatial distribution of cluster centroids overlaid on  
 OpenStreetMap.

### 186 2.1.2. Identifying minibus taxi stops

188 To generate the mobility patterns and establish the potential for charging at stops, it was necessary to  
 190 identify the spatial clusters with stopping events. Additional temporal analysis was required to determine  
 192 the stop times and stop durations. We therefore further analysed each spatial cluster to identify sets of data  
 194 points representing either a *stop event* or a *movement event* within the cluster’s spatial extent. A *stop event*  
 196 in our work is closely related to a “stay point” as defined by Zheng et al. (2009) and Damiani et al. (2014) and  
 refers to a series of consecutive GPS locations within a cluster’s spatial extent, with a taxi velocity below a  
 threshold of 1 km/h. The arrival time of the stop event is the time of the first GPS location in the series, and  
 the duration of the stop-event is the difference between the timestamps of the first and last GPS locations  
 in the series as illustrated in Figure 1c. The *movement events* (or waypoints) represented by all the cluster  
 data points that do not belong to the ‘stop event’ category were preserved for use during minibus taxi route  
 generation in the EV model.

198 For each spatio-temporal cluster we generated a statistical summary describing the total number of stop  
 200 events, average stop arrival time, average stop duration, and the standard deviations from these. The  
 202 statistical summary helped to identify the spatia clusters with the most stop events and their typical time  
 and duration. We were thus able to identify spatial clusters with many stop events as formal taxi stops  
 (terminuses). Spatial clusters with lower counts could be identified as intersections where the taxis pause for  
 204 traffic, or informal stops made en route to pick up passengers. Clustering the stop events temporally also  
 helped to identify the times when these stops typically occurred.

### 2.1.3. Generating routes

206 To simulate the mobility of MBTs between the three towns and subsequently study their energy require-  
208 ments, we generated the routes linking the identified stops. A *route* in this context is a series of edges  
connecting two or more stop events, often starting and ending in different clusters (or cluster centroids). A  
simulated MBT follows pre-selected routes as part of its daily route plan within the simulation boundary.

210 We used the stop events' cluster centroids, the waypoints (GPS data representing moving events), the  
roads network, and SUMO's shortest path Dijkstra algorithm to generate the routes. The underlying road  
212 network was based on OpenStreetMaps (OSM) (OpenStreetMap contributors, 2017), which included the  
roads, intersections, speed limits, and traffic lights information. All the GPS data points (including cluster  
214 centroids and waypoints) were snapped to the OpenStreetMap's road network, and the shortest path between  
the origin and destination points of interest was computed using SUMO's implementation of the Dijkstra  
216 algorithm (Lopez et al., 2018). This algorithm searches for the route with the least *cost* (Lewis, 2020), where  
the *cost* can be the distance, time, or electricity consumption of the simulated EV. In this study, we defined  
218 the cost as the *distance* (we omitted speed due to simulation performance considerations). For each simulated  
day we generated a route, and from these routes we computed extra information that affects an EV's (or  
220 eMBT's) energy usage, such as the total distance, the road inclination and the road curvature.

### 2.2. The eMBT EV model

222 We set up a simulation model using a custom SUMO electric vehicle simulation model, SUMO EV, to  
measure the temporal variation of power and energy usage and the relationships between power consumption  
224 and eMBT speed. The model's parameters were specified to match the prevailing MBT used in South  
Africa, the Toyota Quantum. The weight and front surface area used for a synthetic eMBT were measured  
226 from one of the Toyota Quantum minibus taxis operating in Stellenbosch. We approximated the rest of the  
parameters according to the recommendations by Fridlund and Wilen (2020). These parameters include:  
228 height 2.3 m, width 1.9 m, front-facing surface area 4 m<sup>2</sup>, weight 2900 kg, constant power intake 100 W,  
propulsion efficiency 0.8, recuperation efficiency 0.5, roll drag coefficient 0.01 and radial drag coefficient 0.5.  
230 The simulation program initialised the eMBT model for each date that was simulated. The eMBT model  
was applied to the generated routes. For every second of simulation time, the simulator logged the energy  
232 consumption and speed of the eMBT as it progressed along its route.

