

Improved implementation of travel time randomization for incorporating V_s uncertainty in seismic ground response

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Abstract

Accounting for uncertainty in shear wave velocity (V_s) profiles has been recognized to be critical to seismic ground response analysis (GRA) and probabilistic seismic hazard analysis (PSHA). V_s randomization models are among the most widely used approaches to account for this uncertainty, often referred to as aleatory variability within the context of PSHA. Researchers have investigated alternate ways of more realistically accounting for V_s uncertainty, such as randomizing the cumulative shear wave travel time (tts) instead of V_s directly. While some preliminary assessments suggest that tts randomization allows for better management of V_s uncertainty, more validations are needed to guide its use in practice. This study aims to fill a knowledge gap by performing a thorough review of the tts randomization framework and suggesting changes that will lead to improved implementation. Specifically, through the use of real experimental data and Monte Carlo simulations, we identify several issues which, if left unimproved, could lead to bias and unrealistic results. These issues particularly pertain to: (1) methods used for bounding simulated layers, (2) approaches for merging column and bedrock models, and (3) appropriate values of the lognormal standard deviation on tts and inter-layer correlation for randomizing tts . For each issue, we devise recommendations and demonstrate that they provide a clear improvement on the current tts randomization framework. The revised steps put forward in this article do not require any additional model parameters, but rather, simply improve upon the existing methodology. The findings of this study enhance our understanding of the tts randomization framework, and the recommendations we provide will enable researchers and engineers to adopt it more robustly and confidently in engineering practice.

1 Introduction

Predicting the influence of subsurface geomaterials on earthquake ground shaking, known as site effects, is a crucial aspect that controls the seismic hazard for many engineering projects. In current practice, it has become the standard to conduct seismic hazard analyses for critical facilities and major infrastructure within a probabilistic framework, and to model site effects using predominantly one-dimensional (1D) ground response analysis (GRA). Owing to the flexibility of probabilistic seismic hazard analysis (PSHA), different sources of uncertainty can be integrated into the hazard calculations using procedures that continue to evolve. However, recent studies have shown that the uncertainty in 1D GRA and its propagation into PSHA can significantly drive the hazard estimates. Thus, proper quantification and modeling of this uncertainty is of paramount importance (Passeri et al., 2019; Pehlivan et al., 2016; Rathje et al., 2010).

Uncertainties in 1D GRA namely stem from: (1) selection of the input rock motions, (2) characterization of the shear wave velocity (V_s) profile, (3) characterization of the nonlinear dynamic material properties, (4) specification of the analysis method, and (5) suitability of the underlying 1D site assumptions (Passeri et al., 2019; Rathje et al., 2010; Thompson et al., 2012). In this article, we focus on the V_s profile, which is a fundamental component of any site-specific GRA. The V_s profile can be characterized using invasive/borehole methods (e.g., downhole, crosshole, and P-S suspension logging) or noninvasive/surface wave methods (e.g., active- and passive-surface wave measurements). However, regardless of the dynamic site characterization method, uncertainty in the derived V_s profile is inevitable, and the purpose of this article is to highlight challenges that are encountered in current and newly proposed procedures that attempt to model this uncertainty.

Invasive and noninvasive V_s measurements are influenced by two types of uncertainty: (1) aleatory variability, and (2) epistemic uncertainty. Aleatory variability is related to the inherent spatial variation of subsurface properties. This variability corresponds to natural changes in the layering and stiffness of subsurface materials, and it can be quantified by testing at multiple locations across the site. Epistemic uncertainty, on the other hand, stems

from uncertainties in the measured data and those introduced during analysis. This uncertainty is attributed to our inability to perfectly measure the V_s profile and it can be quantified by using multiple characterization techniques and/or different data processing and analysis methods. Although this distinction of uncertainties is conceptually evident, their separation in practice is nontrivial.

For many years, both variability and uncertainty have been modeled as a single random variable, in which a reference base-case V_s profile is randomized using a statistical model, such as that developed by Toro (1995). More recently, the state-of-practice in PSHA has moved toward separating aleatory variability from epistemic uncertainty. It is becoming increasingly common to model the latter using alternative base-case profiles, typically a best-estimate, upper-case, and lower-case V_s profiles. Even when using alternative base-case profiles to account for epistemic uncertainty in V_s , aleatory variability within PSHA is additionally accounted for by randomizing each of these alternative V_s profiles (EPRI, 2012).

A growing body of literature has investigated the efficacy of these commonly used approaches in capturing V_s aleatory variability and epistemic uncertainty. For example, several researchers have compared site response predictions from V_s randomization with ground motion observations at vertical seismometer arrays (Field and Jacob, 1993; Hallal et al., 2022; Kaklamanos et al., 2020; Passeri et al., 2020; Teague et al., 2018). Besides these studies, others have performed theoretical assessments (without comparison to observations) to examine the influence of V_s randomization (Pehlivan et al., 2016; Rathje et al., 2010; Barani et al., 2013; Bazzurro and Cornell, 2004; Griffiths et al., 2016a; Tran et al., 2020) and alternative V_s profiles (Passeri et al., 2019; Griffiths et al., 2016a) on site response predictions.

An unsettling conclusion from these studies is that, although it is common for engineers to use randomized and/or alternative V_s profiles to account for V_s uncertainty in GRAs, these procedures, as currently implemented, often generate unrealistic V_s profiles that do not represent well the actual site conditions. More specifically, both approaches commonly generate V_s profiles that fail to match other site-specific experimental data (e.g., layering from boring logs, fundamental site frequency, surface wave dispersion data) and result in uncontrolled and potentially unconservative median site response predictions, which can be detrimental for seismic hazard estimates. These challenges have motivated the development of alternative approaches to effectively model general V_s uncertainty. One such development is that proposed by Passeri et al. (2020) based on randomizing the cumulative shear wave travel time (tts).

Despite several potential improvements gained through tts randomization, more validations are required to ensure its successful implementation in practice. Hallal et al. (2022) assessed multiple approaches to account for V_s variability in 1D GRAs, including tts randomization. The authors concluded that although tts randomization likely offers an improvement over traditional V_s randomization, some outstanding challenges remain that require further attention before adopting this approach in practice. The aim of this article is to scrutinize these challenges and to provide guidelines which will work toward better modeling of V_s variability in 1D GRA. The findings of this study will enhance our understanding of the tts randomization framework, and the recommendations we provide will allow researchers and engineers to adopt this framework more confidently.

The article begins with a presentation of the statistical framework of V_s randomization and a discussion of its challenges. Then, the adjustments introduced by Passeri et al. (2020) to tackle these challenges using the tts randomization framework are described. Despite the potential benefits of the tts randomization framework, we argue, based on real experimental data and Monte Carlo simulations, that some of the introduced adjustments may pose additional challenges, which might in turn lead to bias and unrealistic results if not implemented appropriately. For each challenge, we examine revised implementation approaches and demonstrate that they provide a clear improvement on the current framework. The recommendations proposed in this article do not require any additional model parameters beyond those specified by Passeri et al. (2020), but rather focus on methodologies for improved implementation. Finally, we close with a discussion on future directions and potential improvements in need of further investigation.

2 V_s randomization and its challenges

2.1 Statistical framework of V_s randomization

V_s randomization is currently performed within a Monte Carlo framework, predominantly using the Toro (1995) model, which is one of the earliest published approaches and remains one of the few systematic statistical models available for this purpose. This framework operates on three components: (1) a layering model to randomize layer thicknesses, (2) a bedrock model to vary bedrock depth, and (3) a velocity model to simulate V_s variability. For

these various components, Toro (1995) developed input parameters based on a total of 557 V_s profiles, most of which are from various California sites, and these input parameters are applicable to specific site classes (across an entire seismic site class) or applicable to a generic site (across all seismic site classes).

The layering model attempts to reflect the trend observed by Toro (1995) in layer thicknesses, which is thin layers near the surface transitioning to thick layers at depth. This is achieved by modeling the occurrence of a layer interface as a non-homogeneous Poisson process with a depth-dependent occurrence/interface rate parameter (λ), as shown in Fig. 1a. Toro (1995) defined λ using a modified power-law function:

$$\lambda = c_3(z + c_1)^{c_2} \quad (1)$$

where c_1 , c_2 , and c_3 are fitting parameters and z is depth in meters. Toro (1995) recommended generic values of 10.86, 0.89, and 1.98 for c_1 , c_2 , and c_3 , respectively, which result in a decreasing value of λ with depth (Fig. 1a). Because the occurrence of a layer interface is modeled as a non-homogeneous Poisson process, the distance between two interfaces, which is layer thickness, follows an exponential distribution with the same parameter λ . The theoretical mean layer thickness is the reciprocal of the occurrence rate parameter (i.e., $1/\lambda$), as shown in Fig. 1b. A sample exponential probability density function for thickness at a particular depth (around 18 m) with $\lambda = 0.1$ is shown in Fig. 2. By plotting similar probability density functions for layer thickness with depth, a two-dimensional thickness probability density function can be visualized, as shown in Fig. 1b. Additional information contained in Fig. 1 will be discussed later in the paper.

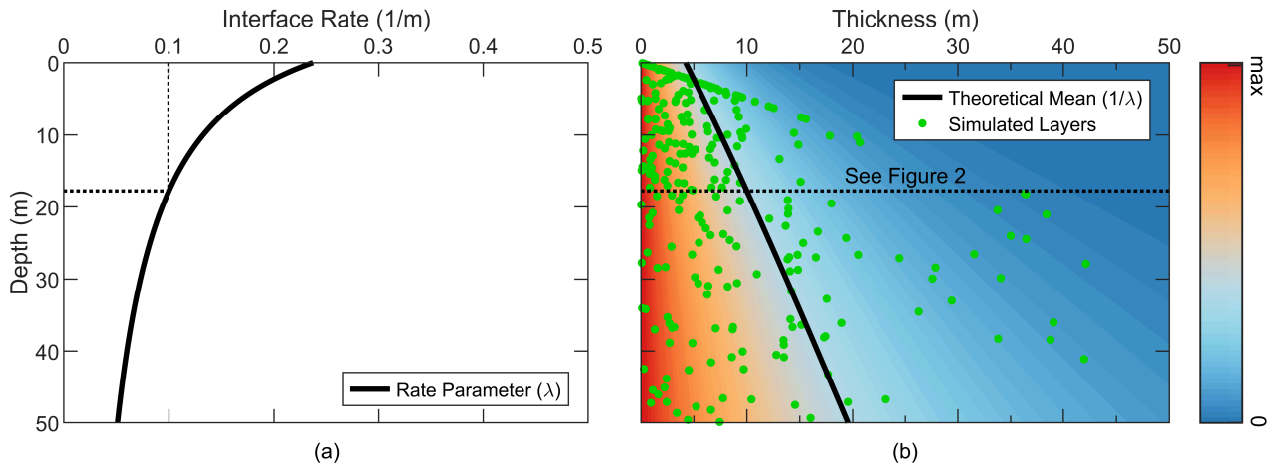


Figure 1: The layering model developed by Toro (1995) to randomize V_s profile layer thicknesses. Shown are: (a) a depth-dependent rate parameter (λ) using the generic parameters recommended by Toro (1995), and (b) a two-dimensional probability density function (pdf) of the layer thicknesses, which is defined by the same depth-dependent λ . Also shown are a set of 275 simulated layers from 50 V_s profiles. Each circle symbol corresponds to a simulated layer plotted at its mid depth.

