

Asymmetries in electromagnetic interactions: A virtual-wire model for reactionless propulsion with preliminary experimental validation

Abstract

This study investigates asymmetries in electromagnetic forces within non-closed current systems. A systematic analysis of the "carrier asymmetry" phenomenon leads to a reactionless propulsion concept based on an open-circuit coil. To address momentum conservation within classical electrodynamics, we propose a "virtual-wire" model that transforms the physical open-circuit coil into a virtual closed loop by introducing an ideal, massless conductor segment. This formulation links the observed net thrust to the directed flux of electromagnetic field momentum arising from structural symmetry breaking. Two independent experimental setups were designed for preliminary observations. The primary setup uses a C-shaped working coil (12,000 turns, 70° opening) driven at 100 MHz (≈ 5 W, 0.3 A). Direction-reversal tests (opening oriented east, south, west, and north) and stationary controls reveal reproducible displacement opposite the opening direction, with an estimated net thrust on the order of 10^{-4} N. Tracker video analysis shows a buildup lag and decay tail on the order of seconds, consistent with a near-field momentum storage mechanism. Error analysis and statistical testing confirm the reliability of the observed effect. This work provides a self-consistent theoretical framework and experimental reference for exploring novel propulsion mechanisms within classical physics.

Keywords: Electromagnetic interaction; Force asymmetry; Reactionless propulsion; Virtual-wire model; Momentum conservation; Open-circuit coil.

23 **1. Introduction**

24 Newton's third law is a cornerstone of macroscopic mechanics. In electromagnetism,
25 however, momentum conservation in finite, open, or transient current systems requires the
26 inclusion of electromagnetic field momentum. This classical requirement implies that, under
27 specific configurations, electromagnetic forces on current elements may exhibit asymmetries
28 such as temporal misalignment, non-collinearity, or carrier asymmetry. Investigating these
29 phenomena may inspire propulsion principles that do not rely on reaction mass expulsion.

30 This study systematically categorizes several typical forms of asymmetry in
31 electromagnetic interactions. Based on this categorization, we propose a reactionless
32 propulsion concept that exploits carrier asymmetry. The core idea is to break the internal self-
33 balance of electromagnetic forces within a loop by designing a geometrically incomplete
34 current-carrying circuit—an open-circuit coil—thereby generating a net force on the remaining
35 physical conductors (the Physical Segment). Such a concept, however, immediately raises a
36 fundamental theoretical question: how is momentum conserved?

37 To address this question, the primary contribution of this work is the original proposal of
38 the "virtual-wire" physical model. Operating strictly within Maxwell's equations and the
39 Lorentz force law, this model offers a clear, self-consistent, and classically grounded
40 framework for understanding momentum conservation in open-circuit coil systems. Second,
41 we conducted preliminary experiments that yielded qualitative indications consistent with the
42 model's predictions, providing a starting point for future quantitative verification.

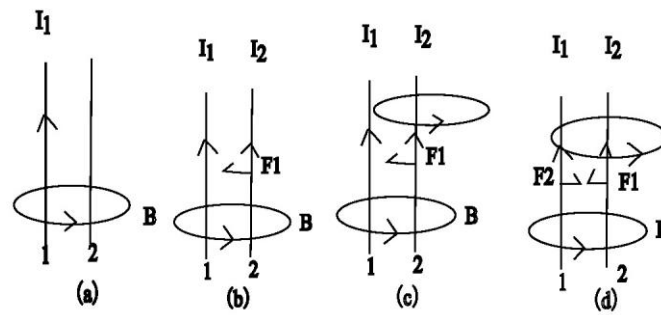
43 **2. Three Forms of Asymmetry in Electromagnetic** 44 **Interaction**

45

46 This section systematically analyzes several forms of asymmetry that electromagnetic
47 forces may exhibit under specific configurations within classical electrodynamics. These forms
48 differ from the simple, intuitive version of Newton's third law. They do not violate physical
49 conservation laws but instead emphasize that in electromagnetic systems, momentum must be
50 carried jointly by matter and the field.

51 **2.1 Temporal Asymmetry: Time Delay Between Action and** 52 **Reaction Forces**

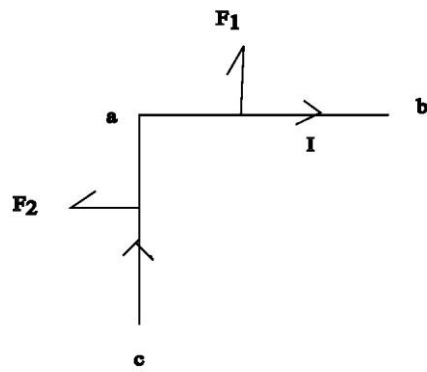
53 Due to the finite speed of light, an inherent delay exists in the force interaction between
54 source and receiver during transient processes. Consider two parallel straight wires separated
55 by a sufficient distance (Fig. 1). When the current in one wire changes abruptly, the change in
56 magnetic force experienced by the other wire lags. During this delay, the net force on the two-
57 wire system is nonzero until a new equilibrium field is established. This classical phenomenon
58 reveals temporal asymmetry in electromagnetic interactions during transients. The total
59 momentum of the system (mechanical momentum of the wires plus field momentum) remains
60 conserved, but the mechanical momentum changes of individual parts are temporally
61 misaligned.