With an average of 201 routes per taxi, the volume of output data from the model was huge. Our goal  
234 was to obtain useful metrics that would summarise this data. The first metric we considered was the average  
power usage profile of the whole eMBT fleet. Such a profile would indicate how much power the eMBTs used  
236 at various points in time. This profile would be indispensable, for example, for testing the hypothesis that  
there would be a good charging opportunity at midday. It would also show what order of magnitude the  
238 motor size should be. We calculated the profile by obtaining the power-vs-time profile for each day, averaging  
this across all days for each eMBT, and then averaging that across all eMBTs in the fleet. The profile was  
240 plotted with respect to time.

### 2.3. PV model simulation setup

242 We set up the SAM-based PV model to calculate the energy available from photovoltaic sources and to  
study the daily charging potential for each eMBT in a synthetic fleet of nine eMBTs. The model generates  
244 the plane-of-array solar irradiance profile based on radiometric data, solar azimuth angle, and photovoltaic  
panel tilt angle. We used radiometric data for a year sampled every 15 minutes from the National Solar  
246 Radiation Database (Sengupta et al., 2018). The azimuth and tilt angles were set at 0°(North) and 20°,  
respectively, a common configuration which maximises energy yield in South Africa (Le Roux, 2016).

248 To get the output power profile of the PV array, a 16% system efficiency was applied to the irradiance  
profile, i.e., 20% and 80% were used for the solar panel and balance of the system (including the inverter),  
250 respectively. We used the stop event analysis from Section 2.1.2 to further analyse the battery charging  
potential from solar PV by evaluating the times at which the stop events occurred and their durations. We  
252 first applied thresholds to filter out stop events with durations above 8 hours or below 20 minutes. This was  
to ensure that stop events irrelevant to our study did not skew the statistics. These stop events were grouped  
254 according to the spatial cluster in which they occurred, and temporal clustering was done within each spatial  
cluster to obtain spatio-temporal clusters.

256 Based on the stop events detected during the spatio-temporal clustering, we computed the potential  
 258 energy sourced from PV per day. For each eMBT stop event, the PV output-power-profile was integrated  
 260 from the beginning to the end of the stop event in order to calculate the total energy that could be charged  
 262 from PV during that stop event. The PV energy of each stop event was summed to get the total energy that  
 could be charged from PV for that day as a function of the area of the PV array. These “daily PV charging  
 potentials” were aggregated for each taxi and plotted as box plots. This metric allowed us to approximate  
 the size of the PV array required to provide a certain percentage of an eMBT’s energy demands.

### 3. Results and discussion

264 This section describes the results obtained from applying our three models to the floating car data from  
 Stellenbosch and its surrounds. The results obtained refer specifically to the MBT mobility, the eMBT’s  
 266 power requirements and the potential charging opportunities. The charging opportunities are separated into  
 stop times for the purpose of source-ambivalent charging, and potential charging from PV.

268 The inter-town MBT mobility modelling provides spatial clustering of the identified stop events that  
 serve as input to the PV modelling while generating routes used to determine the power requirements of the  
 270 individual eMBT and the fleet of eMBTs.

Table 1: Summary of the MBT stop events identified during the cluster analysis. The clusters are grouped by vehicle ID and sorted by duration in descending order. The vehicles with boldfaced IDs were plotted in Figure 2. (Note:  $\mu$  = Mean,  $\sigma$  = Standard deviation)