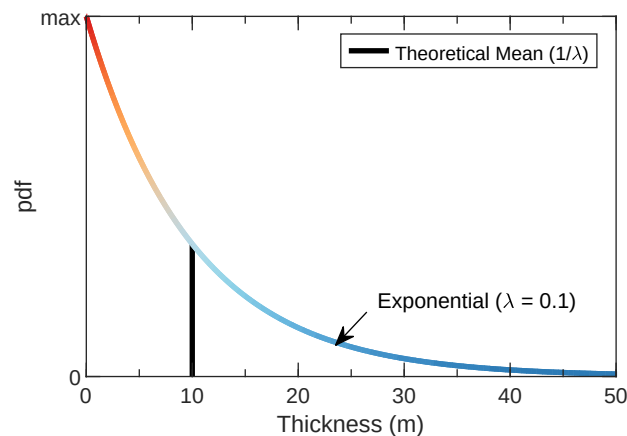


Figure 2: A sample exponential pdf for thickness at a particular depth (around 18 m) with $\lambda = 0.1$, as shown using the dotted line in Fig. 1b. The pdf is color-coded based on its density, similar to Fig. 1b.

Bedrock depth in the [Toro \(1995\)](#) model is simulated separately from the soil layer interfaces. However, unlike the layering model, little guidance is provided. [Toro \(1995\)](#) utilized a uniform distribution but did not specify how the parameters were set. In research ([Passeri et al., 2020](#); [Teague et al., 2018](#); [Griffiths et al., 2016a,b](#)) and practice, uniform, normal, and lognormal distributions have been used to model the depth to bedrock, and their parameters are either assumed or calculated when multiple V_s measurements are available.

One-dimensional V_s profiles in the [Toro \(1995\)](#) model are simulated from a non-stationary lognormal random field, which is defined by a depth-dependent V_s lognormal standard deviation ($\sigma_{\ln V_s}$) and an inter-layer correlation model (ρ). [Toro \(1995\)](#) observed that if the V_s in a layer is above average, then the V_s in the layer directly below it has a similar tendency. This tendency is modeled using a positive ρ , which is defined as a function of depth-dependent and thickness-dependent correlations (ρ_d and ρ_t , respectively):

$$\rho = (1 - \rho_d)\rho_t + \rho_d \quad (2)$$

$$\rho_d = \begin{cases} \rho_{200} \left[\frac{d+d_0}{200+d_0} \right]^b & \text{for } d \leq 200 \text{ m} \\ \rho_{200} & \text{for } d > 200 \text{ m} \end{cases} \quad (3)$$

$$\rho_t = \rho_0 \cdot \exp\left\{\frac{-t}{\Delta}\right\} \quad (4)$$

where ρ_{200} , d_0 , b , ρ_0 , and Δ are parameters for which [Toro \(1995\)](#) provided site class generic values, d is the average of midpoint depths of successive layers, and t is the difference between these midpoint depths. Generally, this model gives higher ρ for deeper and/or thinner layers.

Finally, a first-order autoregressive function is used to define V_s in each layer. This model predicts the V_s of a layer as a function of the V_s of the layer above it and ρ . The V_s of layer i (V_{s_i}) is simulated from a lognormal distribution with a median equal to the base-case V_s at its mid-depth ($\tilde{V}_{s_i}$) and a specified $\sigma_{\ln V_s}$, as given by:

$$V_{s_i} = \exp\{\ln(\tilde{V}_{s_i}) + Z_i \cdot \sigma_{\ln V_s}\} \quad (5)$$

$$Z_i = \begin{cases} \varepsilon_i & \text{for } i = 1 \\ \rho_i \cdot Z_{i-1} + \varepsilon_i \sqrt{1 - \rho_i^2} & \text{for } i > 1 \end{cases} \quad (6)$$

where Z_i and Z_{i-1} are standard scores (number of standard deviations from the mean, i.e., $\ln(\tilde{V}_{s_i})$) for layers i and $i - 1$, respectively, and ε_i is a standard normal random variable for layer i . [Toro \(1995\)](#) provided site class generic values for $\sigma_{\ln V_s}$ that range between 0.27–0.37. [Stewart et al. \(2014\)](#) considered a subset of the V_s profiles from [Toro \(1995\)](#) and recommended "site-specific" $\sigma_{\ln V_s}$ values of 0.15 for depths ≤ 50 m and 0.22 for depths > 50 m, which are preferable whenever a site-specific V_s profile is available and when spatial variations are not expected to be extreme.

2.2 Challenges of Vs randomization

Most researchers agree that V_s profiles developed from blind application of V_s randomization using generic parameters are often unrealistic, even when using the lower, "site-specific" $\sigma_{\ln V_s}$ from [Stewart et al. \(2014\)](#). The unsatisfactory results from blind application of V_s randomization can be attributed to a combination of factors. First, the assumed non-homogeneous Poisson model proposed by [Toro \(1995\)](#) results in layer thicknesses that are highly variable, even if the mean values are reasonable. For example, and as discussed in the next paragraph, Fig. 1b shows simulated layers that display extreme variability. Second, the median V_s of each randomized layer is set based only on the base-case V_s at its mid-depth (Equation 5), which is a discrete point. While the mid-depth V_s might be appropriate in some cases, it provides very limited information that ignores potential V_s variations at shallower and/or deeper depths along the simulated layer thickness. Third, separate randomization of layer thicknesses and V_s may result in double counting of uncertainty ([Passeri et al., 2020](#)). These factors combined may yield shallow, thick layers with unrealistic velocities that represent deeper/stiffer material.

For example, Fig. 1b shows a set of layer thicknesses obtained from 50 randomized V_s profiles using the generic λ provided by [Toro \(1995\)](#) (Fig. 1a). Note that each circle symbol corresponds to a simulated layer plotted at its mid-depth. Because of the assumed statistical layering model, randomized V_s profiles might have a different number of layers. In Fig. 1b, most of the randomized V_s profiles needed 5–6 layers to reach a depth of 50 m, resulting in a total of 275 simulated layers for all 50 randomized V_s profiles. As evident, the simulated layer thicknesses show

extreme variability. For example, at depths between 20–40 m, the simulated layer thicknesses range between 1–40 m, even though the theoretical mean values are between 10–15 m. While this variability is not surprising given the nature of the assumed exponential distribution for layer thicknesses, it might not be realistic for many sites. In addition, the simulated top layer in some of the randomized profiles has a thickness as high as 40 m. These thick near-surface layers will consequently be assigned V_s values solely based on their mid-depth, which will be as deep as 20 m in this case, and likely inconsistent with the near-surface V_s .

Another challenge with V_s randomization is the need to specify several input parameters which are site-specific, but not typically available. Assumptions are typically required to set parameters needed to define the rate parameter controlling the layering randomization (Equation 1), to define the statistical distribution of bedrock depth and its parameters, to calculate inter-layer correlations (Equations 2–4), and to set the $\sigma_{\ln V_s}$ (Equation 5). Because a wealth of site characterization information is not typically available, these parameters are often guessed or assumed based on generic relations derived for other sites, which introduces additional uncertainty into the site response predictions.

To investigate the consequences of these challenges, site response predictions with V_s randomization have been compared with observations at vertical seismometer arrays by, for example, Field and Jacob (1993) at the Turkey Flat array in California, Teague et al. (2018) at the Garner Valley array in California, Kaklamanos et al. (2020) at 10 arrays from the Kiban-Kyoshin network (KiK-net) in Japan, Passeri et al. (2020) at the Mirandola array in Italy, and Hallal et al. (2022) at the Treasure Island and Delaney Park arrays in the United States. The collective results of these studies indicate that many of the randomized V_s profiles represent unrealistic site conditions, which in turn produces site response predictions that are different from observations. In addition, Griffiths et al. (2016a,b), Teague et al. (2018), and Teague and Cox (2016) noted that many randomized V_s profiles are inconsistent with the experimental site signature, which is defined by experimental dispersion data and estimates of the fundamental site frequency (f_0) from horizontal-to-vertical (H/V) spectral ratios of noise measurements ($f_{0,H/V}$).

This extreme V_s variability generally decreases the amplitude of the predicted site response (Rathje et al., 2010), causing a broadening and underprediction of site amplification in comparison to observations at downhole arrays, which is unconservative. Several procedures have been recommended to mitigate some of the challenges of V_s randomization, such as screening randomized V_s profiles based on the experimental site signature (Hallal et al., 2022; Teague et al., 2018; Griffiths et al., 2016b) or randomizing tts instead of V_s (Passeri et al., 2020). We focus on tts randomization and its challenges next.

3 Statistical framework of tts randomization

Passeri et al. (2020) introduced tts randomization, which included several adjustments meant to resolve some of the challenges of traditional V_s randomization. First, they proposed a method to mitigate unrealistic layer thicknesses by defining acceptable layer thickness bounds. Second, tts includes cumulative information about the V_s profile, which avoids potential problems arising from randomizing about a discrete point in the V_s profile (i.e., mid-depth of each layer). Third, tts randomization deals with a single random variable, which eliminates double counting of uncertainty that results from separate layering and V_s randomization. However, despite potential improvements gained by applying these adjustments, tts randomization may pose additional challenges that require due care to avoid bias and unrealistic conditions in the simulated V_s profiles. Below, we summarize the statistical framework of tts randomization and then discuss challenges and recommendations for improved implementation in the following section.

Randomization can be performed on tts , which deals with a single random variable that is a function of both V_s and layer thicknesses:

$$tts = \sum_{i=1}^n \frac{h_i}{V_{s_i}} \quad (7)$$

where n is the number of layers, h_i is the thickness of layer i , and V_{s_i} is its shear wave velocity. The proposed framework by Passeri et al. (2020) adopted most of the formulations and equations from Toro (1995), but applied them to tts . The proposed framework operates on three components: (1) a column model to randomize soil layer thicknesses and tts , (2) a bedrock model to vary bedrock depth and its V_s , and (3) merging of the column and bedrock models. Passeri et al. (2020) discuss different approaches for handling V_s profiles developed from invasive and noninvasive methods. When multiple V_s profiles from inversion of surface wave data are available, site-specific input parameters can be estimated, but we only discuss the generic application herein, which requires a single base-case V_s profile and aligns more closely with the Toro (1995) approach.

Although randomization is performed on tts , it is essential to represent the randomized tts profiles as Vs profiles, which are the input to GRAs. For this purpose, the same layering model from Toro (1995) is adopted for tts randomization, but it is recommended that the parameters in Equation 1 (i.e., c_1 , c_2 , and c_3) be specified such that they result in a theoretical mean layer thickness with depth that is consistent with the measured thickness profile. In addition, Passeri et al. (2020) recommended bounding the simulated layer thicknesses by defining an acceptable range determined by upper and lower factors (e.g., $\pm 50\%$) applied to λ , as shown in Fig. 3. Imposing these acceptable bounds is intended to eliminate unrealistic layer thicknesses. The same 275 simulations of layer thickness from Fig. 1b are also shown in Fig. 3b, but now color coded based on their location within or outside the acceptable range bounds. The results are shown prior to imposing the bounds to highlight unacceptable simulated layers. Passeri et al. (2020) imposed the acceptable bounds by truncating the simulated layer thicknesses at the bounds. Results and challenges from imposing the bounds in this way are discussed later in this article.

After randomizing layer thicknesses, and instead of modeling the variability in Vs , the model operates on tts using the inter-layer correlation model (Equations 2–4) and first-order autoregressive function (Equations 5 and 6) developed by Toro (1995). Thus, the tts of adjacent layers are assumed to be positively correlated and the tts of each layer is assumed to be lognormally distributed with a median and a specified tts lognormal standard deviation (σ_{lntts}). Passeri et al. (2020) provided a new set of generic parameters for the inter-layer correlation model (ρ_{200} , d_0 , b , ρ_0 , and Δ , refer to Equations 2–4) and recommended σ_{lntts} values of 0.01–0.02 based on Vs profiles derived from inversion of active-source surface wave testing at 71 sites in Italy.

Randomized tts profiles are then converted to Vs profiles, which are referred to as column models. While this information is sufficient to define the column models, one other important detail is worth discussing. Passeri et al. (2020) did not explicitly detail how the median tts should be obtained. For example, Vs randomization models commonly set the median Vs for each randomized layer equal to the base-case Vs at the mid-depth of that layer. However, if tts randomization is similarly performed at the mid-depth, any Vs (or tts) information in the second half of each randomized layer will not be accounted for. Therefore, for tts randomization, the median tts used for the randomization of a specific layer should be set equal to the base-case tts at the bottom-depth of that layer. This is simply because tts includes cumulative information about the base-case Vs profile, which guarantees capturing the full properties.