62 **Fig.1 Schematic illustrating the transient delay of electromagnetic forces between parallel**
 63 **straight wires.** (a) Wire 2 is already within the magnetic field of wire 1, which carries a steady
 64 current. (b) At time t_0 wire 2 is energized and immediately experiences a force from wire 1's
 65 field. (c) During the interval Δt , the field generated by wire 2 has not yet propagated to wire 1,
 66 so wire 1 experiences no force. (d) After Δt , forces between the two wires reach equilibrium

67 **2.2 Directional Asymmetry: Non-Collinearity of Action and** 68 **Reaction Forces**

69 The direction of electromagnetic force is strictly governed by the Lorentz force
 70 law, $\mathbf{F} = I \int d\mathbf{l} \times \mathbf{B}$. In complex current configurations, the forces on two interacting current
 71 elements may not lie along their connecting line. A typical example is two perpendicularly
 72 connected wire segments (Fig. 2). The Ampere forces between them are equal in magnitude
 73 but mutually perpendicular, rather than collinear and opposite. This shows that the directions
 74 of an electromagnetic "force pair" are determined by the local current element directions and
 75 the external magnetic field. Their points of application and reaction may be spatially separated,
 76 embodying directional non-collinearity.

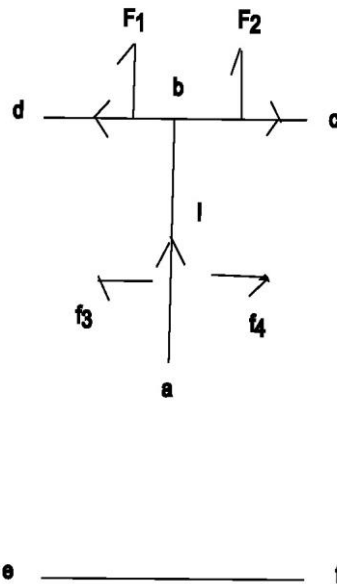


77 **Fig.2 Schematic illustrating the direction of Ampere forces between perpendicularly**
 78 **connected wires.** Wires ca and ab are perpendicular and carry current. According to the
 79 Ampere force law, the force F1 on wire ca is perpendicular to itself, and the force F2 on
 80 wire ab is also perpendicular to itself. Although $|F_1| = |F_2|$, the two force vectors are
 81 perpendicular, not satisfying a collinear and opposite relationship

82 **2.3 Carrier Asymmetry: Apparent "Disappearance" of Net** 83 **Internal Reaction Force**

84 When analyzing a subsystem of a complex current-carrying loop, an intriguing
 85 phenomenon may occur: the subsystem exerts a net force on other parts, while the vector sum
 86 of the reaction forces from those other parts upon it is zero. For instance, in a specific
 87 symmetric three-wire structure (Fig. 3), the middle wire exerts forces on the two parallel side
 88 wires. However, due to symmetry and opposite current directions in the side wires, their
 89 reaction forces on the middle wire cancel each other. From the subsystem's perspective, it
 90 "exerts force" while itself "experiences no force"—the net reaction force appears to disappear.
 91 This disappearance is an apparent phenomenon that arises when analyzing the specific wire
 92 structure as an isolated subsystem. In reality, when considering the entire closed-loop system,
 93 the reaction force is transferred to other corresponding parts of the loop, and the total

94 mechanical force of the entire system is zero. This carrier asymmetry provides a key idea for
 95 actively designing unbalanced electromagnetic force systems and serves as the core basis for
 96 the propulsion concept in this paper.



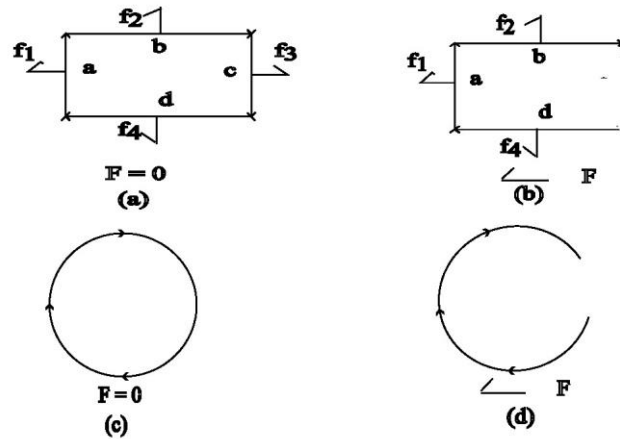
97 **Fig.3 Schematic of a three-wire structure illustrating "carrier asymmetry" in**
 98 **electromagnetic interaction.** Wire ab is connected to two parallel wires bd and bc of equal
 99 length. When current flows as shown, wire ab exerts forces (F1 F2) on bd and bc, but the
 100 reaction forces f3 and f4 from them on ab sum to zero due to symmetry. Wire ef represents the
 101 equivalent part in a physically closed loop that would bear this reaction force

102 **3. Propulsion Concept Based on Open-Circuit Coils and** 103 **the Virtual-Wire Theoretical Model**

104 **3.1 Propulsion Concept**

105 Based on the carrier asymmetry phenomenon elaborated in Section 2.3, we propose a
 106 propulsion concept. By actively designing a current-carrying loop with an incomplete
 107 geometric structure—namely, an open-circuit coil (such as a U-shaped or C-shaped coil)—the

108 self-balance of internal electromagnetic forces within the loop is disrupted (Fig. 4). Through
 109 electromagnetic induction, the open-circuit coil acquires an induced current (due to the open
 110 ends, the induced current exhibits a standing wave distribution with nodes at the two open ends).
 111 Theoretically, a net force is generated on the open-circuit coil. Its essence is the vector sum of
 112 the Lorentz forces experienced by the currents in these conductors within the asymmetric
 113 magnetic field produced by the entire coil (including the virtual closed path introduced for
 114 analysis). The momentum of the entire system (coil + electromagnetic field) is strictly
 115 conserved.