Minibus Taxi ID	Spatio-temporal Cluster ID	Stop events count	Arrival (h)		Duration (h)		Terminus Name
			$\mu$	$\sigma$	$\mu$	$\sigma$	
T1000	C101	302	12.0	4.8	<b>1.5</b>	1.2	North
	C102	309	14.1	3.1	<b>1.4</b>	1.2	Central
	C104	15	17.4	1.3	0.7	0.3	South
	C103	18	7.1	0.4	0.5	0.2	South
<b>T1001</b>	C111	1074	12.9	5.3	<b>1.5</b>	1.1	North
	C112	782	14.6	3.2	<b>1.2</b>	1.1	Central
	C114	41	16.6	1.4	0.7	0.4	South
	C113	17	7.1	0.4	0.5	0.2	South
<b>T3001</b>	C311	686	12.5	4.7	<b>1.5</b>	1.2	North
	C312	689	14.2	3.4	<b>1.2</b>	1.0	Central
	C314	87	16.1	1.3	0.7	0.3	South
	C313	37	7.2	0.4	0.5	0.1	South
T4000	C402	495	14.2	3.4	<b>1.5</b>	1.4	Central
	C401	406	11.8	4.5	<b>1.3</b>	1.0	North
	C404	42	16.4	1.0	0.6	0.2	South
	C403	29	7.0	0.4	0.5	0.1	South
<b>T5000</b>	C501	787	10.5	4.3	<b>1.3</b>	1.1	North
	C502	709	14.7	3.4	<b>1.2</b>	1.0	Central
	C503	139	16.3	1.0	0.6	0.2	South
	C504	30	7.4	0.4	0.5	0.2	South
T6000	C601	34	8.5	0.4	<b>5.9</b>	1.0	North
	C602	82	16.6	1.1	<b>1.1</b>	0.8	North
	C603	52	7.1	1.0	<b>1.0</b>	0.6	North
T6001	C611	403	12.4	4.7	<b>1.4</b>	1.1	North
	C612	359	14.1	3.3	<b>1.3</b>	1.2	Central
	C613	11	7.2	0.5	0.5	0.2	South
	C614	8	17.6	1.0	0.5	0.2	South
T7000	C702	904	14.3	3.2	<b>1.3</b>	1.1	Central
	C701	765	10.7	4.1	<b>1.3</b>	1.1	North
	C704	30	16.5	1.5	0.6	0.3	South
	C703	33	7.0	0.4	0.5	0.2	South
T7001	C712	430	15.0	3.7	<b>1.4</b>	1.1	Central
	C711	272	12.0	4.9	<b>1.1</b>	0.9	North