Bedrock properties are randomized separately using a joint distribution, where bedrock depth and Vs are assumed to be lognormally distributed and positively correlated (i.e., higher bedrock Vs tends to be associated with deeper bedrock), with the latter having a recommended generic correlation coefficient of 0.508. Instead of arbitrarily imposing a bedrock depth on a soil column model, an equal number of bedrock depths and soil columns are generated, which are then merged by pairing each bedrock depth (from a lognormal distribution) with the soil column that has the closest bottom depth (from the non-homogeneous Poisson process). This merging is

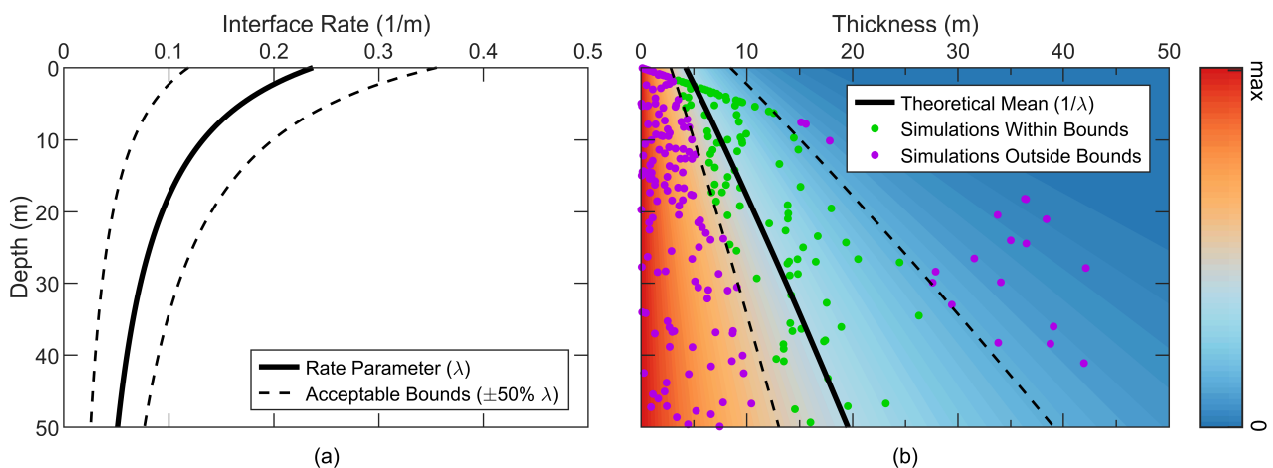


Figure 3: The layering model adopted by Passeri et al. (2020) for tts randomization, which is the same as that developed by Toro (1995), but with the addition of enforcing acceptable bounds, as shown for: (a) interface rate, and (b) layer thickness. These bounds are simply defined as factors applied on λ (e.g., $\pm 50\% \lambda$) to bound the layering randomization and avoid generating layers with unrealistic thicknesses. The same 275 layer simulation results from Fig. 1b are shown here, but color coded based on their location within or outside the acceptable range bounds. We note that results are shown prior to imposing the bounds.

intended to avoid unrealistic profiles, which could arise from enforcing a bedrock depth that is inconsistent with the layer interfaces.

4 Challenges and recommendations for implementing *tts* randomization

The work by Passeri et al. (2020) is indeed a step in the right direction of addressing some of the limitations of traditional V_s randomization. However, in scrutinizing some of the adjustments introduced by Passeri et al. (2020), we show that they give rise to three additional challenges that require further improvements. Particularly, these challenges pertain to: (1) bounding simulated layer thicknesses, (2) merging column and bedrock models, and (3) randomizing *tts*. In the next subsections, we use Monte Carlo simulations and/or real data to demonstrate these challenges and recommend improved implementations that are grounded in fundamental principles of statistics and probability.

4.1 Bounding simulated layer thicknesses

Despite the potential for unrealistic variability in layer thicknesses resulting from the statistical model developed by Toro (1995) (i.e., non-homogeneous Poisson model), as demonstrated in Fig. 1, this model continues to be commonly used in practice and research, and has also been directly incorporated into at least one site response software package, Strata (Kottke and Rathje, 2009). In addition, Passeri et al. (2020) adopted the same model but with modifications, as previously discussed. Thus, rather than developing a different statistical model for randomizing layer thicknesses, we strictly adhere to the work of Toro (1995) and Passeri et al. (2020), but with improved implementation. Passeri et al. (2020) proposed truncating simulated layers at acceptable bounds set as a symmetric factor on λ (e.g., $\pm 50\% \lambda$). We show that imposing and defining the acceptable bounds in this way can lead to bias by clustering layer thicknesses at the upper and lower acceptable boundaries. Therefore, to mitigate this bias, and rather than incorporating additional parameters, we simply provide recommendations to impose and define the acceptable bounds in a different, unbiased manner.

4.1.1 Imposing acceptable layer thickness bounds

The resulting layer thicknesses from applying the method adopted by Passeri et al. (2020), which we refer to as Method 1, are shown in Fig. 4a. Note that these data points are based on the 275 simulated layers shown in Fig. 1 and Fig. 3, although the number of layers will differ after imposing the bounds. In addition, a histogram of the final layer thicknesses after imposing the bounds is shown in Fig. 4c. Because layer thicknesses vary with depth, the histogram values are normalized by the theoretical mean thickness for better illustration. It is evident that forcing unacceptable layers to be equal to the bounds causes many of the simulated layer thicknesses to be clustered at the bounds, and more so at the lower thickness bound (Fig. 4c). This is an artifact of the assumed distributions and how the bounds are imposed. Recall from Fig. 3b that many of the simulated layer thicknesses fell outside the acceptable bounds, particularly below the lower thickness bound, which is due to the high probability density function of the exponential distribution at low values (Fig. 2). Consequently, Method 1 adopted by Passeri et al. (2020) could be improved to produce a better distribution of the final layer thicknesses.

To overcome this challenge, we propose a simple fix by rejecting simulated layers that are outside the acceptable bounds and repeating their simulation until they fall within the bounds. Results from applying this method, which we refer to as Method 2, are shown in Fig. 4b and d. In contrast to the results discussed earlier, the final layer thicknesses in this case are not clustered at any of the bounds, but rather have a good coverage range that is more consistent with the assumed exponential distribution. Consequently, care should be taken in how the acceptable layer thickness bounds are imposed on the randomizations to avoid any bias in the final layer thicknesses. It is highly recommended that unacceptable simulated layer thicknesses be rejected and re-simulated, as proposed in this article, rather than forced to the boundaries. We note that, on average, unacceptable layers in Fig. 4b had to be re-simulated twice until an acceptable thickness was obtained, but this number will vary depending on the width of the bounds.

Despite the better results achieved by Method 2, it is evident that the final layer thicknesses are biased to thicker layers on aggregate. As shown in Fig. 4c, the mean of the simulated layer thicknesses is higher than the theoretical mean when imposing the bounds using Method 1. This bias remains even when Method 2 is applied (Fig. 4d). The overall bias to thicker layers is governed by the boundary values used by Passeri et al. (2020) (i.e., $\pm 50\% \lambda$), which lead to unsymmetrical thickness bounds, as discussed next.

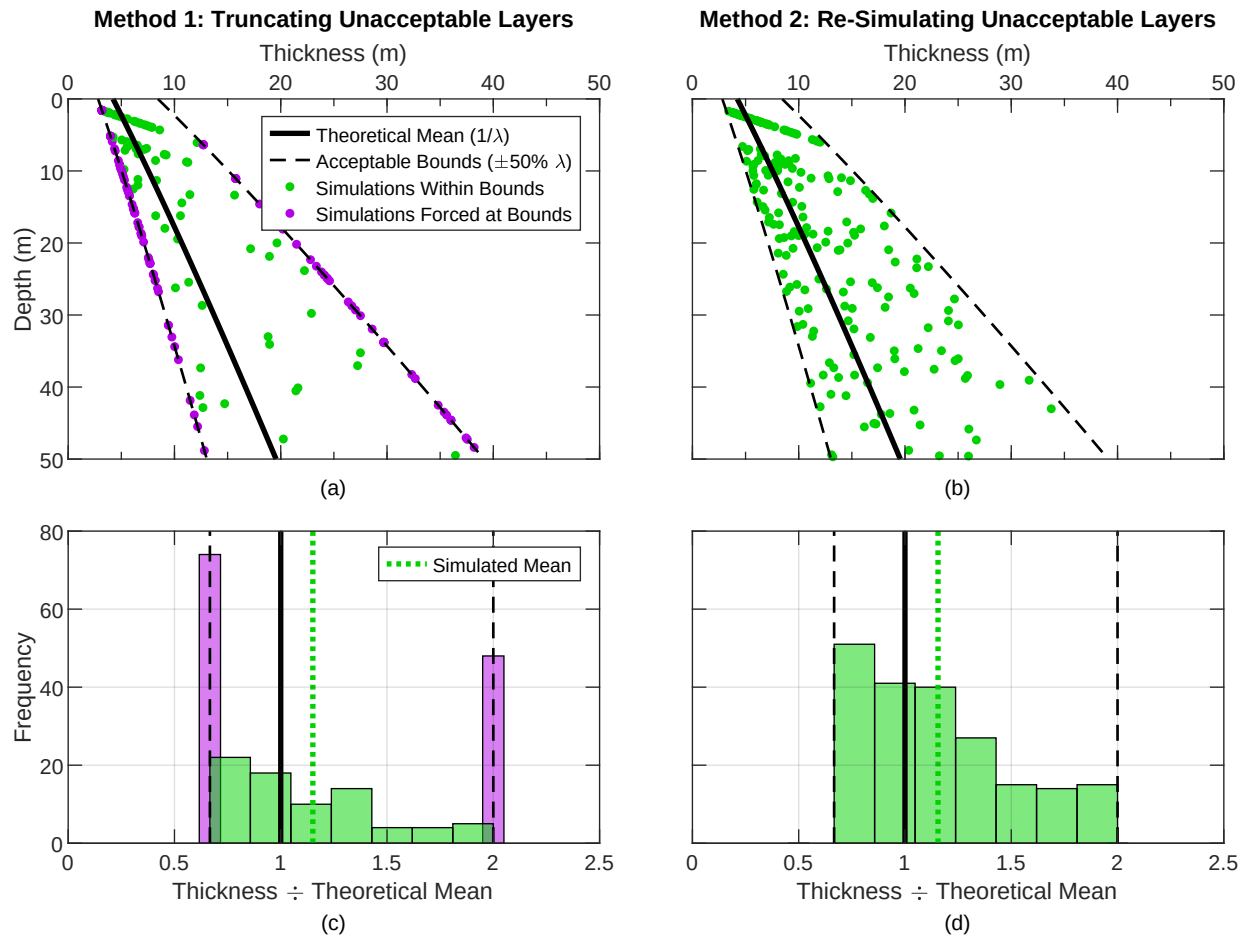


Figure 4: Resulting layer thicknesses after imposing acceptable thickness bounds using two different methods: (1) truncating unacceptable layers at the boundaries (i.e., forcing all simulations that are outside the bounds equal to the values of the bounds), which is adopted by Passeri et al. (2020), and (2) re-simulating unacceptable layers, which is the method proposed in this article for improved implementation. For each method, we show: (a, b) the final layer thicknesses with depth, and (c, d) a histogram of the final normalized layer thicknesses. Because the thickness increases with depth, the histogram values are normalized by the theoretical mean thickness for better illustration.