116
 117 **Fig.4 Schematic comparing forces on closed loops and open-circuit coils.** (a) & (c): The
 118 total electromagnetic force on a complete closed current loop is zero, indicating self-balance.
 119 (b) & (d): When part of the loop is removed, the remaining open-circuit coil portion loses part
 120 of its internal balance, resulting in an apparent net external force

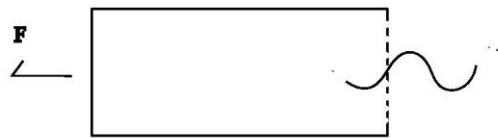
121 3.2 Original Theoretical Model: The Virtual Wire

122 The concept of an open-circuit coil generating net force immediately raises the question of
 123 momentum conservation: where is the reaction force corresponding to this thrust? To provide

124 a self-consistent explanation within classical electrodynamics, we propose the "virtual-wire"
125 model.

126 3.2.1. Model Construction

127 In the theoretical analysis, an ideal, massless, zero-resistance virtual-wire segment is used
128 to connect the two open ends of the physical open-circuit coil, thereby forming a virtual,
129 complete closed current loop (Fig. 5). All field and force calculations are performed within this
130 virtually closed loop.



131 **Fig.5 Schematic of the “Virtual-Wire” model.** The solid lines represent the physical open-
132 circuit coil. The red dashed line represents the “Virtual-Wire” used for theoretical analysis.
133 Together, they form a virtual closed loop for calculation and analysis

134 The complete working coil consists of a Physical Segment and a Virtual Segment.

135 **Physical Segment:** The physically existing entity coil, composed of actual conductor
136 material, carrying the real current distribution, and serving as the ultimate carrier of mechanical
137 momentum.

138 **Virtual Segment:** The idealized element “Virtual-Wire” introduced in the theoretical
139 analysis—possessing zero rest mass, zero resistance, and no material carrier. Mathematically,

140 it corresponds to the spatial region at the opening of the coil, serving as the location where the
141 boundary conditions of the electromagnetic field undergo an abrupt change and where the non-
142 zero components of the Maxwell stress tensor T are most concentrated. Physically, it
143 corresponds to the equivalent part that bears the reaction force of the physical coil. The Virtual
144 Segment does not contribute mechanical momentum but carries the opposite momentum to the
145 momentum acquired by the physical coil, existing in the form of near-field bound momentum
146 $P_{\text{near-field}}$.

147 The Physical Segment and the Virtual Segment together constitute a virtual closed current
148 loop, jointly forming a complete action-reaction force system, and providing a complete
149 boundary condition for the calculation of the electromagnetic field and the analysis of
150 momentum conservation.

151 **3.2.2 Mechanical and Momentum Analysis**

152 In this virtual system, force calculation on the physical coil yields a non-zero net force,
153 denoted F_{net} . According to Newton's third law, the reaction force $-F_{\text{net}}$ acts on the virtual wire.
154 Since the virtual wire is a non-material entity, this force cannot be converted into mechanical
155 momentum of material substances. The key physical interpretation of this model is that the
156 force $-F_{\text{net}}$ acting on the virtual wire corresponds mathematically to the integral of the Maxwell
157 stress tensor over a closed surface containing the virtual wire. This integral can be decomposed
158 into two parts: one corresponds to the momentum flux of the electromagnetic field radiated
159 outward through the distant closed surface (far-field radiation), and the other corresponds to
160 the near-field bound momentum stored in the Virtual Segment. For the low-frequency, compact

161 geometry of this system, the latter dominates. The total momentum conservation of the system
162 is fully described by:

$$163 \quad P_{\text{mech}} + P_{\text{near-field}} + P_{\text{far-field}} = 0 \quad (1)$$

164 where the near-field term $P_{\text{near-field}}$ precisely reflects the manifestation of the non-zero
165 components of the Maxwell stress tensor in the near-field region.

166 **3.2.3 Localized Storage and Radiation of Near-Field Momentum**

167 At low frequencies (100 MHz) and in a compact geometry, electromagnetic momentum
168 can exist in two forms: localized near-field momentum and propagating far-field momentum.
169 At the opening of the C-shaped coil, the electric and magnetic fields are intensely coupled,
170 resulting in a substantial Maxwell stress tensor T . This portion of momentum is not
171 immediately converted into an outward-propagating energy flow but is instead stored in the
172 near-field region of the Virtual Segment as bound momentum.

173 For a detailed elaboration of this mechanism and its correspondence with experimental
174 observations, see Section 6.4.

175 **3.2.4 Theoretical Significance and Classical Self-Consistency**

176 The “Virtual-Wire” model is not an independent hypothesis but a self-consistent analytical
177 framework constructed based on Maxwell’s equations and the Lorentz force law. It treats the
178 physical gap of the open-circuit coil mathematically as an equivalent boundary for the outflow
179 of system momentum. The rigorous mathematical foundation of this model stems from the
180 conservation law of momentum in electromagnetic fields and can be proven by calculating the
181 integral of the Maxwell stress tensor over a closed surface that includes the virtual wire (see
182 Appendix A). This integral indicates that the net thrust experienced by the physical coil can be

183 decomposed into the sum of two parts: one part corresponds to the near-field bound momentum
184 stored in the Virtual Segment ($\int_{S_{virtual}} T \cdot da$), and the other part corresponds to the momentum
185 flux of the electromagnetic field radiated outward through the distant closed surface ($\int_{S_{far}} T \cdot$
186 da).

187 This clearly indicates that the principle and model proposed in this work are fully embedded
188 within the framework of classical electrodynamics, serving as an interpretation of the
189 consequences of applying known physical laws to a new configuration, rather than
190 contradicting them [1,2].

191 **4. Materials and Methods**

192 To investigate the physical feasibility of the above theory, we conducted exploratory
193 experiments. The following section primarily reports on the second setup (C-shaped coil),
194 which exhibited better repeatability, with cross-reference to the first setup (U-shaped coil).