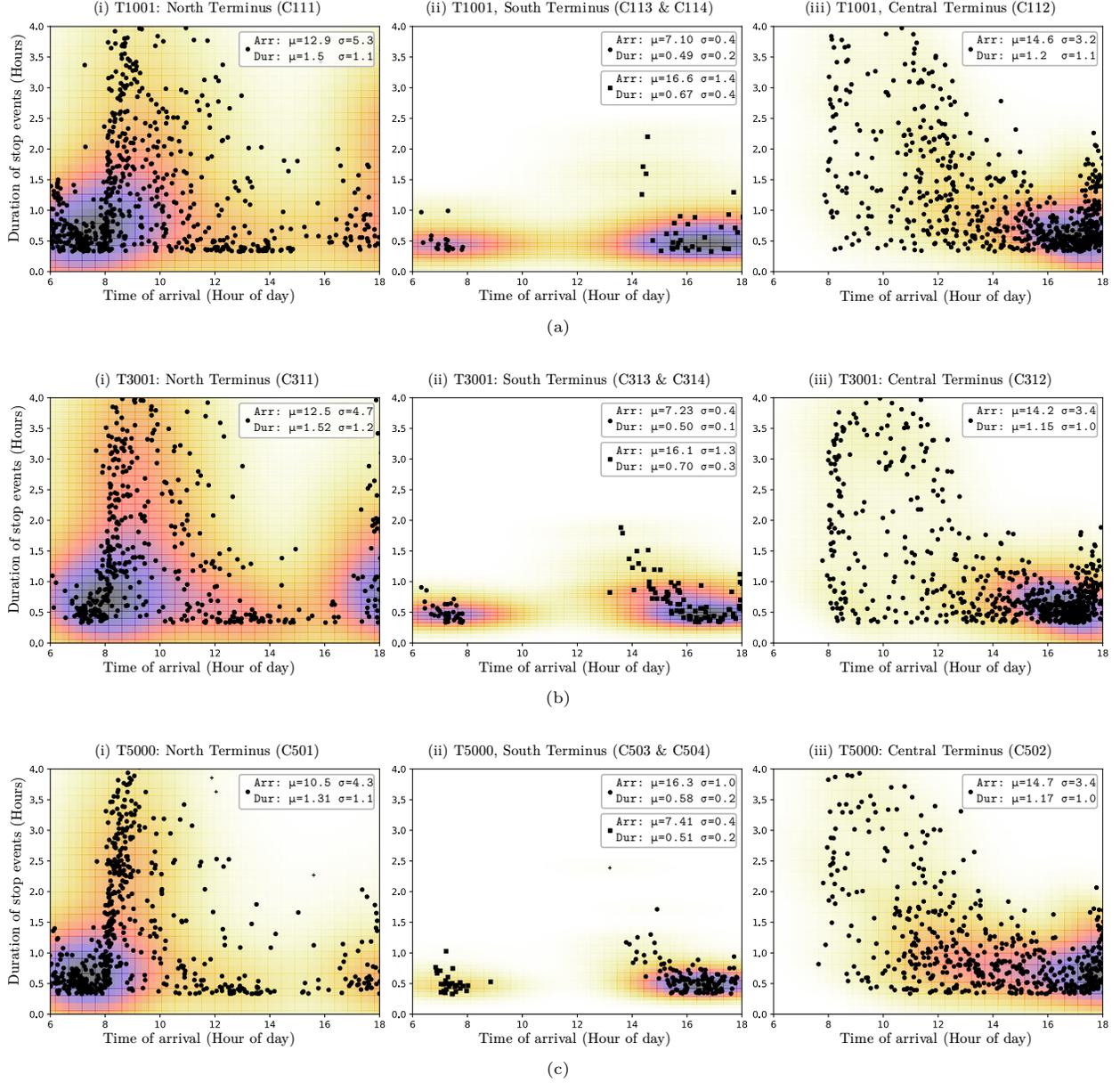


Figure 2: Spatio-temporal clustering of arrival time and duration of stops at significant spatial-clusters for three MBTs: (a) T1001; (b) T3001; (c) T5000. *North, South and Central termini* refer to the spatial-clusters situated near termini found in Kayamandi in Stellenbosch, Somerset West, and Stellenbosch Central, respectively.

### 3.1. Mobility analysis

Figure 2 shows the results of the spatio-temporal clustering of data from three minibus taxis to determine the stops. Despite the seemingly chaotic patterns, the clustering analysis identified spatio-temporal clusters of stops. The figure shows how each minibus taxi has a vertically distributed (i.e. varying duration) morning cluster at around 8:00 am, and a horizontally distributed (i.e. varying arrival time) cluster in the evening. For example, the spatio-temporal clusters in the South Terminus indicate that those spatial clusters were visited in the morning and in the evening.

The spatio-temporal clusters were primarily used in SUMO to generate the traffic simulator’s mobility patterns and then analyse the charging potential during stationary periods. A statistical summary of all the identified stop clusters, showing the stationary periods during daylight hours grouped by taxi, is provided in Table 1. Although the standard deviation is substantial, the mean stop durations of the clusters were more than one hour for at least two stops per taxi. The arrival times of the longer stops were all between 10:30 am and 3:00 pm except for one outlier taxi T6000, which exhibited wildly different clustering results. Accordingly, the clusters indicate that there should be substantial potential for charging from solar power.

### 3.2. Energy analysis

The output of the EV simulation is shown in Figure 3. The mean instantaneous power demand versus time of a working weekday is shown in Figures 3a. A clear typical temporal profile is apparent for the minibus taxis, closely matching the peak traffic hours. There is a sharp peak demand period from 6:00 am to 9:00 am, with a peak value of 32 kW. A diminished demand with a mean of 6 kW is observed from 9:00 am to 1:00 pm, constituting a period of substantially reduced activity, further demonstrating the potential for solar charging. This is followed by a gradual increase to a less pronounced peak value of 30 kW between 5:00 pm and 6:00 pm. This flatter evening demand profile slowly declines to return to the trough of 7 kW by 9:00 pm. Complete inactivity is observed from 11:30 pm to 4:30 am. Not only is this profile clearly defined, but the variation between taxis, shown by the minimum and maximum profiles in the shaded area, is minimal. The only substantial deviation is the increase in the maximum profile just after 9:00 pm, which results from the long-distance journeys over weekends (departing at 9:00 pm on Friday evenings) and holidays, as reported by Ebot Eno Akpa et al. (2016).