4.1.2 Defining acceptable layer thickness bounds

The assumed statistical distribution of layer thickness (exponential) is unsymmetrical and long tailed (Fig. 2), which makes defining appropriate bounds nontrivial. Passeri et al. (2020) used symmetric bounds on interface rate, as defined using factors on λ (e.g., $\pm 50\% \lambda$), which we will refer to as rate-symmetric bounds. To demonstrate the effect of these bounds on the acceptable range, Fig. 5 shows the statistical distribution of layer thickness at a particular depth with $\lambda = 0.1$ (refer to Fig. 1 and Fig. 2). The acceptable thickness range based on $\pm 50\% \lambda$ at this depth, as highlighted in the green region, is 6.7–20 m, which is unsymmetrical relative to the theoretical mean thickness of 10 m. This asymmetry causes the mean thickness of the acceptable range (green dotted line in Fig. 5) to be higher than the theoretical mean, introducing an overall bias to thicker layers. Thus, if engineers develop a site-specific λ based on available data, and then bound the simulations using rate-symmetric bounds, the final layer thicknesses, on aggregate, will be greater than, and inconsistent with the site-specific λ .

To ameliorate this bias, the acceptable bounds should be specified such that the mean thickness of the acceptable range is consistent with the theoretical mean, which we refer to as mean-consistent bounds. Since the rate-symmetric bounds are biased to thicker layers, then the acceptable range should either be extended further toward thinner layers, or reduced to limit thicker layers. Fig. 5 shows, in red, the acceptable range based on limiting thicker layers (i.e., using rate bounds of -30% to $+50\% \lambda$ instead of $\pm 50\% \lambda$). By appropriately limiting thicker layers from the rate-symmetric bounds, the mean thickness of the acceptable range becomes consistent with the theoretical mean (red dotted line in Fig. 5).

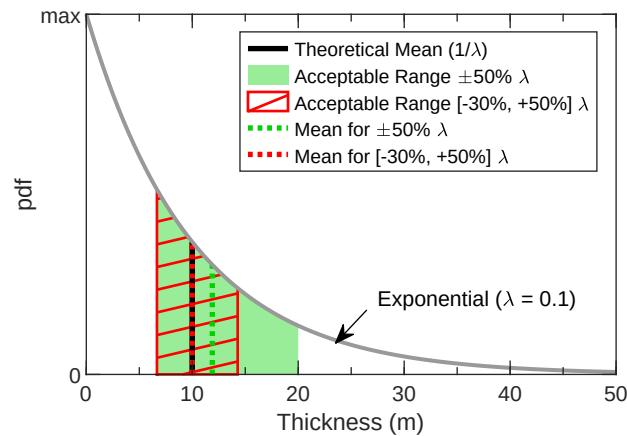


Figure 5: Alternative approaches to define acceptable bounds for the layering model and their corresponding thickness ranges at a particular depth with $\lambda = 0.1$ (refer to Fig. 2). The wider acceptable range shown in green is based on symmetric interface rate bounds, as defined using symmetric factors on λ (e.g., $\pm 50\% \lambda$), which were used by Passeri et al. (2020); we refer to these as rate-symmetric bounds. The narrower range shown in red, which we propose as an improved approach for defining acceptable layer thickness bounds, has a mean thickness that is consistent with the theoretical mean; we therefore refer to these bounds as mean-consistent bounds.

Fig. 6 shows the resulting layer thickness simulations from using the rate-symmetric $\pm 50\% \lambda$ bounds from Passeri et al. (2020) (same results as Fig. 4b and d) and the mean-consistent -30% to $+50\% \lambda$ bounds proposed herein. Both bounds were imposed on the simulations by re-simulating unacceptable layers (i.e., Method 2 in Fig. 4). The layer thicknesses based on the mean-consistent bounds (Fig. 6b and d) have a simulated mean that is in perfect agreement with the theoretical mean, unlike the results based on the rate-symmetric bounds, which are biased to thicker layers (Fig. 6a and c). This provides further evidence supporting that rate-symmetric bounds result in an overall bias to thicker layers, which can be corrected by using the proposed mean-consistent bounds.

The -30% to $+50\% \lambda$ is just one set of mean-consistent bounds, and Fig. 7 shows other combinations of upper and lower mean-consistent bounds. Also shown are the rate-symmetric bounds used by Passeri et al. (2020), with the circle symbols being the specific cases demonstrated in Fig. 5 and Fig. 6. Fig. 7 thus provides engineers with an easy way to define the acceptable bounds recommended in this article, by simply choosing any point along the relationship for mean-consistent bounds. The -30% to $+50\% \lambda$ bounds (red circle symbol in Fig. 7) are believed to be appropriate for sites with moderate spatial variability in layer thicknesses, and wider bounds could be used for sites with high spatial variability in layer thicknesses. However, we do not recommend using bounds beyond -50% to $+150\% \lambda$, because otherwise, the benefit of applying the bounds is negligible. More research on this topic is required to establish typical bound values for different site conditions.

4.2 Merging column and bedrock models

After generating soil layer thicknesses that are within the acceptable bounds, which are referred to as column models, an equal number of bedrock depths are independently simulated using an assumed lognormal distribution. Then, each bedrock depth is merged with a column model that has the closest bottom depth. This merging is intended to avoid enforcing a bedrock depth that is inconsistent with the layer interfaces. However, an exact match between the simulated bedrock depths (from a lognormal distribution) and layer interfaces in the column model (from a Poisson model) is virtually impossible. Bedrock depth is enforced on the column model after merging, and thus, the thickness of the deepest column layer will be altered. Depending on the magnitude of this alteration, the thickness of the deepest column layer might become outside the acceptable bounds, which defies the goal of bounding layer thicknesses.

To demonstrate this undesirable effect, Fig. 8a, c, and e present simulation results after merging 50 column and 50 bedrock models. To investigate the effect of the width of the acceptable soil layer thickness range on merging, results are shown for three different sets of mean-consistent bounds, with Fig. 8a having tight bounds (less thickness variability) and Fig. 8e having wide bounds (more thickness variability). Each circle symbol corresponds to a layer in a column model, with each column model having multiple layers. All simulated layers fell entirely within the acceptable bounds prior to merging with bedrock models. Bedrock models were simulated using a lognormal distribution with a median of 45 m and a depth to rock lognormal standard deviation of 0.05.

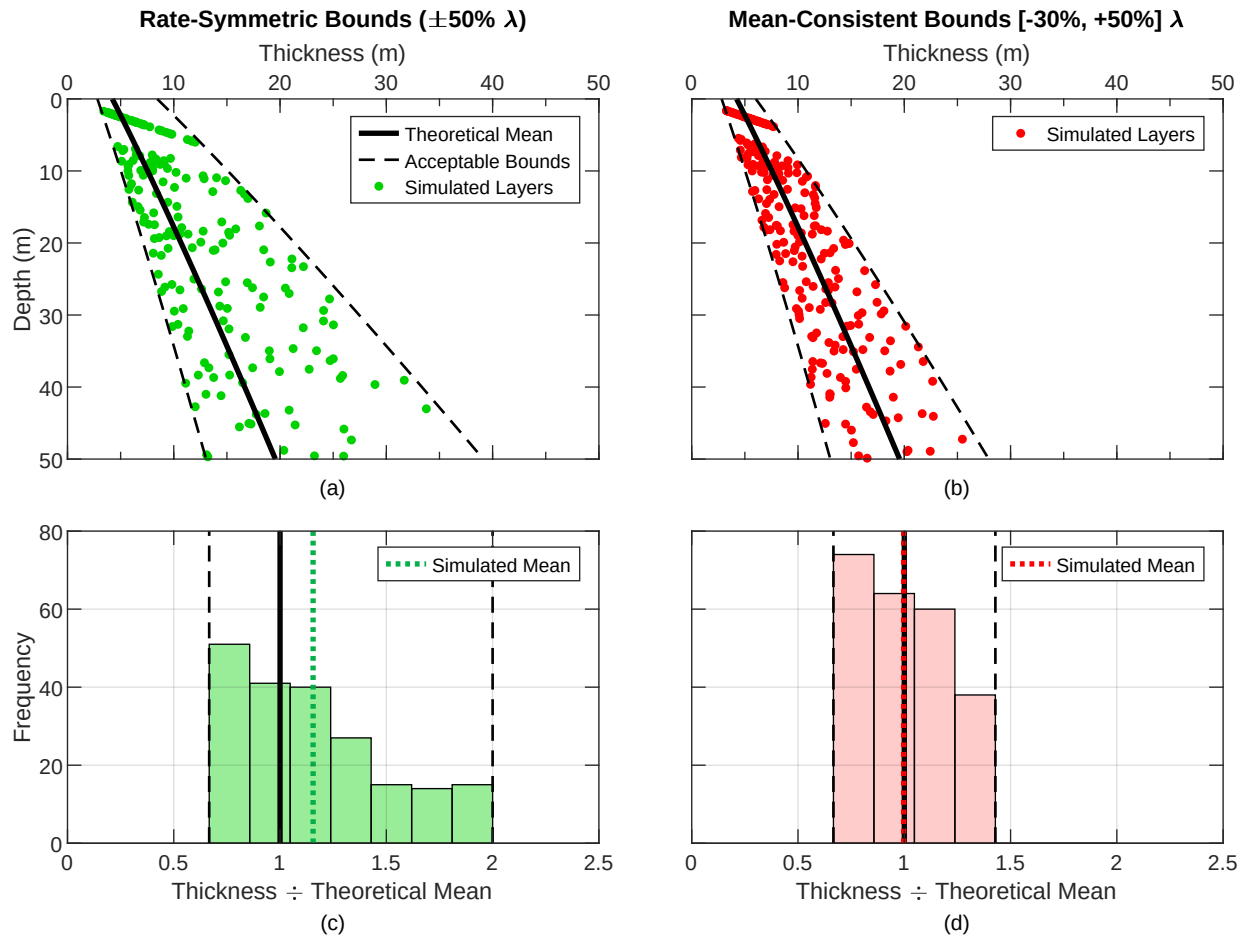


Figure 6: Resulting layer thicknesses after imposing acceptable thickness bounds: (1) rate-symmetric bounds from Passeri et al. (2020), and (2) mean-consistent bounds as proposed in this article. For each method, we show: (a, b) the final layer thicknesses with depth, and (c, d) a histogram of the final normalized layer thicknesses.

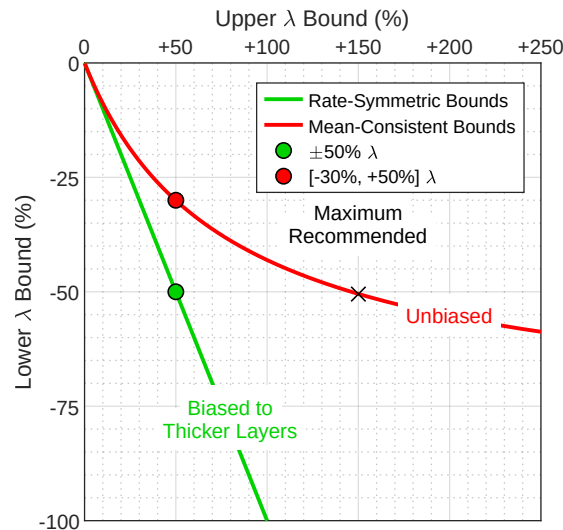


Figure 7: Relationship between upper and lower acceptable layer bounds defined as factors on λ for the rate-symmetric bounds used by Passeri et al. (2020) and for the improved mean-consistent bounds proposed in this article. Also shown are the cases demonstrated in Fig. 5 and Fig. 6 and the maximum recommended range for the mean-consistent bounds.