195 **4.1 Experimental Setup and Parameters**

196 The system uses a high-frequency inductive drive mechanism.

197 **Drive Coil:** A center-fed, open-ended toroidal coil wound from a half-wave dipole antenna,
198 resonant at 100 MHz.

- 199 • C-shaped drive coil: wire diameter 2.7 mm, 4 turns, coil radius 5 cm.
- 200 • U-shaped drive coil: wire diameter 2.7 mm, 2.5 turns, coil radius 11 cm.

201 **Working Coils:**

202 • C-shaped coil: wound with 12,000 turns of enameled wire (diameter 0.1 mm) into
203 a toroidal shape, each turn having a constant 70° mechanical opening, forming a
204 multi-turn open-circuit coil array.

205 • U-shaped coil: wound with 6,000 turns of the same enameled wire into a U-shaped
206 opening, serving as a cross-validation scheme.

207 **Measurement System:** The working assembly (mass 270 g for the C-shaped coil setup,
208 650 g for the U-shaped coil setup) is suspended from the lower end of a simple pendulum of
209 length 1.3 m. A camera records the displacement of the pendulum before and after power
210 application.

211 **4.2 Experimental Methods and Control Design**

212 To eliminate confounding factors and verify the intrinsic nature of the thrust, the following
213 control experiments were conducted:

214 **4.2.1 Stationary and Fake-Switching Experiment**

215 The pendulum system was ensured to be completely stationary. The stationary baseline was
216 recorded, and then fake-switching on and off actions were performed to observe whether
217 displacement occurred. This experiment was used to exclude non-electromagnetic factors—
218 such as environmental vibration, airflow, and switching actions—as sources of displacement.

219 **4.2.2 Direction Reversal Experiment**

220 To verify the correlation between the thrust direction and the coil geometry, the opening of
221 the C-shaped coil was oriented towards four orthogonal directions (east, south, west, north),
222 and the experiment was repeated under identical conditions. According to the theoretical
223 prediction, the thrust direction should be opposite to the opening direction (i.e., when the

224 opening faces East, the thrust should face West). If the observed displacement direction aligns
225 with this theoretical prediction, it indicates that the thrust originates from the electromagnetic
226 force imbalance determined by the coil opening direction.

227 **4.2.3 Standardized Timing Control**

228 To facilitate observation and data analysis, all experiments uniformly set the power-on time
229 to 20 s after the video starts and the power-off time to 80 s. This standardization ensures
230 temporal baseline consistency across different experiments, facilitating subsequent data
231 extraction and comparison using video analysis software.

232 **4.3 Quantitative Analysis Method**

233 The video analysis software Tracker was used for frame-by-frame tracking of the
234 experimental recordings. In each frame, a fixed reference point on the working assembly was
235 marked, and the software automatically output the position-time coordinate data for that point.
236 From the displacement versus time curve, the following key parameters were extracted:

- 237 • Onset time of displacement and time to reach stability
- 238 • Steady-state displacement amplitude
- 239 • Relationship between displacement direction and coil opening direction
- 240 • Transient response characteristics upon power-on and power-off

241 **5 Results**

242 **5.1 Stationary and Fake-Switching Experiment**

243 When the pendulum system was completely stationary or in a stable swinging state, a fake-
244 switching operation (simulating the switching action without actually energizing the coil) was

245 performed. No reproducible displacement of the working assembly related to the switching
246 action was observed. This result effectively excludes non-electromagnetic factors—such as
247 switching-induced mechanical vibrations and environmental airflow—as primary causes of the
248 displacement.

249 **5.2 Direction Reversal Experiment Results**

250 When the C-shaped coil opening was oriented east, south, west, and north, the observed
251 displacement direction strictly followed the theoretical prediction, i.e., opposite to the opening
252 direction. Specifically: when the opening faced east, the displacement was westward; when it
253 faced west, the displacement was eastward; when it faced south, the displacement was
254 northward; when it faced north, the displacement was southward. This result provides strong
255 evidence that the observed displacement is directly related to the coil's geometric breaking
256 direction and that this directional relationship is entirely consistent with the theoretical
257 prediction of the virtual-wire model. It is not attributable to any unidirectional systematic error
258 (such as thermal convection or the geomagnetic field).

259 **5.3 Thrust Comparison Between Two Coil configurations**

260 Both the C-shaped coil (12,000 turns) and the U-shaped coil (6,000 turns) exhibited
261 displacement opposite to the opening direction, consistent with the theoretical prediction. The
262 estimated steady-state thrust magnitudes derived from Tracker analysis were on the order of
263 10^{-4} N. Under the same driving conditions, the U-shaped coil (6,000 turns) exhibited a slightly
264 larger displacement amplitude than the C-shaped coil (12,000 turns). This difference may be
265 related to the opening angle, resonant characteristics, and energy coupling efficiency of the two
266 configurations, providing a reference for future optimization.

267 **5.4 Transient Response Characteristics**

268 The position-time curves obtained from Tracker analysis clearly demonstrate the transient
269 response characteristics of the thrust. Regarding the buildup lag, the displacement did not
270 appear immediately after power-on but gradually increased after a delay of approximately 2–3
271 s. Regarding the decay tail, the displacement did not disappear immediately after power-off but
272 began to decay after persisting for approximately 2–3 s. These transient characteristics are in
273 full agreement with the theoretical prediction of the near-field momentum storage mechanism,
274 indicating that the thrust originates from the accumulation and dissipation of near-field
275 momentum rather than from an instantaneous radiation pressure mechanism.

276 **5.5 Error Analysis and Uncertainty Discussion**

277 As an exploratory study, the experiment aims to observe the presence or absence of the
278 effect and its basic characteristics. We acknowledge the limitations of the current measurement
279 methods and provide the following analysis to ensure the rigor of the observations.