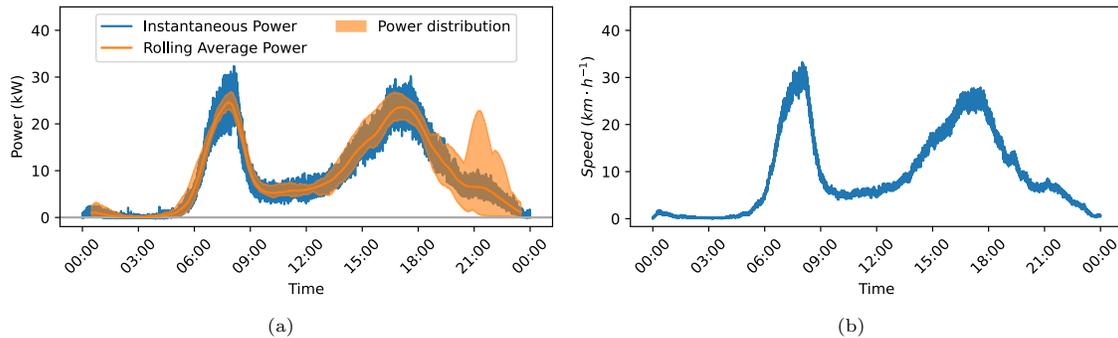
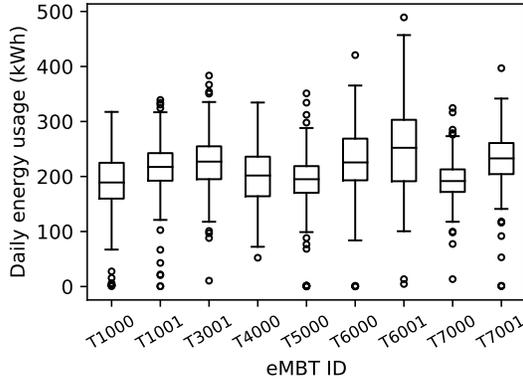


Figure 3: Summary of electrical for all the simulated eMBTs (a) Daily power (instantaneous and rolling average) sampled per second; (b) Speed vs time

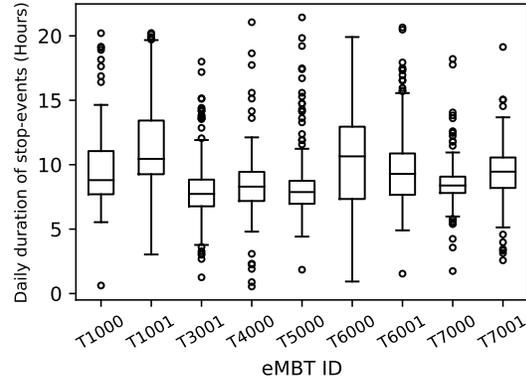
This profile indicates the energy demand profile requirements of the eMBTs, and already hints at substantial charging potential during the evening – probably from grid power – and during the middle of the day – preferably from solar power.

Figure 3b shows the MBT’s speed versus time of the day, the similarity of which highlights the substantial impact of speed on power draw. The energy required was close to linearly proportional to the distance travelled, which demonstrates that a simpler distance-based model would have provided good estimations and required substantially less processing power. The mean energy required per day is 212 kWh.

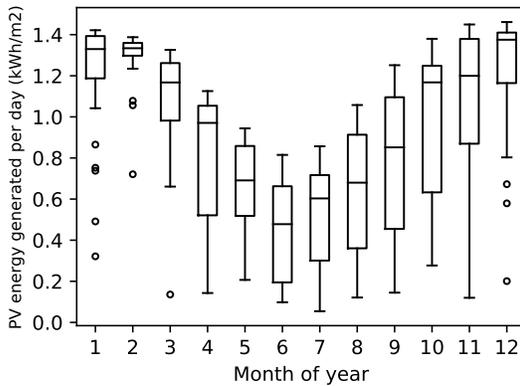
The distribution of energy usage per taxi per day, is shown in Figure 4a for the nine taxis. The taxis’ energy usage is similar, with the median energy per taxi per day across all taxis ranging from 189 kWh to 252 kWh, with the mean of the medians equal to 215 kWh. For any given taxi, on 75 % of the days less than



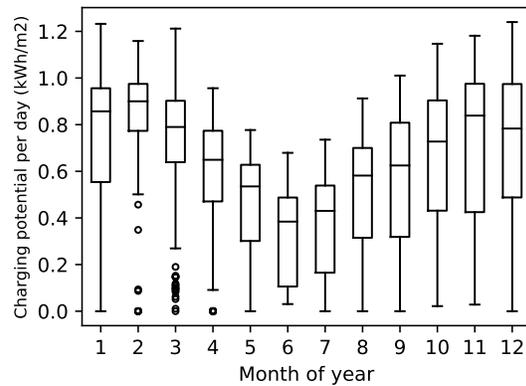
(a) Energy used per eMBT.



(b) Durations of stop events per eMBT.



(c) PV generation per  $m^2$  per month.



(d) PV charging potential per eMBT per  $m^2$  per month.

Figure 4: Summary of mobility, energy requirements, and charging potentials.

308 303 kWh is used. Eight of the nine taxis, on all days, use less than 420 kWh, while the other taxi uses up to  
 310 490 kWh.