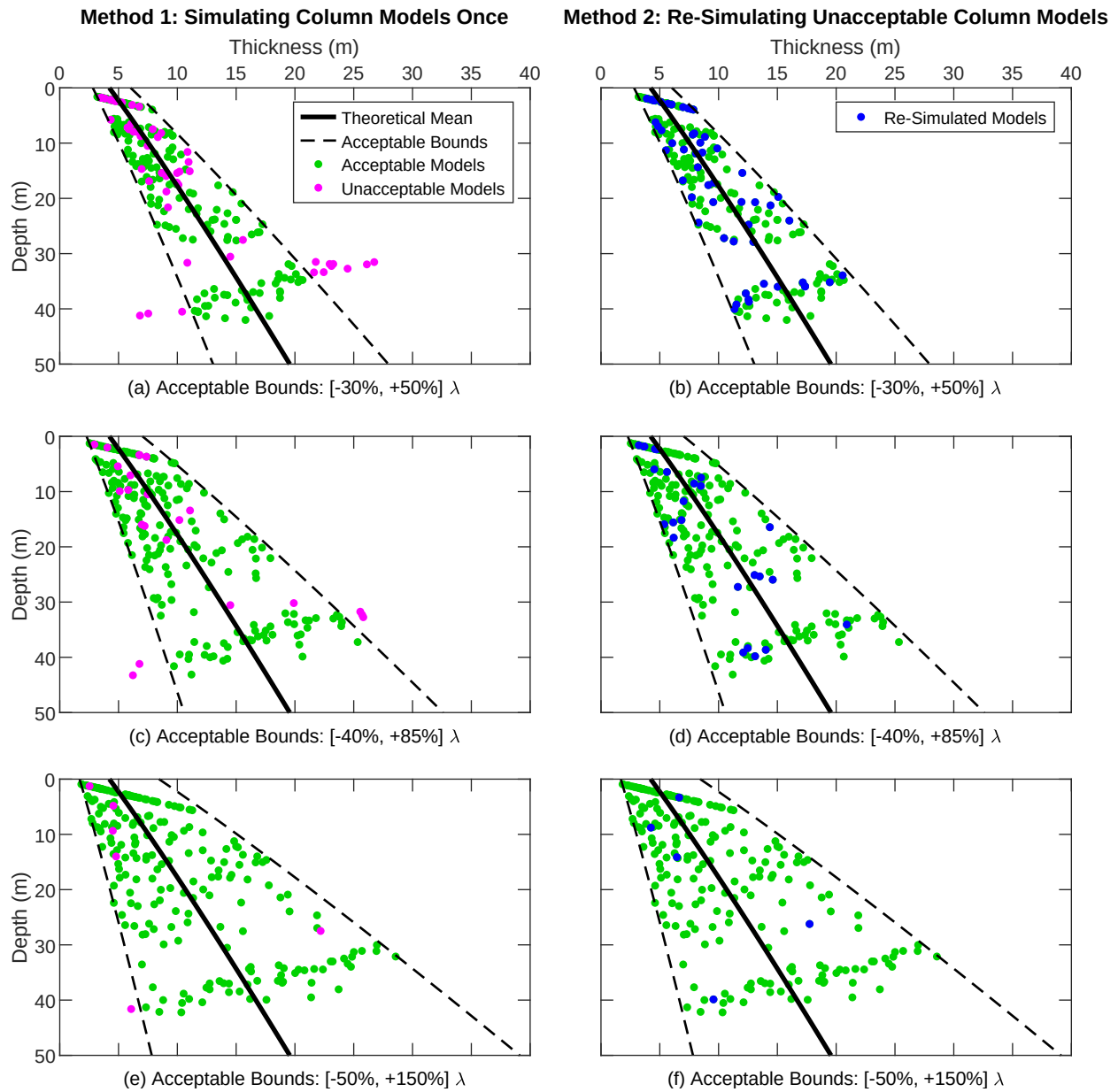


Figure 8: Resulting layer thicknesses after merging column and bedrock models using two different methods: (a, c, e) Method 1 simulating column models only once, which is implemented by Passeri et al. (2020), and (b, d, f) Method 2 re-simulating column models with unacceptable deep layers, which is proposed in this article. Results are shown for three sets of mean-consistent bounds to investigate the effect of the width of the acceptable layer thickness range on merging. Note that although shallower layers are unaffected by merging and remain within the acceptable bounds, all layers for models with unacceptable deep layers are highlighted in magenta.

It is evident from Fig. 8a, c, and e that merging column and bedrock models without checking the thickness of the deepest layer after merging, which is the method implemented by Passeri et al. (2020) and which we refer to as Method 1, could potentially cause some of the deepest layers to fall outside of the acceptable thickness bounds. Although shallower layers are unaffected by merging and remain within the acceptable bounds, all layers for models with unacceptable deep layers are highlighted in magenta (Fig. 8a, c and e). The results show that merging is particularly more critical for tighter bounds (e.g., -30% to +50% λ in Fig. 8a), simply because even small changes in the thickness of the deepest layer after merging could cause it to fall outside the bounds. In Fig. 8a, 12 out of 50 models had unacceptable deep layers after merging. However, with wider bounds (e.g., -50% to +150% λ in Fig. 8e), there is a greater margin within which the thickness of the deepest layer above bedrock could be altered and remain acceptable. In this case, only a single model had an unacceptable deep layer after merging.

In an effort to ensure full consistency between the randomized layer thicknesses, their acceptable bounds, and the randomized bedrock depths, we simply propose re-simulating a new set of column models and then merging them only with the bedrock models that resulted in unacceptable deep column layers, which we refer to as Method 2. Results from applying this method are shown in Fig. 8b, d, and f, in which the re-simulated models are highlighted in dark blue. These results assert that Method 2, proposed herein, yields layers that are entirely within the acceptable bounds, even after merging. Therefore, it is recommended that column model with unacceptable bottom layer thicknesses after merging be completely rejected (i.e., all layers), entirely re-simulated, and then re-merged with the remaining bedrock models. We note that it might be necessary to re-simulate unacceptable column models more than once until the resulting model, after merging, is entirely within the acceptable bounds. This can be easily automated.

4.3 Randomizing tts

The final step of tts randomization is simulating tts for each layer in the soil column from an assumed lognormal distribution, which is defined by a median tts , σ_{lntts} , and ρ . As discussed earlier, the median tts of each layer should be set equal to the bottom-depth base-case tts . The simple rationale behind this is that tts is a cumulative parameter, and thus the bottom-depth value captures the base-case properties to the depth of interest. In this subsection, we focus on challenges and recommendations for specifying appropriate σ_{lntts} and ρ values.

The extent of material property variability incorporated into GRAs for tts randomization is controlled by σ_{lntts} . This is analogous to σ_{lnVs} for Vs randomization, which has been shown to have a significant effect on the predicted seismic site response (Rathje et al., 2010; Boushehri et al., 2020). Passeri et al. (2020) suggested that σ_{lntts} is depth independent and recommended values between 0.01–0.02 based on Vs profiles derived from the inversion of active-source surface wave data. Thus, this recommended σ_{lntts} range reflects uncertainties associated with the non-uniqueness of surface wave inversion. However, Hallal et al. (2022) hypothesized, based on comparisons of predicted site response from tts randomization with recorded ground motions at several borehole array sites, that using the recommended σ_{lntts} of 0.02 underestimates spatial variability. In addition, some researchers have hesitated using values as low as 0.01–0.02 in practice. In this article, we use numerous borehole and surface wave Vs measurements from a real dataset along with Monte Carlo simulations to further investigate appropriate σ_{lntts} values. Hallal and Cox (2022) presented preliminary results on the influence of σ_{lntts} from Monte Carlo simulations. While our results indicate the need for higher σ_{lntts} , we show that this might yield unrealistic Vs profiles, with excessively high or even negative Vs values, which must be mitigated by increasing ρ .

4.3.1 Investigations of σ_{lntts} Based on Real Data

We first compare the recommended σ_{lntts} range of 0.01–0.02 with σ_{lntts} associated with in-situ measured Vs profiles from a site located in the East Gulf Coastal Plain of western Georgia, USA (Damm et al., 2021), which we refer to as the Greenfield site. A comprehensive deep Vs profile site characterization project was conducted at the Greenfield site using several invasive and noninvasive tests, resulting in a total of 27 Vs profiles. The invasive methods included 10 seismic cone penetration tests (mostly in the top 30 m) and 8 PS suspension logging tests, whereas the noninvasive tests resulted in 5 Vs profiles from spectral analysis of surface waves (SASW) surveys and 4 median Vs profiles from combined multichannel analysis of surface waves (MASW) and microtremor array measurements (MAM). All tests were performed within an area of approximately 1 km².

Fig. 9 presents the 27 Vs profiles from the Greenfield site, their corresponding σ_{lnVs} , 27 tts profiles, and their corresponding σ_{lntts} . The site has a median time-averaged Vs in the top 30 m (V_{S30}) of 370 m/s, which classifies as Site Class C, very dense soil (ASCE, 2022). Except for the top 25 m, σ_{lnVs} is in the range of 0.10–0.20 (Fig. 9b), which is consistent with low-to-moderate variability (Stewart et al., 2014). The low spatial variability has also been confirmed through consistency between H/V curves from ambient noise recordings at 38 distinct locations across the site. While not shown here for brevity, the H/V curves are nearly identical, providing further evidence of the site's low spatial variability. However, despite the apparent low spatial variability at the Greenfield site, the σ_{lntts} of the 27 Vs measurements is in the range of 0.05–0.10 across the entire depth of 150 m, which is 5 times as much large as the range recommended by Passeri et al. (2020). Again, we would like to emphasize that the 0.01–0.02 range recommended by Passeri et al. (2020) mostly reflects uncertainties associated with the non-uniqueness of surface wave inversion. However, in the context of PSHA and ground response analyses, randomization approaches are used to account for Vs aleatory variability. While we only present measurements from a single dataset, albeit a high quality one, the considerably higher σ_{lntts} at a site where there is evidence of low spatial variability provides strong experimental support to the conclusions of Hallal et al. (2022), that to account for spatial variability, a σ_{lntts} of 0.01–0.02 is perhaps too low, at even relatively homogeneous sites.

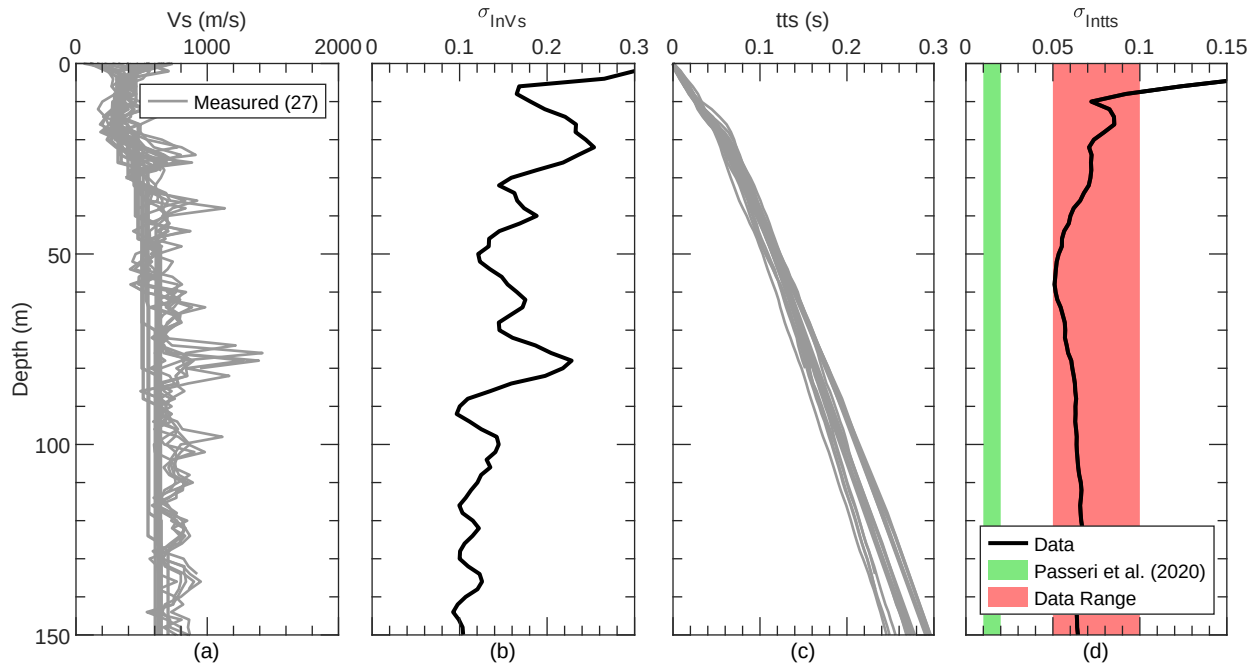


Figure 9: (a) Comparison of a total of 27 invasively and noninvasively measured V_s profiles at the Greenfield site, (b) their corresponding $\sigma_{\ln V_s}$, which is consistent with low-to-moderate variability sites, (c) their 27 tts profiles, and (d) comparison of their $\sigma_{\ln tts}$ with the recommended range of 0.01–0.02 by Passeri et al. (2020).