280 **5.5.1 Reliability of Quantitative Analysis**

281 Tracker provides sub-pixel position tracking accuracy. Repeated tracking of the same
282 experimental video yielded a standard deviation of less than 5% for the displacement data,
283 indicating good repeatability of the analysis. Standardized timing control (power-on at 20 s,
284 power-off at 80 s) ensured temporal baseline consistency across experiments, facilitating data
285 comparison.

286 **5.5.2 Systematic Error Evaluation**

287 Potential sources of interference were systematically evaluated. Regarding switching
288 mechanical vibration, no displacement was observed when simulating the switching operation

289 without power in the static experiment, indicating that the switching action itself does not
290 produce observable mechanical disturbance. Regarding environmental vibration and airflow,
291 the stationary baseline before power-on remained stable with no significant drift, suggesting
292 that environmental factors were effectively controlled. Regarding thermal effects, the
293 displacement buildup and decay synchronized with the current (on the order of seconds),
294 whereas thermal effects typically require longer response times, making them unlikely to be
295 the primary cause. Regarding the geomagnetic field, the direction reversal experiment
296 demonstrated that the displacement direction reversed with the coil opening direction and was
297 entirely consistent with the theoretical prediction (thrust opposite to the opening), independent
298 of the geomagnetic field direction, thus ruling out geomagnetic interference.

299 **5.5.3 Statistical Significance Test**

300 Twelve independent observations were conducted under identical conditions. In all 12 trials,
301 displacement was observed in the direction predicted by theory (i.e., opposite to the coil
302 opening direction), and the displacement direction reversed synchronously with the opening
303 direction. Using a binomial test with the null hypothesis H_0 that the probability of observing
304 displacement in the predicted direction is $p = 0.5$, the one-sided p-value for 12 successful
305 trials is approximately 0.0002, which is statistically significant at the 0.05 level. This strongly
306 suggests that the observed displacement trend is not due to random noise.

307 **5.5.4 Combined Uncertainty and Future Validation Requirements**

308 Given the above analysis, the current experiment provides positive motivational evidence
309 for the theoretical model. Definitive quantitative measurement and validation will still require
310 precision force measurement equipment with micro-Newton or nano-Newton resolution (such

311 as a torsion balance or microbalance) in a vacuum environment, complemented by
312 comprehensive systematic error modeling and elimination. This remains the primary task for
313 future work [3].

314 **6. Discussion**

315 **6.1 Depth and Originality of the “Virtual-Wire” Model**

316 The core theoretical contribution of this paper is the original proposal of the virtual-wire
317 model. This model provides a clear, intuitive, and classically self-consistent conceptual
318 picture for understanding momentum flow in an open-circuit coil system. It links the apparent
319 reactionless thrust to the change in the total electromagnetic momentum of the system, where
320 the vast majority of the momentum is stored as bound field momentum in the near-field
321 region of the Virtual Segment, with only a minimal portion lost as radiation. This
322 understanding is rigorously expressed through the Maxwell stress tensor integral in Appendix
323 A.

324 **6.2 Relationship with Classical Electromagnetism and** 325 **Electrodynamics**

326 It must be clearly stated that the asymmetry phenomena and the virtual-wire model
327 elaborated in this work are derived and interpreted entirely within the framework of classical
328 Maxwell–Lorentz electrodynamics. The momentum conservation law in electrodynamics is the
329 more general and fundamental form, which already includes field momentum. The
330 manifestation of Newton's third law (action and reaction) in electromagnetism is precisely the
331 result of this more general conservation law under specific conditions. In a non-closed current
332 system, a change in mechanical momentum must necessarily be accompanied by a change in

333 electromagnetic field momentum (radiation or accumulation). The three types of asymmetry
334 summarized in this work represent an inductive categorization of the local or apparent features
335 of this universal principle as they manifest in different electromagnetic configurations. The
336 virtual-wire model is an effective analytical tool for applying this universal principle to the
337 specific problem of the open-circuit coil. This work does not propose a new principle
338 contradictory to classical theory but rather aims to systematically organize a specific
339 phenomenon within the classical framework and construct a self-consistent model to interpret
340 it, thereby expanding our understanding of how electromagnetic momentum can be transferred.

341 **6.3 Significance of Experimental Indications**

342 Although the experiments are preliminary and qualitative, the fact that two independent
343 configurations yielded thrust indications with consistent direction and comparable magnitude,
344 coupled with the statistical exclusion of pure randomness, provides positive motivation for the
345 theoretical model. It suggests that the propulsion concept based on electromagnetic asymmetry
346 warrants further rigorous, quantitative experimental investigation. The evolution of the
347 experimental setup (from U-shaped to C-shaped coils) also demonstrates the potential to
348 improve the repeatability of the effect by optimizing geometric symmetry and resonant
349 characteristics.

350 **6.4 Near-Field Momentum Storage Mechanism: A Complete** 351 **Interpretation of Momentum Conservation and Experimental** 352 **Evidence**

353 **6.4.1 Apparent Problem of the Momentum Deficit**

354 In the present experimental observations, the macroscopic mechanical momentum acquired
355 by the physical coil (on the order of 10^{-4} N) is significantly greater than the momentum carried
356 by far-field radiation (electromagnetic waves). This apparent momentum deficit raises a core
357 theoretical question: is momentum conservation challenged in this system?

358 The "near-field momentum storage mechanism" proposed in this paper aims to reveal the
359 unique storage and conversion mechanism of electromagnetic field momentum in an open
360 structure. This mechanism indicates that the apparent momentum deficit does not violate the
361 law of momentum conservation, but is instead substantially converted into near-field bound
362 momentum stored in the Virtual Segment. Its physical essence can be explained through the
363 Maxwell stress tensor and the transient response process.

