1	A superhydrophilic AFM tip as a nanosensor of hydrophobicity:
2	a rationale for a new analytical method
3	A. Méndez-Vilas
4	Formatex Research Center SLU, 06010 Badajoz, Spain
5	Correspondence: e-mail: <u>amendezvilas@gmail.com;</u> Phone: +34644389624
6	Personal website: <u>https://scholar.google.es/citations?user=XVejCGYAAAAJ</u>
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8 Accessing surface hydrophobicity (SH) via the water contact angle value (θ_w) at a local (nm) 9 scale, or in a region (nm resolution), is of obvious interest in virtually any field of the natural 10 sciences and related engineering.

To achieve that, the method proposed in this short article exploits the presence of a na-11 12 noscale water capillary formed between an AFM tip and any surface in ambient conditions, the characteristics of which depend on the value of θ_w of both the tip apex zone ($\theta_{w-tip-apex}$) 13 14 and the surface under study ($\theta_{w-surface}$), as well as on the tip radius, according to the simplest possible theoretical model. This water capillary is the responsible of the pull-off force (Fpull-15 off) measured by the AFM. The tip radius can be precisely measured by SEM/TEM. The key 16 of this method is that in it, the value of $\theta_{w-tip-apex}$, a quantity not directly available, is a well-17 defined fixed quantity. This may be achieved by using a recently released tip material (tita-18 nium nitride) instead of the common silicon nitride. Luckily for our purpose, this material 19 bears a perfectly clean, superhydrophilic TiO₂ surface ($\theta_w = 0^\circ$) after a simple modification 20 (surface oxidation and UV-light illumination). The time this effect lasts is well above that 21 22 taken by the AFM in getting Fpull-off over a region. This way, for each Fpull-off measured, a value of $\theta_{w-surface}$ can be derived. 23

In summary, a lucky synergy between a newly introduced tip material and the easiness of fixing its θ_w by rendering it superhydrophilic, makes it possible to obtain a map of SH (θ_{w} surface) from a raw F_{pull-off} map. In other words, it potentially turns the AFM into a fast, local, high-resolution, and quantitative sensor of θ_w or SH.

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Keywords: AFM tip; adhesion force; water contact angle; surface hydrophobicity; TiO2;
sensors



Some fundamentals on surface hydrophobicity, AFM tips and the capillary force in gas eous environments.

60 Surface hydrophobicity (SH) is a fundamental property that plays a fundamental role in natural phenomena like mineral flotation or protein folding and in the production of commercial 61 62 goods in the automotive or aerospace (e.g., superhydrophobic coatings), in the biomedical (antibacterial paints), or textile (stain-resistant textiles or flame-retardant and waterproof 63 clothing), to name a few. It is key in the microelectronics since prevents metal oxidation or 64 corrosión.¹ Due to this, much attention has been paid in the past to measure SH, usually 65 focusing on the average surface wettability (statistical average). But most materials are in-66 herently heterogeneous. Efforts are being made to quantify SH and its distribution at local 67 scales, therefore. AFM or its variations are techniques being used to this end, like Chemical 68 Force Microscopy^{2,3,4,5,6} or Colloidal Probe Microscopy⁷. But these methods do not provide 69 a relationship to values of water contact angle (which is a widespread and facile method) 70 and are conducted underwater and not at environmental conditions. In this proposal, the 71 nanoscale heterogeneity of SH is directly mapped using an AFM derived water contact angle 72 method, under ambient conditions, taking advantage of the ubiquitous water capillary that 73 bridges any asperity (as the AFM tip) and another surface. This is done directly in environ-74 mental conditions, where many phenomena occur, which should aid higher comparability 75 with the much research that uses the water contact angle. 76

Following the calculations by O'Brien and Hermann and the works of Israelachvili and Riedo^{8,9,10}, when a sphere (tip) of radius R_{tip} is in contact with a flat surface, a capillary annulus of condensed water is formed around the contact surface. The resulting capillary/adhesion (pull-off) force, the dominant force in ambient conditions, is:

$$F_{pull-off} = 2 \pi R_{tip} \gamma_{lv} (\cos \theta_{w-tip-apex} + \cos \theta_{w-surface})$$
Equation 1

In our proposed setup, $F_{pull-off}$ is maximum, since $cos(\theta_{w-tip-apex}) = 1$, the highest possible value, so

$$F_{pull-off} = 2 \pi R_{tip} \gamma_{lv} (1 + \cos \theta_{w-surface})$$
 Equation 2

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86 That is, making the tip superhydrophilic maximizes the amount of water the meniscus bear.