310 The results show that a maximum usable battery capacity of approximately 500 kWh should be sufficient  
 312 for urban travel, if charging is limited to the stationary period before the day's first trip and for 75% of the  
 312 time a 303 kWh battery would be sufficient.

### 3.3. Charging potential

314 A sizable eMBT fleet could place a substantial burden on the local electrical network and power generation  
 316 capacity of countries in sub-Saharan Africa. The strain on the local utility could cause infrastructure and  
 318 electrical supply problems, so we investigated the opportunities for charging these vehicles from solar PV  
 318 systems. To discover the eMBTs' opportunities and requirements if they are to charge during stationary  
 320 periods, we did a 24-hour analysis of the start times and the durations of stop events. The analysis shows  
 320 what the average charger capacity should be if a vehicle is charged using only power from the local electrical  
 322 utility. We applied a minimum stop duration of 20 minutes and a maximum stop duration of 8 hours to  
 322 ensure that only valid operational stops would be identified and that drop or pick up and go events were  
 322 not included as charging opportunities. We chose the maximum of 8 hours because a taxi in normal service  
 322 would not stop for longer than that on a week day.

#### 3.3.1. Charging from the grid

324 Figure 4b shows the distribution of stop events across days, with the minimum and maximum stop  
 326 duration thresholds applied. The figure shows that the MBTs' stop duration times vary considerably, with

the median duration per day ranging from a minimum of 7.7 hours for taxi T3001 to a maximum of 10.7 hours for taxi T6000.

To calculate the charger capacity we used a relatively high energy demand and a relatively short charging time for an averagely demanding situation. We used the averages of the 75<sup>th</sup> percentile of the energy usage (Figure 4a) and the 25th percentile of the 24-hour stop duration times (Figure 4b) as 247 kWh and 7.65 hours respectively to calculate a charger capacity of 32.3 kW. This assumes a constant charging profile and charging only from the local electrical grid.