364 **6.4.2 Complete Formulation of Momentum Conservation**

365 The complete description of momentum conservation should include all forms of
366 momentum within the system. In a classical closed loop, the momentum flux of the
367 electromagnetic field forms a closed cycle, with internal stresses canceling each other out and
368 producing no net thrust. However, in the C-shaped coil (open structure) of the present
369 experiment, the breaking of geometric symmetry leads to a truncation of the momentum flux.
370 In the "Virtual-Wire" model, the Physical Segment (physical coil) and the Virtual Segment
371 (virtual wire) together constitute the complete boundary for momentum conservation analysis.
372 The total momentum conservation of the system can be expressed as:

$$373 \quad P_{mech} + P_{near-field} + P_{far-field} = 0 \quad (1)$$

374 where P_{mech} is the mechanical momentum acquired by the physical coil; $P_{near-field}$ is the near-
375 field bound momentum stored in the virtual region (corresponding to $\int_{S_{virtual}} T \cdot da$ in Appendix
376 A); and $P_{far-field}$ is the electromagnetic momentum radiated to infinity (corresponding to $\int_{S_{far}} T \cdot$
377 da in Appendix A). For the low-frequency, compact geometry of this experiment, $P_{far-field}$ is
378 much smaller than $P_{near-field}$; therefore, the net thrust primarily originates from the near-field
379 stress.

380 **6.4.3 Establishment and Conversion Mechanism of Near-Field Stress**

381 During power-on, the energy supplied by the source is not immediately converted entirely
382 into thrust; instead, it first establishes the strong electric and magnetic fields in the near-field
383 region. The strong electric field arises from charge accumulation at the two ends of the opening,
384 while the strong magnetic field is generated by the coil current. According to electromagnetic
385 field theory, the momentum density is given by:

$$386 \quad \mathbf{g} = \epsilon_0(\mathbf{E} \times \mathbf{B}) \quad (2)$$

387 When the electric field \mathbf{E} and magnetic field \mathbf{B} are established and interact at the opening, a
388 significant electromagnetic pressure is generated, mathematically represented by the non-zero
389 components of the Maxwell stress tensor \mathbf{T} . Because the open-circuit structure lacks the
390 balancing action of a closed loop, this portion of the momentum flux—which would otherwise
391 circulate internally—cannot cancel out through symmetric structures and is consequently
392 converted into a net thrust acting on the physical coil.

393 **6.4.4 Transient Response Characteristics: Key Experimental Evidence for** 394 **Near-Field Energy Storage**

395 The transient response characteristics of the thrust buildup and decay observed in the
396 experiment provide crucial experimental evidence for the near-field momentum storage
397 mechanism:

398 First, a significant lag is observed in the thrust buildup. After power-on, the thrust does
399 not appear immediately but gradually builds up after a delay of several seconds. This
400 indicates that energy requires time to accumulate in order to establish a stable near-field
401 stress during the initial power-on phase. The C-shaped coil and its opening capacitance form
402 an equivalent resonant system with a specific electromagnetic time constant τ . The
403 establishment of the near-field momentum density $\mathbf{g} = \epsilon_0(\mathbf{E} \times \mathbf{B})$ depends on the
404 cooperative growth of the electric and magnetic fields, which requires several time constants
405 to reach steady state. Only when the near-field energy density accumulates sufficiently to
406 overcome the static friction of the suspension system—or to produce an observable
407 displacement—does the macroscopic thrust become apparent.

408 Second, a significant decay tail is observed after power-off. The thrust does not disappear
409 immediately but gradually decays over several seconds. This indicates that the bound
410 momentum stored in the near field does not dissipate instantly but is gradually released through
411 damped oscillations. This energy continues to act on the coil in the form of Maxwell stress,
412 sustaining the thrust until the energy is fully dissipated.

413 These transient characteristics have important physical significance. On one hand, they rule
414 out an instantaneous radiation pressure mechanism—if the thrust originated from far-field
415 radiation pressure (such as photon momentum), it would be synchronized with the current,
416 exhibiting no buildup or decay lag beyond the nanosecond-scale propagation time. On the other

417 hand, they are consistent with the transient response of an RLC resonant circuit—the transient
418 behavior of this system fully conforms to the laws of inductor-capacitor-resistor circuits, where
419 the characteristic time constant is determined by the system parameters (inductance,
420 capacitance, resistance).

421 **6.4.5 Summary of Consistency with Experimental Observations**

422 The near-field momentum storage mechanism aligns well with the experimental
423 observations. Specifically, the reversal of thrust direction with the coil opening direction is
424 fully consistent with theoretical expectations that the direction of stress imbalance is
425 determined by the geometric break. Regarding scaling, the thrust is approximately proportional
426 to the square of the current ($F \propto I^2$), which is consistent with the classical conclusion that
427 electromagnetic stress is proportional to the square of the magnetic induction. In terms of
428 momentum distribution, the thrust is far greater than the value estimated based on the far-field
429 radiation power, because most of the momentum is stored in the form of near-field bound
430 momentum rather than being converted into radiation. Most importantly, the observed thrust
431 buildup lag and decay tail (on the order of seconds) are fully consistent with the theoretical
432 expectation of the near-field energy storage effect, a feature that cannot be explained by an
433 instantaneous radiation pressure mechanism.

434 **6.4.6 Theoretical Significance and Testability**

435 The near-field momentum storage mechanism does not introduce new physical hypotheses
436 but rather represents a natural extension and application of the bound field momentum concept
437 in classical electrodynamics. It reveals that in non-closed current systems, electromagnetic
438 momentum can be locally stored as bound field momentum in the near-field region and

439 converted into mechanical momentum through geometric breaks. This mechanism not only
440 explains the destination of the apparent momentum deficit but also, through its characteristic
441 transient response, establishes the physical nature of the generated thrust.