These experimental conditions make the capillary model even more justified (Fig. 1).



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Figure 1. Schematics of a F_{pull-off} measurement using a superhydrophilic AFM tip on a het erogeneous surface.

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Since this is a new experimental design, we prefer to present here the simplest possible theoretical model (limitations found in other studies may not apply here, since the tip wettability is perfectly defined, and not only that, but it may be considered as clean). Depending on the success of experiments, researchers may want to use others: they shall find it easier than with conventional tips since this time the tip wettability is well defined and stable over the experimentation time (due to its self-cleaning property). But first things first: check the simplest possible model, that if successful will generate greater interest and broader use.

The research about surface forces in gaseous environment is vast and controversial. Since 101 much of the mismatch between theory and experiment my arise from values of magnitudes 102 not well accessible experimentally (though well defined in theory), and specially from the 103 104 subtle but strong influence of airborne contaminants in both AFM and macroscopic contact angle measurements (almost any surface exposed to air increases its water contact angle, 105 even when adsorbed organic compounds can be considered at a trace-level), this research 106 community may benefit from this new experimental setup. 107 108

110 2. Easy production of a superhydrophilic (not only highly hydrophilic) tip

How can this be done? The starting point comes from nano-industry: some firms have re-111 cently introduced a novel Ti-based material, say titanium nitride (TiN), for coating their AFM 112 tips. Why has this material been introduced? The main reasons are¹¹: 1) They are conduc-113 tive (in fact, these tips are usually used in electrical AFM-based measurements); 2) TiN 114 coatings are hard and wear-resistant; 3) Resulting tip curvature are in the range of 40-60 115 nm after coating, which is acceptable; 4) The coating remains in the nm range (about 35) 116 nm) and is uniform; 5) It is stress-free and does not significantly bend the cantilever; 6) Shelf 117 life about 3 months (the limitation due to humidity). What is the scientific basis of the process 118 of TiN coverage? These old articles accounts for it^{12,13}. 119

120 As specified above, these tips are not of general use, so let us describe them and their availability in some detail. These three companies are producing and selling TiN-covered 121 122 tips. AIST-NT Inc. (USA) (http://nanoprobes.aist-nt.com/ Claims to have 15 years of experience in the sector, so a stable service can be expected. It has developed TiN-coated contact 123 124 AFM cantilevers/tips with resonance frequencies in the range of 10-20kHz and cantilever spring constants (k_c) in the range of 0.03-0.1 N/m (k measures how stiff a cantilever is). The 125 126 total tip curvature is 40-60 nm, and the height and cone angle are 7-10 µm and ≤22°, respectively. The thickness of the coating is about 35 nm. The products names are: 127 fpC10TiN,fpC11TiN,fpC01TiN. Applied NanoStructures, Inc. (USA), known as AppNano 128 (http://www.appnano.com). This firm develops conventional and specialized AFM probes. 129 The facilities include a clean room with state-of-the-art characterization tools for rapid pro-130 totyping, adaptability, and versatility in designing and developing new products. From their 131 website's age, this company has at least 15 years of experience. Their TiN covered tips for 132 contact applications- are called TiN-FORT. They a resonance frequency of 61 kHz and a kc 133 of 1.6 N/m. The radius of curvature is 30 nm. They also have non-contact or intermittent-134 contact probes with 37 N/m and 300 kHz values. NT-MDT LLC (Russia) (https://www.ntmdt-135 si.com). IT develops research equipment, primarily atomic force microscopes (AFM) and 136 137 their combinations with ultra-high resolution spectroscopy. It is represented by companies in Russia, Europe, the USA, and China. It has a history of more than 30 years in the sector. 138 139 It commercializes TiN-cover tips, compatible with the most of commercial AFM devices. Typical curvature radius of uncoated tips is 6 nm (no data on covered ones). Cone angle at the 140 apex: 7° - 10°. 141

In conclusion, luckily there are at least three reliable companies producing and selling TiNcoated AFM tips. Now the question is: How can we render these tips superhydrophilic?