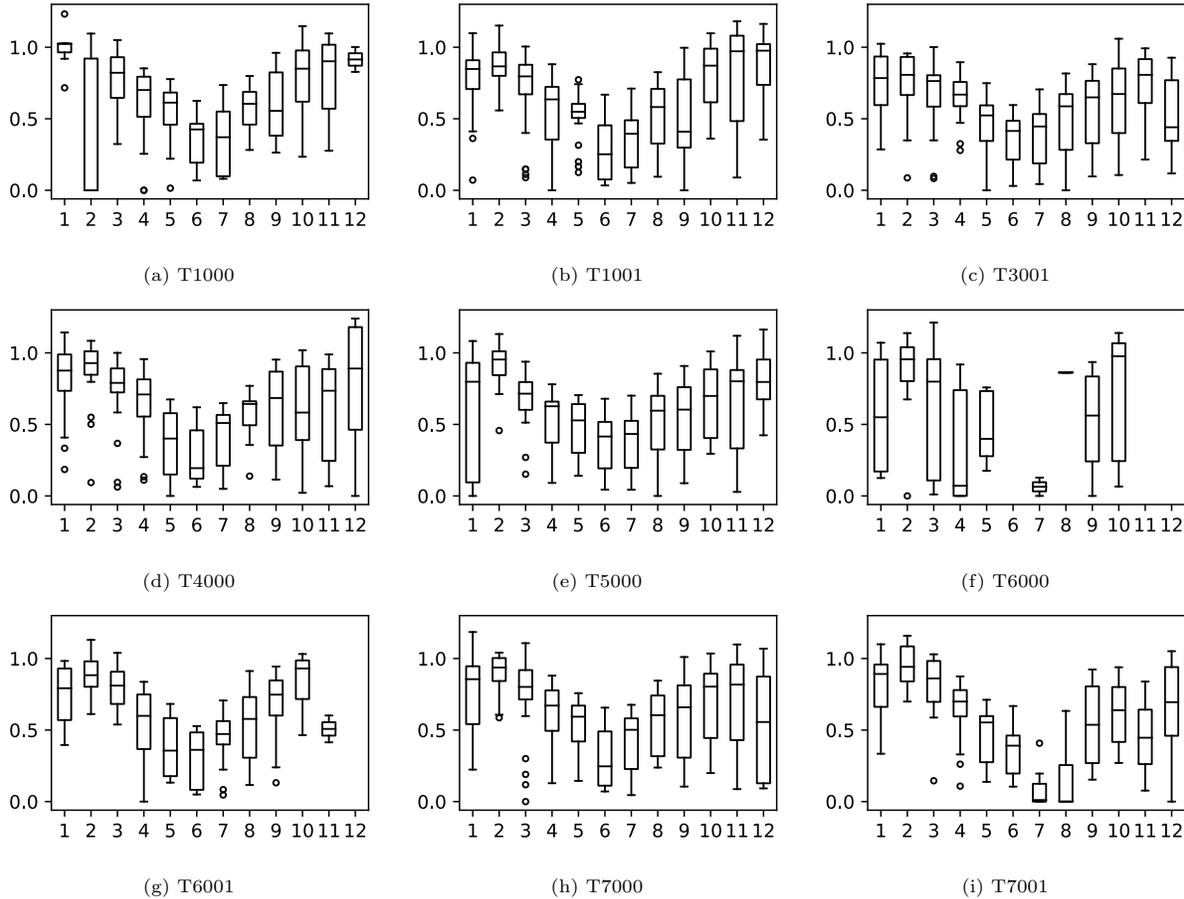


Figure 5: Disaggregated charging potential (in kWh/m<sup>2</sup>) per eMBT for each month of the year.

### 3.3.2. Charging from solar PV

We evaluated the potential for charging the eMBTs from solar PV, both to reduce the load on the electrical grid and to reduce the size of the battery installed in the eMBT. The energy generated per surface area is shown in Figure 4c for each month of the year, representing an upper bound of charging potential during stationary periods.

The aggregate charging potential per square metre of solar panel, for the fleet, is shown in Figure 4d, indicating that a large amount of the generated energy could be used during stops. The desegregated distribution of charging potential for each taxi, per square metre of solar panel, is shown in Figure 5. The variation of charging potential between taxis is low, indicating that the taxis follow similar patterns during the daylight hours, and that they would require similar charging infrastructure. Assuming that the PV installations were sized to exploit the median stop potential per taxi, the potential would vary from a minimum of 0.38 kWh/m<sup>2</sup> to a maximum of 0.90 kWh/m<sup>2</sup> during the year. The results show that a solar installation of approximately 140 m<sup>2</sup> would be required per taxi to ensure that at least 25% of the taxi's daily energy requirements are met by solar supply.

348 Given the estimated 285,000 taxis in South Africa, our analysis indicates that to charge all the minibus  
350 taxis from the national grid will require 9.72% (61.27 GWh/d) of the current daily national energy generation.  
The average taxi would be able to directly utilise between 57% and 80% of installed PV generation capacity  
during normal stops.

#### 352 4. Conclusion

Concern about the possible effects of climate change has driven an energy revolution from internal com-  
354 bustion engines to electric vehicles in the Global North. Pushed by market forces and supplier preferences  
from beyond its own borders, this wave will eventually break over the Global South and its organically evolved  
356 and notoriously chaotic paratransit systems and fragile electrical grids. Sub-Saharan Africa has many spe-  
cific characteristics, challenges, and opportunities that will eventually determine its response. This paper  
358 focuses on paratransit in the region, which transports more than 70% of the region's commuters. One of the  
unanswered questions is how the dissimilar mobility characteristics of the minibus taxis, the mainstay of the  
360 region's paratransit system, will translate into electrical requirements. Since these taxis park spontaneously  
at tacitly known stops of the drivers' choosing, for durations determined by passenger demand, the charging  
362 potential at these stops is unknown. Further, the extent to which these charging stations can be powered by  
the region's abundant sunshine remains unclear. This paper therefore investigated these three unknowns for  
364 minibus taxis in an urban scenario in South Africa's Western Cape Province. The results showed that for the  
taxis we studied would mostly have a similar energy demand with a nominal 250 kWh required per median  
366 day if no additional charging capacity was provided. This would increase to 420 kWh when accommodating  
all days, except for one taxi, which required 490 kWh. Evaluating the charging potential showed that the  
368 median stops per day ranged from 7.7 h to 10.6 h.

As expected, the taxis with the shorter stop periods, and hence less time for charging, are also the ones that  
370 would need more energy because they are more mobile. Nevertheless, a nominal 32 kWh charger will suffice if  
charging only from a fully operational grid. Evaluating the solar irradiation for the stop times and durations,  
372 showed that the mean charging potential per median day ranged from 0.38 kWh/m<sup>2</sup> to 0.90 kWh/m<sup>2</sup>.

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