4.3.2 Investigations of $\sigma_{\ln tts}$ based on simulations

Based on this field evidence, we next assess the effects of using higher $\sigma_{\ln tts}$ on tts randomization results. We investigate the influence of three different $\sigma_{\ln tts}$ values of 0.02, 0.05, and 0.10 on the simulated variability in V_s and on subsequent site response predictions. The assessments are performed at the Treasure Island Downhole Array (TIDA) so that the GRA predictions from tts randomization can be compared to actual ground motion observations. The TIDA site is located in a seismically active region of northern California, approximately 5 km northeast of San Francisco, 12 km west of the Hayward fault, and 20 km east of the San Andreas fault. The site has been characterized through several testing programs, and existing data show that the near subsurface is horizontally stratified, with relatively low spatial variability (Cheng et al., 2021; Papadopoulos and Eliahu, 2009; Tao and Rathje, 2019). The site has a V_{S30} of 165 m/s, which classifies as Site Class E, soft soil (ASCE, 2022).

An invasively measured V_s profile from PS suspension logging at TIDA (Graizer et al., 2004) was used to develop a base-case tts profile for randomization. Then, for each investigated $\sigma_{\ln tts}$ (i.e., 0.02, 0.05, and 0.10), a set of 250 V_s profiles were simulated using the recommended tts randomization procedures discussed above for bounding layers and merging column and bedrock models (i.e., Methods 2). The simulated V_s profiles from tts randomization are shown in Fig. 10. To better interpret the significance of different $\sigma_{\ln tts}$ values, the simulated V_s profiles from tts randomization were used to compute $\sigma_{\ln V_s}$ values. As shown in Fig. 10, the $\sigma_{\ln V_s}$ of the simulated V_s profiles are compared to a typical range of 0.10–0.30, which was chosen based on common values used in practice and in research (Stewart et al., 2014; Rodriguez-Marek et al., 2014; Garofalo et al., 2016a).

It is evident from Fig. 10a, c, and e that the median V_s profiles are similar to the base-cases, indicating that the V_s profiles from tts randomization capture the assumed baseline models, on average, regardless of $\sigma_{\ln tts}$. However, increasing $\sigma_{\ln tts}$ causes an increase in the variability of the simulated V_s profiles and their resulting $\sigma_{\ln V_s}$. This observation is not surprising because $\sigma_{\ln tts}$ controls the magnitude of the modeled variability. However, Fig. 10b shows that using $\sigma_{\ln tts}$ of 0.02 results in $\sigma_{\ln V_s}$ generally below 0.10, which is less than the lower bound of the typical range used in practice and research. These simulation results lend further support to the hypothesis that $\sigma_{\ln tts}$ larger than that recommended by Passeri et al. (2020) might be required to more appropriately model subsurface variability. For example, using a $\sigma_{\ln tts}$ of 0.05 at the TIDA site yields $\sigma_{\ln V_s}$ values below 0.20, but mostly within the typical range (Fig. 10d). Thus, values closer to 0.05 might be more appropriate for sites with low-to-moderate variability, like the TIDA site. Although a $\sigma_{\ln tts}$ of 0.10 (Fig. 10f) appears to yield higher $\sigma_{\ln V_s}$ values that are still consistent with high variability sites, this value of $\sigma_{\ln tts}$ results in a few unrealistic V_s models with very high V_s in some cases (Fig. 10e); this aspect is further addressed later in the article.

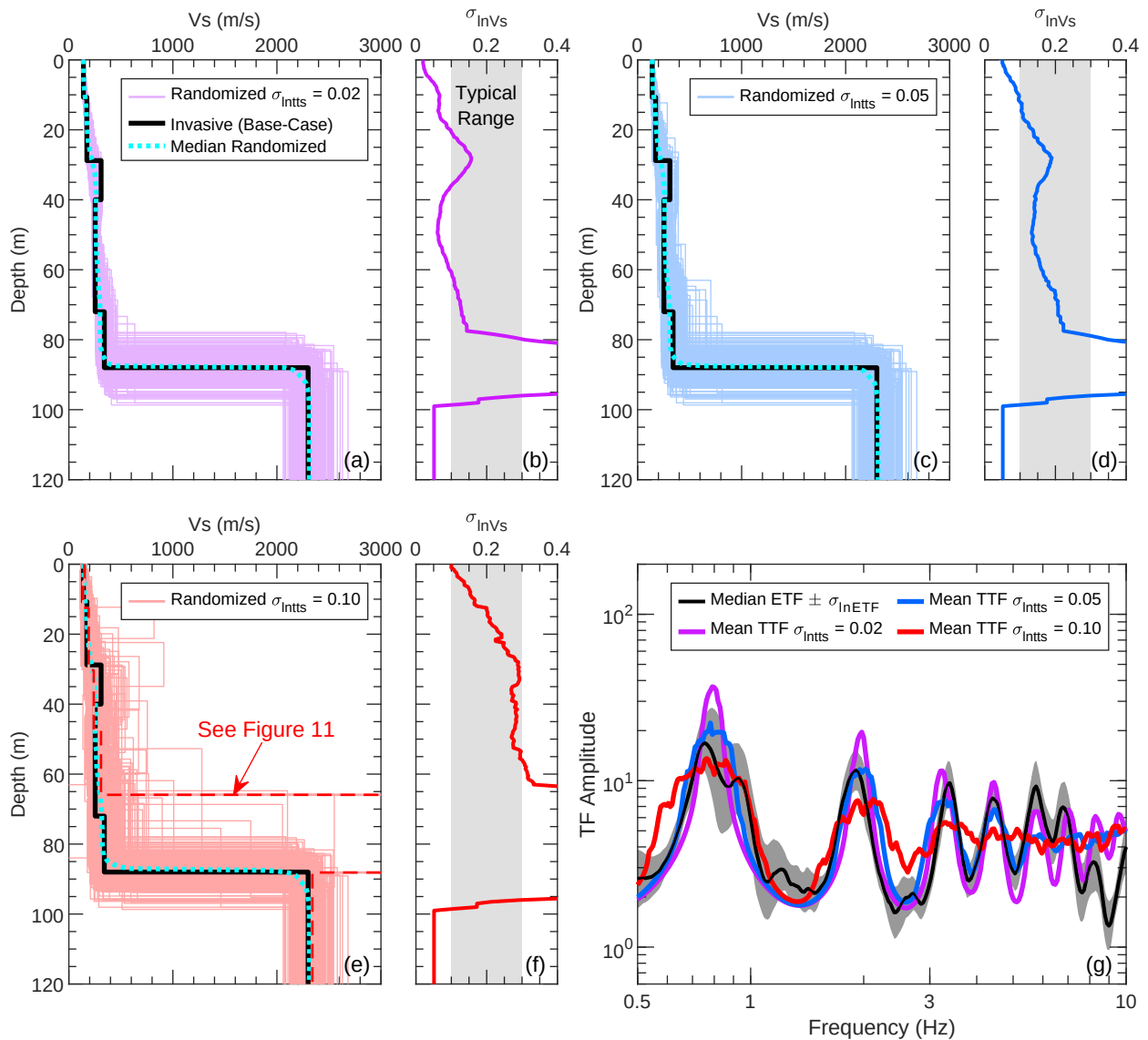


Figure 10: (a, c, e) V_s profiles developed through tts randomization with different levels of σ_{lntts} and the generic ρ model (Equations 2–4) at the Treasure Island Downhole Array (TIDA). (b, d, f) Comparison of the resulting σ_{lnVs} of the simulated V_s profiles with the typical range used in practice and research, as shown in the gray shaded area, which can help interpret the influence of σ_{lntts} on V_s variability. (g) Influence of different levels of σ_{lntts} on the mean theoretical transfer functions (TTFs) and their comparison to the median observed empirical transfer function (ETF) at TIDA.

To assess the influence of σ_{lntts} on the predicted site response, linear-viscoelastic, theoretical transfer functions (TTFs) were calculated for each simulated V_s profile between the surface and deepest triaxial ground motion accelerometer at the TIDA site, which is located at 122 m. TTFs were calculated using the closed-form solution for damped, layered soil over elastic bedrock. The individual TTFs were then averaged to obtain a representative mean TTF. The required input soil properties include V_s , mass density, and small-strain damping ratio (D_{min}). The damping profiles were assigned using the laboratory-based D_{min} (Darendeli, 2001) using estimates of in-situ confining stresses obtained from typical soil unit weights and assumed plasticity indices of 25 for clay layers and 0 for sand layers, similar to Tao and Rathje (2019).

Next, to compare the site response predictions from different σ_{lntts} levels with observations, a suite of 36 recorded low-amplitude ground motions (peak ground accelerations < 0.01 g) was used to compute a median empirical transfer function (ETF) between the deepest accelerometer and the ground surface. For each horizontal component of all selected ground motions, an ETF was computed as the ratio of the Fourier amplitude spectra (FAS) of the horizontal surface accelerations divided by the horizontal rock accelerations. Then, the lognormal me-

dian and the lognormal standard deviation (σ_{lnETF}) of all individual ETFs from the two horizontal components of recorded earthquake events were computed. By including only low-amplitude motions, we ensure that challenges associated with modeling nonlinear soil behavior do not interfere with our attempts to understand the effects of spatial variability. It should be noted that since the ETFs represent the surface-to-rock ratio in which the rock time histories include both upgoing and downgoing waves, the TTFs are modeled to include those effects using what is referred to as the within boundary condition at depth. For more details, please refer to Hallal et al. (2022); Hallal and Cox (2021).

Fig. 10g compares the mean TTFs computed from tts randomization using the three different levels of $\sigma_{ln tts}$ with the median ETF. Increasing levels of variability cause a decrease in the predicted mean TTF amplitude, which is in line with observations by Rathje et al. (2010) for traditional V_s randomization. While the mean TTF from using $\sigma_{ln tts} = 0.02$ is the only one that clearly captures all amplification modes observed in the ETF, there is persistent amplification overprediction at frequencies below 5 Hz (Fig. 10g). Using a $\sigma_{ln tts}$ of 0.05 gives a better match to the ETF at TIDA over the entire frequency range, whereas a higher value of 0.10 significantly over-flattens amplification at higher frequencies. As was noted above, the TIDA site is characterized by low spatial variability. In fact, due to the nature of its hydraulic fill construction, it is known as a prototypical 1D site. Even at this low spatial variability site, a $\sigma_{ln tts} = 0.02$ value appears to be too low to accurately capture the amplitude range of the fundamental mode, and a higher value of approximately 0.05 appears to better represent spatial variability within the tts randomization framework. While a $\sigma_{ln tts}$ of 0.10 might not be appropriate in this case, as revealed by the underprediction of the observed site response at all amplification modes (Fig. 10g), this higher value might be appropriate for sites with higher spatial variability. However, Fig. 10e shows that this also generates some unrealistic V_s profiles, which are examined hereafter.

A concerning observation when implementing tts randomization with high $\sigma_{ln tts}$ is generating unrealistic V_s models. This is evident in several of the V_s profiles in Fig. 10e that have soil layers in the top 60 m with $V_s > 800$ m/s. Additionally, some V_s profiles at depths between 60–80 m have layers with $V_s > 2000$ m/s, despite the fact that the base-case profile has $V_s < 400$ m/s over this same depth range. One of the simulated V_s profiles even has a layer with negative V_s between approximately 65 and 85 m.