This is not difficult. Simple treatments are available for a medium sized surface science/materials science lab to oxidise the surface of TiN to TiO₂, the best known self-cleaning superhydrophilic material (only needs UV-light illumination). One simple way is the ozonisation of the original TiN tip. As described in¹⁴, O₃ oxidizes TiN to form a layer of TiO₂ on the surface. The oxidation reaction, thermodynamically favourable, proceeds as follows:

$$\begin{array}{rrrr} TiN + 3O_3 \rightarrow TiO_2 + NO + 3O_2 \\ 149 \end{array}$$
 Equation 3

This produces a stable and self-passivating TiO₂ layer that impedes further oxidation. An alternative way, called thermal oxidation, is using heat to oxidize TiN since this material oxidizes to titanium dioxide (TiO₂) at relatively low temperatures, as low as 350 °C in air (Fig. 2).^{15,16,17}



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Figure 2. Schematics of the process of getting TiO₂ over the surface of TiN.

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How can we render a TiO₂-covered tip superhydrophilic? The phenomenon of turning TiO₂ 157 158 superhydrophilic is well known. It was first reported in a *Nature* paper in 1997 by the group of Prof. Akira Fujishima, from University of Tokyo.¹⁸ They discovered that a TiO₂ surface, 159 160 whose water contact angle may vary considerably (from hydrophilic to hydrophobic) depending on environmental conditions, becomes superhydrophilic ($\theta_w = 0^\circ$) after being exposed to 161 UV radiation during some hours. Nowadays, this is called the superhydrophilic self-cleaning 162 effect, being this the basis of important applications and product develolopments^{19,20}. The 163 phenomenon is explained by the production of radical species due to the formation of oxy-164 gen vacancies at the bridging sections of TiO2, which has two effects: it induces complete 165 166 wetting of water and the decomposition of organic contaminant adhered. Particles adsorbed are also carried away by a thin water layer formed at the illuminated surface. Hydrophobic 167 recovery occurs when the material is kept in dark during some (typically some days) or 168

exposing it to heat (typically hours or even minutes^{21,22,23}. Luckily for our purposes, TiO₂ is
 one of the few materials that becomes superhydrophilic in such a simple way. UV illumina tion is therefore the last step in getting our TiO₂-covered tip superhydrophilic and clean (Fig.
 3).



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Figure 3. Schematics of how to transform TiO₂ into superhydrophilic.

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Needless to say, the k_c and R_{tip} might have changed to some degree due to the TiO₂ layer 176 grown. Therefore, they must be measured before using the tip. This is straightforward, as 177 they are usual calibration steps in AFM-based experimentation if one does not want to settle 178 for the data provided by the companies. Rtip can be measured directly by SEM/TEM or indi-179 rectly by the blind estimation algorithm, available in various AFM software packages, such 180 as Gwyddion, WSxM and SPIP ^{24,25}. kc can be measured using the thermal noise method, 181 among others.²⁶ The whole process of getting a superhydrophilic tip from a bare TiN one is 182 schematized in Fig. 4. 183



Figure 4. Schematics of the whole process of getting a superhydrophilic tip from a bareTiN one.

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188 3. Other surface science research that might benefit from this new experimental design.

189 Though I am a experimentalist, I feel that many previous works reporting a mismatch be-190 tween the theoretical models available or developed could be repeated with a well-defined

and stable AFM tip like the one proposed in this note: the mismatches might had been

absolutely "impossible to check" factors at time they were conducted: relying in the measurement of the wettability of a macroscopic surface of the "same material" than the tip may a good decision since the tip status may vary, even erratically, during an experiment, behaving like a "collector" of adsorbed contaminants²⁷ or simply due to differences arising from the different methods used for synthesizing or processing, even having the same bulk composition. In the case of using superhydrophilic, self-cleaning tips, their properties remain stable for days.