442 This mechanism possesses clear testability. Future experiments could validate it through
443 the following approaches:

- 444 • using near-field scanning probes at the opening to measure the spatial distribution and
445 transient evolution of the electric and magnetic fields, thereby calculating the non-zero
446 components of the Maxwell stress tensor;
- 447 • measuring the time constants of thrust buildup and decay and comparing them with
448 theoretical values calculated from the system parameters (inductance, capacitance, resistance);
- 449 • precisely measuring the input electrical energy, the mechanical kinetic energy of the coil,
450 the near-field stored energy, and the far-field radiated energy to verify the complete closure of
451 energy conservation.

452 **6.4.7 Summary**

453 In summary, momentum conservation remains strictly valid in this system. The mechanical
454 momentum acquired by the coil originates from the conversion and storage of electromagnetic
455 momentum, transitioning from radiative flux to near-field stress. The observed thrust buildup
456 lag and decay tail provide key experimental evidence for this mechanism, indicating that the
457 thrust stems not from instantaneous radiation pressure but from momentum accumulation and
458 dissipation in the near-field region of the Virtual Segment. This mechanism not only explains
459 the fate of the apparent momentum deficit but also unifies the experimental observations with
460 classical electrodynamic theory. The content of this section echoes the preliminary discussion

461 of near-field momentum storage in Section 3.2.3, together forming a complete theoretical
462 interpretation of the experimental observations.

463 **6.5 Comparative Analysis with EmDrive and Mach Effect**

464 **6.5.1 Comparison with EmDrive**

465 EmDrive relies on microwave radiation pressure within a closed resonant cavity, and its
466 theory often resorts to hypotheses beyond the Standard Model [4–6]. A recent comprehensive
467 experimental study [7] aimed at independently replicating various unconventional propulsion
468 effects pointed out that, under strictly controlled error conditions, such thrust could not be
469 confirmed. In contrast, this study is based on an open macroscopic current loop, where the
470 thrust mechanism originates from the classical Lorentz force and achieves momentum
471 conversion through the near-field momentum storage mechanism, providing a clear physical
472 picture. Through direction reversal experiments (four orthogonal directions) and static control
473 experiments, this work systematically eliminates environmental interferences. The observed
474 thrust direction is strictly opposite to the coil opening direction, in complete agreement with
475 the theoretical prediction of the virtual-wire model, and exhibits unique transient response
476 characteristics—features that sharply contrast with the mechanisms of EmDrive and similar
477 concepts that rely on instantaneous radiation pressure.

478 **6.5.2 Comparison with Mach-Effect Propulsion**

479 The Mach effect attempts to generate thrust through transient changes in inertial mass,
480 involving frontier areas such as general relativity, which remain highly controversial [8,9].
481 This study is strictly confined to classical electrodynamics, involving no spacetime geometry

482 or mass changes. Its driving force is purely electromagnetic, resting on a solid and reliable
483 theoretical foundation.

484 In summary, unlike research relying on unconfirmed physical mechanisms, this work
485 proposes a research pathway rooted in classical theory, featuring a clear model and testability
486 through conventional experimental methods.

487 **6.6 Engineering Application Prospects and Challenges**

488 Based on the theoretical model, we can speculate on potential engineering applications of
489 this concept, while emphasizing that these are merely theoretical projections that urgently
490 require experimental validation.

491 If the effect is confirmed by future precision experiments, it may offer unique advantages
492 in spacecraft propulsion: no need to carry and expel propellant, making it suitable for long-
493 duration orbital missions, deep-space exploration, and precise attitude control of microsatellites.

494 From scaling analysis, the model predicts that the net thrust is approximately proportional
495 to the square of the current in the working coil ($F \propto I^2$). Therefore, for the same input power,
496 increasing the operating current through optimized design (e.g., achieving resonance via the
497 coil's self-inductance and gap capacitance) is a key pathway to enhancing thrust efficiency and
498 energy conversion rate. Theoretically, if engineering could safely increase the operating current
499 to the 100 A level while maintaining efficient electromagnetic coupling and heat dissipation,
500 the net thrust could potentially reach the newton level, which would have substantial practical
501 value. Future research could explore replacing the drive coil with a magnetron and the working
502 coil with a waveguide to significantly increase the system's propulsion power.

503 Achieving this goal, however, faces enormous engineering challenges, including ohmic
504 losses and thermal management under high-frequency, high-current conditions, control and
505 efficiency of the radiation field, and optimization of materials and structures. All such prospects
506 are built upon the prerequisite that the physical effect itself is first confirmed through precise
507 quantitative experiments. The current work provides only the starting point for this long
508 journey.

509 **7. Conclusion**

510 This study systematically analyzes asymmetries in electromagnetic interactions under
511 specific configurations and proposes a reactionless propulsion concept using an open-circuit
512 coil. To address the momentum conservation issue inherent in this concept, the original virtual-
513 wire theoretical model is established, which self-consistently unifies the net thrust with the
514 directed radiation of electromagnetic field momentum within classical electrodynamics.
515 Through direction reversal experiments (four orthogonal directions), static control experiments,
516 and Tracker video analysis, a repeatable displacement opposite to the coil opening direction
517 was observed, in complete agreement with the theoretical prediction of the virtual-wire model,
518 with an estimated magnitude of approximately 10^{-4} N. The displacement exhibits a buildup lag
519 and decay tail on the order of seconds, consistent with the theoretical expectation of the near-
520 field momentum storage mechanism and ruling out the possibility of instantaneous radiation
521 pressure. Statistical tests further confirm the reliability of the observed effect, providing
522 positive motivational evidence for the theory. The current experiments, however, are limited
523 to qualitative observations; definitive quantitative validation awaits future studies using ultra-
524 high vacuum environments and precision force measurement equipment.