To help understand the reason underlying such highly variable and unrealistic V_s profiles, Fig. 11 is used to more closely examine one of the most erratic tts -randomized V_s profiles from Fig. 10e. In addition to the V_s profile, Fig. 11 shows the base-case and randomized tts profile and the inter-layer correlation coefficients. Recall that tts is randomized at each layer interface from a lognormal distribution, such as those shown in gray in Fig. 11b, with the assumption that successive randomized tts values are positively correlated. Each assumed tts distribution has a median equal to the base-case tts (black circle symbols in Fig. 11b) and a specified $\sigma_{ln tts}$ (0.10 in this case). A simulated V_s profile from tts randomization is obtained from the slopes of the lines connecting successive randomized tts values (e.g., the red square symbols in Fig. 11b). Because tts is cumulative (Equation 7), it should strictly increase with depth. However, this condition is not enforced in the tts randomization framework. For example, consider the region highlighted in orange in Fig. 11b, within which the successive tts distributions at approximately 65 m and 88 m overlap. Overlapping distributions at successive depths allow for simulated tts values at these depths to possibly be equal to one another, or even decrease with depth; the latter would result in a negative V_s . For the example V_s profile under consideration, the randomized tts values at approximately 65 and 88 m are quite similar, resulting in a nearly vertical tts slope (Fig. 11b), and consequently an unrealistically high V_s , in excess of 3000 m/s (Fig. 11a).

Problems like this are a consequence of two main factors: (1) wider tts distributions at depth (i.e., higher absolute variance for the same $\sigma_{ln tts}$ due to larger base-case tts at greater depths, as evident in Fig. 11b), and (2) generally closer tts distributions at depth (i.e., lower inter-layer travel times due to typically higher velocities at depth). Both of these factors generally occur simultaneously at greater depths, exacerbating the possibility of unrealistic results. While all log tts distributions in Fig. 11 have the same $\sigma_{ln tts}$, the variance of the tts distributions (not in log space, but similar to those plotted in Fig. 11b) changes. Particularly, it is a fact that the variance of lognormal distributions is proportional to the mean value. Consequently, because the mean tts increases with depth, the assumed lognormal tts distributions become wider, even when using the same $\sigma_{ln tts}$. This is clearly demonstrated in Fig. 11b, which shows that the tts distribution below 80 m has a higher variance than those at shallower depths, although all have the same $\sigma_{ln tts}$. If the tts distributions have very different base-case values (i.e., are far apart from each other in time space), then using a $\sigma_{ln tts} = 0.10$ will not necessarily result in an overlap of successive distributions, as evident at shallow depths in Fig. 11b. However, the results are exacerbated by the fact that the subsurface gets stiffer with depth, meaning that tts increases at a much slower rate. Consequently, successive tts distributions overlap because they are wider and their locations are closer in time, both of which generally occur simultaneously at greater depth. This overlap poses a challenge to tts randomization.

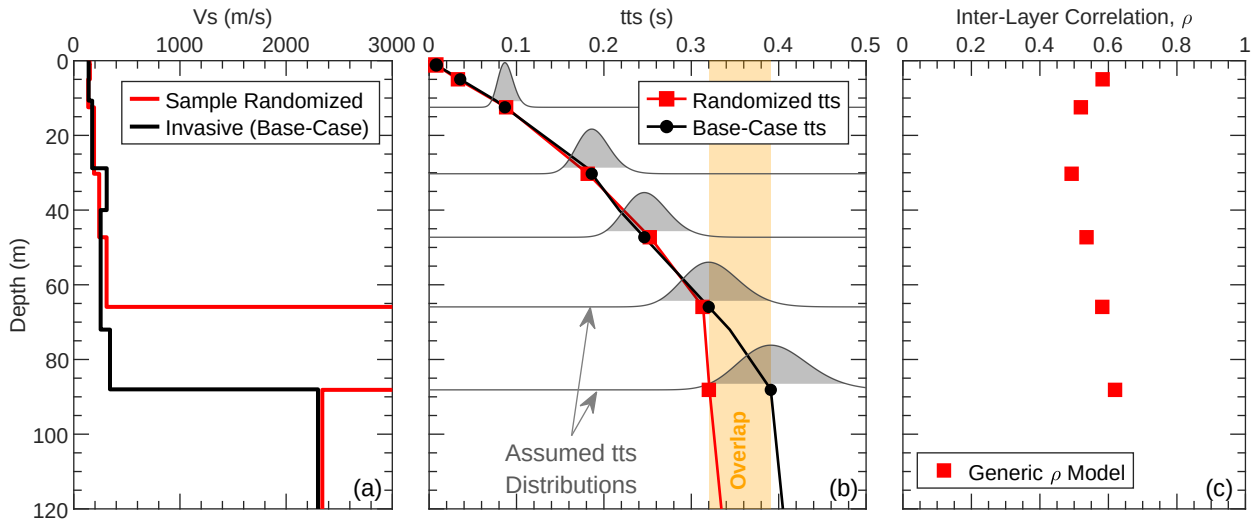


Figure 11: A sample simulated model with unrealistic V_s from tts randomization using σ_{Intts} of 0.10 at TIDA. Shown are: (a) the V_s profiles, (b) the tts profiles along with sample tts distributions used in the simulations, and (3) the ρ calculated using the generic model adopted by Passeri et al. (2020) (Equations 2–4). The orange shaded region in (b) highlights the overlap between successive tts distributions at depths of 65 m and 88 m, which allows for unrealistic V_s .

The unfavorable results specifically arise when the simulated tts at successive depths have very different Z-scores (i.e., number of standard deviations from the base-case). For example, the randomized tts at approximately 65 m in Fig. 11b is comparable to its base-case (Z-score ≈ 0), but at approximately 88 m it is considerably lower (Z-score ≈ -2). This causes the randomized tts slope to be near vertical, resulting in an unrealistic V_s layer. Recall that the tts of successive layers are assumed to be positively correlated, meaning that the simulated Z-scores of successive layers have similar tendencies. The value of ρ (Equation 2) controls the magnitude of this tendency and thus, it is likely that with higher ρ , successive Z-scores would be more similar, and as a result, unrealistic V_s values would be mitigated. As shown in Fig. 11c, the parameters recommended by Passeri et al. (2020) for the correlation model result in ρ below 0.6 for the sample simulated profile. However, as we argue next, because tts is a cumulative parameter, values at successive depths should be more highly correlated. Below, we revisit the Greenfield site and then use Monte Carlo simulations to examine appropriate ρ values.

4.3.3 Investigations for ρ based on real data

Fig. 12 compares the ρ of the tts profiles from the V_s measurements at the Greenfield site to those calculated using the model adopted by Passeri et al. (2020) (Equations 2–4). The functional form of this model is based on Toro (1995), but we use the parameters recommended by Passeri et al. (2020) for tts randomization. As shown in Equations 2–4, ρ is assumed to be depth- and thickness-dependent. Consequently, to investigate the influence of inter-layer separation distance (i.e., t in Equation 4) on the Greenfield site data, ρ was computed for thicknesses of 2, 10, and 20 m, as shown in Fig. 12. We note that ρ relates the tts Z-scores at successive depths (similar to Equation 6). Thus, to back-calculate the empirical ρ values from the field V_s profiles, tts Z-scores were first computed for each tts profile. Then, ρ values were computed between all Z-scores using separation distances of 2, 10, and 20 m (Fig. 12b). The 2 m results are better suited for the near surface, where layers are generally thinner, whereas those from either 10 m or 20 m are better suited for greater depths.

The high tts inter-layer correlation is strikingly evident in Fig. 12b, which shows that a tts profile that is above the median (i.e., positive Z-score), remains above the median with almost the same Z-score, and vice versa. Quantitatively, the ρ for 2 m separation distances based on the Greenfield site data is above 0.85 at all depths, whereas that based on Passeri et al. (2020) remains below 0.8 over nearly the entire depth (Fig. 12c). For higher separation distances, ρ is low in the near surface for the Greenfield site data, which is not surprising because thicker layers generally do not occur at shallow depths. However, as depth increases, the Greenfield site data ρ values for both 10 and 20 m rapidly increase beyond 0.8. All three separation distances show similar trends of high ρ at depths greater than 40 m that approach 1.0, which is much greater than the ρ values from Passeri et al. (2020). Fig. 12 strengthen our argument that, since tts is cumulative, ρ is higher than results from the generic model. Therefore, in what follows, we will investigate the effect of using higher ρ on tts randomization results.

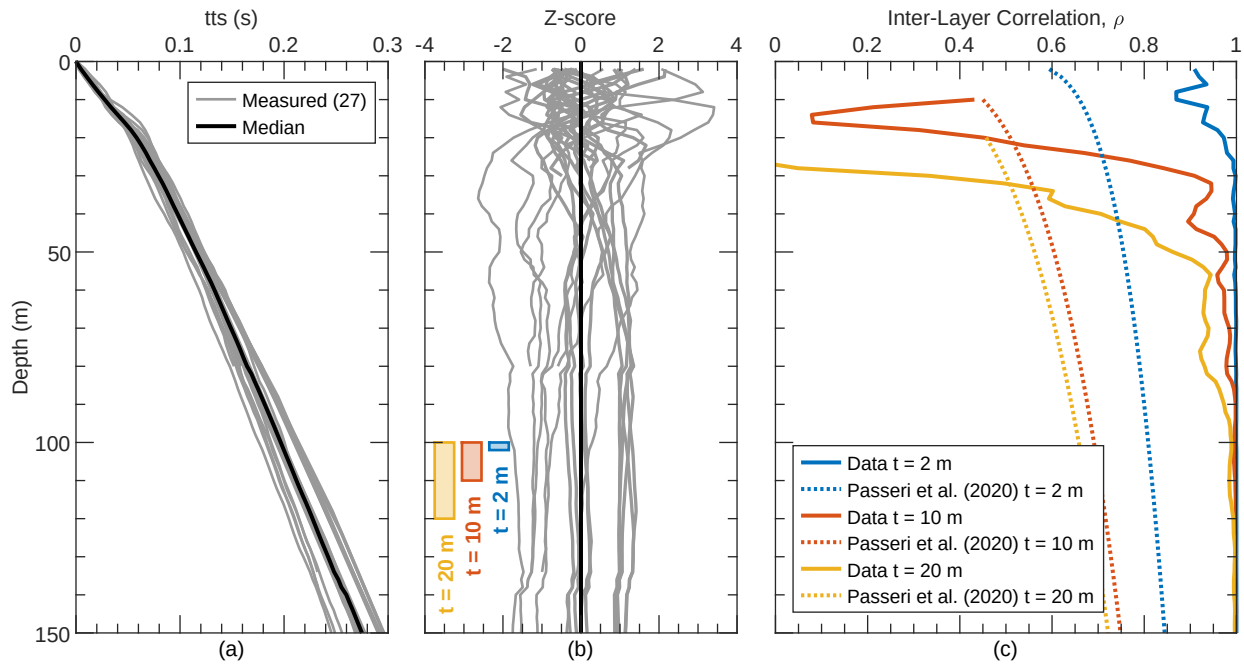


Figure 12: (a) Comparison of the tts profiles and their median from the 27 measured V_s profiles at the Greenfield site (Fig. 9). (b) Comparison of the tts Z-scores of the tts profiles, which simply represent the number of standard deviations a tts profile is from the median tts with depth. (c) Comparison of the inter-layer correlation (ρ) values from the Greenfield site data with those from the generic model adopted by Passeri et al. (2020) for three different thicknesses (t).

4.3.4 Investigations for ρ based on simulations

Fig. 13 shows the V_s profiles simulated from tts randomization at the TIDA site with $\sigma_{lntts} = 0.10$ and using the generic ρ model and higher ρ obtained by adding fixed values of 0.2 and 0.4 to the generic ρ . We note that we believe $\sigma_{lntts} = 0.10$ might be too high for the TIDA site, but is used herein to examine whether increasing ρ mitigates unrealistic V_s profiles from tts randomization. The ρ values from the generic model ranged between 0.45–0.65, depending on the layer thicknesses and depth, and those increased by 0.2 thus ranged between 0.65–0.85, whereas those increased by 0.4 ranged between 0.85–1.00. Fig. 13 demonstrates that increasing ρ mitigates unrealistic V_s profiles, and consequently, decreases σ_{lnVs} , even though all results are based on the same σ_{lntts} . The decrease in σ_{lnVs} with increasing ρ is a manifestation of not allowing profiles with unrealistic V_s to be generated from overlapping tts distributions.