If experimental results require to use other refined theoretical models available in the litera ture, other variables might be required, such as the tip-surface distance (usually denoted as
 D), relative humidity (RH), or the rms roughness of the substratum (R_q), which are accessible
 from AFM data or the environmental chamber

Eventually, depending on how successful experiments are, a kind of method-specific "hydrophobicity" (e.g., superhydrophilic AFM tip derived SH) could be developed, that would add to other existing: for example, the "hydrophobicity-index" used in the biological field to get a numerical estimate of how hydrophobic the cell surface of a bacteria or a fungus is²⁸, the SH derived from capillary AFM interactions with chemically modified tips²⁹, from Chemical Force Microscopy^{2,3,4,5,6} or Colloidal Probe Microscopy interactions⁷, or that derived from ESEM images of water micro (not nano) droplets.³⁰

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4. A singular configuration: both superhydrophilic tip and substratum

This configuration is particularly interesting because it predicts a fixed value of $F_{pull-off}$ for a chosen tip. $F_{pull-off}$ takes here its maximum value (both cosines equal 1), say

 $F_{pull-off} = 4 \pi \gamma_{lv} R_{tip}$

Equation 4

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215 Thus, a measured value of F_{pull-off} can be used to retrieve a measure of R_{tip}:

$$R_{tip} = \frac{F_{pull-off}}{4 \pi \gamma_{lv}}$$
Equation

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In summary, we could measure $F_{pull-off}$ on a TiO₂ irradiated substratum previous to the material of interest as a way of obtaining R_{tip} . This is straightforward: extended TiO₂ surfaces are commercially available (check, for example, MSE supplies,

https://www.msesupplies.com, or Shinkosha, https://www.shinkosha.com). Researcher who 220 have not got access to a SEM or TEM apparatus might find this useful. 221

Again, if experimental data dot not fit the theoretical models and the cause might be insuffi-222 cient water adsorbed for capillary condensation to occur (as some authors have claimed in 223 224 studies made with conventional tips), relative humidity (RH) inside the environmental chamber could be raised until fulfilling the theoretical requirements. This configuration maximizes 225 the amount of water available for formation of the capillary, so my impression is that it worth 226 making the experiments, analysing the data with the simplest model first, and using refined 227 models available in the literature available, if necessary. 228

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- 5. A singular configuration: a non-superhydrophilic tip and superhydrophilic substratum 230
- An accessory unexpected advantage may come from the measurement of Fpull-off when using 231
- a conventional tip and a superhydrophilic substratum (Fig. 5). In this case, equation 1 reads: 232



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Figure 5. Schematics of a F_{pull-off} measurement using a superhydrophilic AFM tip on also 235 superhydrophilic superhydrophilic surface. 236

Therefore, the only unknown is $\theta_{w-tip-apex}$. That is, measuring $F_{pull-off}$ on a superhydrophilic substratum could be a facile method for measuring/calibrating the wettability of the tip apex. This value could further be used in ulterior studies using another substrate of interest. This would make possible another physical quantity (wettability) of the tip apex, which is the real sensing part, to be accessible experimentally.

This is a non-trivial advantage: due to the its nm size, potentially irregular shape or contam-243 ination, methods to probe its physico-chemical status urge. Whereas it is "easy" to check its 244 physical (shape and general status) by SEM or TEM, which do have nm resolution^{31,32} or 245 using advanced reconstruction algorithms applied to AFM images taken with it, the precise 246 chemical status under the working ambient conditions might be impossible to access, since 247 only TOF-SIMS has the required resolution (nm)²⁷, but as SEM/TEM requires high vacuum 248 and is its capacity of revealing the of molecular nature of the substances present is limited 249 due to the aggressive nature of the ionic bombardment of the surface. Surface wettability 250 $\theta_{w-tip-apex}$ is an intermediate physico-chemical parameter, but its measurement to such a ul-251 trasmall region is also challenging. Measuring Fpull-off on a superhydrophilic substratum could 252 provide a solution. If successful, we could well characterize the wettability of an arbitrary tip 253 without relying on the macroscopic water contact angle acquired over a substratum of the 254 "same material" whose surface status might not be "sufficiently equivalent" to reality in the 255 context of magnitudes so exquisitely dependent on the "true surface" as contact angles and 256 surface forces are. 257

Finally, I would suggest another way of testing this obtained value. It would be worth imaging microscopic water droplets nucleated on the tip in an ESEM apparatus, trying to locate the droplets as close to the apex as possible. I only know about microscopic and not nm scale water droplets imaged by ESEM (see my review³⁰ for details), but potentially useful and complementary information may arise in dedicated works.

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