The most intriguing observation from Fig. 13 is that although ρ influences the simulated V_s profiles and their σ_{lnVs} , the results suggest that it has a minor effect on the mean TTFs (Fig. 13g). Except for slight differences in the mean TTFs near the fundamental mode, the results are comparable for all ρ and still provide poor site response estimates at higher frequencies. One possible explanation is that all simulations were based on the same σ_{lntts} , which is the key parameter controlling the extent of variability incorporated into GRA. Nonetheless, even if the mean TTF appears to be unaffected by ρ for this particular case, it is important that this parameter be appropriately specified to avoid generating unrealistic V_s profiles. The appropriate value of ρ is site-specific, but it appears that values in excess of 0.7–0.8 are more appropriate when implementing tts randomization, particularly for deeper layers. In order to maintain depth-dependent values, engineers can either increase ρ from the generic model by approximately 0.2–0.3 or adjust the model parameters in Equations 2–4 to guarantee a higher ρ . Site-specific tts ρ values can also be developed if multiple V_s measurements are available (refer to Fig. 12).

While using higher ρ helps mitigate unrealistic V_s profiles with excessively high or negative V_s values, we strongly recommend that when performing any statistical randomization, a robust screening criteria be invoked. For example, Griffiths et al. (2016a,b), Teague et al. (2018), and Teague and Cox (2016) proposed and examined a strategy to exclude randomized V_s profiles that fail to reasonably fit the experimental “site signature” (i.e., broadband experimental surface wave dispersion data and fundamental site frequency estimates from H/V curves). Hallal et al. (2022) implemented similar site signature screening for V_s randomization results at two vertical seismometer arrays and demonstrated the significant improvements that can be achieved to site response predictions. Screening

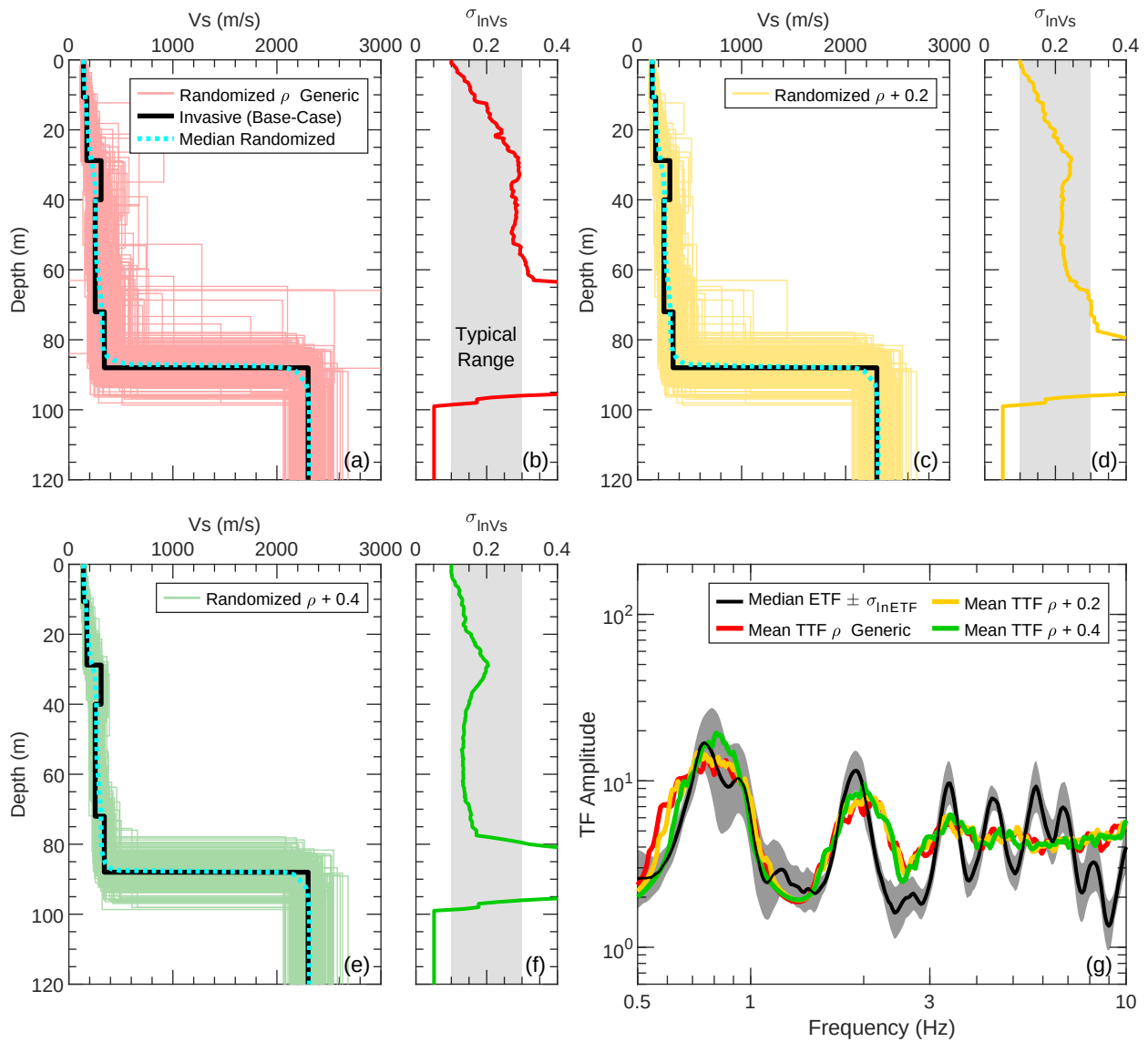


Figure 13: (a, c, e) V_s profiles developed through tts randomization with different levels of ρ and constant $\sigma_{lntts} = 0.10$ at TIDA. (b, d, f) Comparison of the resulting σ_{lnVs} of the simulated V_s profiles with typical ranges, as shown in the gray shaded area, which can help interpret the influence of σ_{lntts} on V_s variability. (g) Influence of different levels of ρ on the mean TTF and their comparison to the observed median ETF at TIDA. The simulations with higher ρ in (c) and (e) are simply based on adding fixed values of 0.2 and 0.4, respectively, to the generic, depth-dependent ρ used in (a).

unrealistic profiles could also be potentially performed using the fundamental site frequency estimated from H/V curves and V_{S30} values, which are more readily available than broadband experimental surface wave dispersion data. However, this requires further examination to establish best screening practices.

5 Discussion and future developments

The assessments presented above demonstrate some of the pressing challenges associated with tts randomization, for which we provided guidelines and recommendations for improved implementation. A summary of the recommendations and improvements introduced in this article is provided in Table 1. We would like to emphasize that these recommendations do not require any additional model parameters or constraints. For the sake of simplicity, we opted to strictly adhere to the work of Passeri et al. (2020), but with improved implementation. While the framework presented herein forms the basis for an improved methodology to incorporate variability into site response, this research raises additional questions in need of further investigation.

Table 1: Summary of the steps of *tts* randomizations, their implementation by Passeri et al. (2020), and their recommended improved implementation as proposed in this article.

Steps of <i>tts</i> randomization	Passeri et al. (2020)	This article
Imposing acceptable layer thickness bounds	Truncating unacceptable layers at bounds	Re-simulating unacceptable layers
Defining acceptable layer thickness bounds	Rate-symmetric bounds (e.g., $\pm 50\% \lambda$)	Mean-consistent bounds (e.g., $[-30\%, +50\%] \lambda$)
Merging column and bedrock models	Simulating column models once	Re-simulating unacceptable column models
Specifying σ_{lntts} for randomizing <i>tts</i>	0.01–0.02	~ 0.05
Specifying ρ for randomizing <i>tts</i>	Generic model (Equation 2)	Equation 2 + fixed value (e.g., Equation 2 + 0.2)

First, while constraining the layering model, as introduced by Passeri et al. (2020), helps mitigate unrealistic layers, this requires two additional input parameters: upper and lower acceptable bounds. In addition, the assessments undertaken in this article have revealed that the procedures through which these bounds are imposed and defined can introduce unintended bias into the distribution and mean of the final simulated layer thicknesses. While our recommendations for re-simulating unacceptable layers and using mean-consistent bounds overcome this bias, this is still based on the adjustments of Passeri et al. (2020). The prospect of being able to randomize layer thickness more simply and realistically using an alternative statistical model that does not need to be bounded in a specific way should serve as an incentive to future research.

Second, while our assessments at the Greenfield site and the TIDA site provide evidence of the need for using higher σ_{lntts} than 0.02 when accounting for spatial variability, even for sites with low variability, both evaluated sites have V_{S30} values consistent with soil conditions. Future work should focus on developing appropriate σ_{lntts} recommendations for different site conditions and for sites with differing degrees of variability. On a wider level, research is also needed to determine whether σ_{lntts} is depth independent, as suggested by Passeri et al. (2020). Results from the Greenfield site (Fig. 9d) suggest that σ_{lntts} is higher at shallow depths, which is consistent with the higher near-surface V_s variability reported in other studies (Garofalo et al., 2016a,b).

Third, we have shown that using higher ρ for *tts* is critical to avoid unrealistic V_s profiles, particularly at depth and at stiffer sites, where *tts* distributions might overlap. Because the data we presented herein and all models adopted in the literature argue that ρ is likely depth-dependent, we sought to achieve a higher depth-dependent ρ by simply increasing the values computed from the generic model from Passeri et al. (2020) by a fixed value between 0.2–0.3. However, developing a new set of correlation model parameters is an important aspect to pursue. While recommendations for higher σ_{lntts} and a higher ρ values are provided, it is clear that engineers must put more thought into the site-specific determination of σ_{lntts} and ρ when implementing *tts* randomization.

Fourth, based on preliminary assessments the authors have performed, randomizing the time-averaged V_s instead of *tts* is another potential improvement. Passeri et al. (2020) argued that randomization can be performed on *tts*, or equivalently, on the time-averaged V_s . However, the authors discussed their framework only in terms of *tts*. Nonetheless, the time-averaged V_s can help mitigate unrealistic V_s profiles resulting from overlapping *tts* distributions without using higher ρ . This is because overlapping time-averaged V_s distributions are not necessarily unrealistic, and the slope of the time-averaged V_s between two depths can be vertical or backward. These would correspond to a V_s equal to the time-averaged V_s or lower, respectively, rather than excessively high or negative V_s when performing *tts* randomization. More research on this topic is needed.

6 Conclusions

It is standard practice to model the variability in V_s profiles in 1D GRA for critical facilities and major infrastructure using a stochastic framework, such as that developed by Toro (1995). However, several studies have expressed concerns about the blind application of this approach. Randomization can be alternatively performed on *tts*,

which deals with a single random variable with depth, as proposed by Passeri et al. (2020). Nonetheless, despite potential improvements from implementing *tts* randomization, adoption of this new framework in practice is limited due to the fact that it has not been thoroughly validated yet.

In this article, we scrutinized the outstanding challenges of *tts* randomization and devised strategies for improved implementation that are grounded in fundamental principles of statistics and probability. These challenges and recommendations particularly pertain to: (1) methods used for bounding simulated layers, (2) approaches for merging column and bedrock models, and (3) appropriate values of σ_{Intts} and ρ for randomizing *tts*. The positive impacts of this work are better understanding of *tts* randomization and more confidence in adopting this approach. The guidelines for improved implementation of *tts* randomization, combined with the original framework of Passeri et al. (2020) and the future directions that were outlined in the Discussion and Future Developments section, will work towards better modeling and propagation of V_s variability in 1D GRA.

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