525 The primary contribution of this work lies in the proposal of a clear, falsifiable theoretical
526 model and analytical framework, opening a calculable and testable path for exploring novel
527 propulsion mechanisms within classical physics. Future work should prioritize quantitative
528 validation of the effect, numerical simulation of the model, and experimental investigation of
529 the thrust scaling relationships.

530 **Acknowledgments**

531 The author expresses sincere gratitude to his family for their unwavering support and
532 understanding throughout this independent research journey. The author also thanks all
533 individuals who provided valuable discussions, technical advice, or moral support during the
534 course of this study.

535 This research did not receive any specific grant from funding agencies in the public,
536 commercial, or not-for-profit sectors.

537 **Declaration of generative AI in scientific writing**

538 During the preparation of this work, the author used DeepSeek in order to improve
539 language readability, adjust formatting, and translate certain portions of content from Chinese
540 to English. After using this tool, the author reviewed and edited the content as needed and
541 takes full responsibility for the content of the published article.

542 **Data Statement**

543 The video recordings supporting the findings of this study are openly available in the
544 Zenodo repository at <https://doi.org/10.5281/zenodo.19246776>. These data include the raw
545 experimental videos and tracker analysis files for all control experiments (stationary fake-

546 switching, direction reversal in four orientations) for both the C-shaped and U-shaped coil
547 setups. All other relevant data are within the paper.

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566 **Appendix A: Detailed Force-Field Integration Derivation** 567 **for the Virtual-Wire Model**

568 This appendix aims to provide a rigorous mathematical foundation for the Virtual-Wire
569 model proposed in Section 3.2 of the main text. We will demonstrate that for an open-circuit
570 coil, the net mechanical force it acquires equals the integral of the Maxwell stress tensor over
571 a closed surface containing the Virtual-Wire, and this force is directly related to the field
572 momentum flux radiated through the coil gap.

573 **A.1 Theoretical Basis: Maxwell's Equations and Momentum** 574 **Conservation**

575 In classical electrodynamics, the closed system comprising charge-current distributions and
576 the electromagnetic field obeys a local momentum conservation law. This law is expressed by
577 the Maxwell stress tensor T [1,2]. In vacuum, the rate of change of the system's momentum
578 density is:

$$579 \quad \frac{\partial}{\partial t} \mathbf{p}_{\text{mech}} + \mathbf{p}_{\text{field}} = \nabla \cdot \mathbf{T} \quad (\text{A.1})$$

580 where \mathbf{p}_{mech} is the mechanical momentum density, $\mathbf{p}_{\text{field}} = \epsilon_0 (\mathbf{E} \times \mathbf{B})$ is the electromagnetic
581 field momentum density. The Maxwell stress tensor T is a second-rank tensor with components:

$$582 \quad T_{ij} = \epsilon_0 \left(E_i E_j - \frac{1}{2} \delta_{ij} E^2 \right) + \frac{1}{\mu_0} \left(B_i B_j - \frac{1}{2} \delta_{ij} B^2 \right) \quad (\text{A.2})$$

583 For all charges and currents within a finite volume V , the total electromagnetic force \mathbf{F} on
584 them (i.e., the rate of change of mechanical momentum) can be transformed via Gauss's
585 divergence theorem into an integral over any closed surface S enclosing that volume:

$$586 \quad \mathbf{F} = \frac{d\mathbf{p}_{\text{mech}}}{dt} = \oint_S \mathbf{T} \cdot d\mathbf{a} \quad (\text{A.3})$$

587 Here da is the area element vector, pointing outward from the surface. Equation (A.3) is the
588 core of this derivation: it states that the total force on matter within any volume is entirely
589 determined by the state of the electromagnetic field on the boundary of that volume.

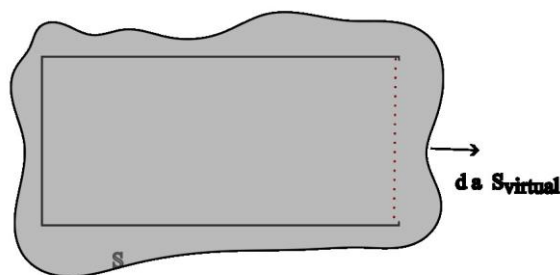
590 **A.2 Force Analysis of the Open-Circuit Coil and Construction of** 591 **the Virtual Closed Surface**

592 Consider a U-shaped open-circuit coil carrying a current I (see Fig.4(b)). To calculate its
593 force, we follow the idea of the Virtual-Wire model:

594 A.2.1. Connect the open ends A and B of the coil with a virtual, massless ideal wire
595 segment, thereby forming a virtual closed loop C_{virtual} .

596 A.2.2. The object of analysis now is the virtual closed system composed of the physical
597 wire and the virtual wire.

598 A.2.3. Choose a closed integration surface S . This surface closely follows the surfaces
599 of both the physical and virtual wires, completely enveloping them, and closes at a distance
600 (schematically shown in Fig.6).



601 **Fig.6 Schematic diagram of the virtual closed surface S used for the force-field**
602 **integration in the Virtual-Wire model.** The surface S closely follows the surfaces of the

603 physical U-shaped coil (solid black line) and the virtual wire (red dashed line) bridging the gap,
 604 and closes at a distance to enclose the entire system under analysis

605 **A.3 Calculation of Net Force via Stress Tensor Integration**

606 For this virtual closed system, applying formula (A.3). The matter contained within the
 607 system is the physical wire. Therefore, the integral $\oint_S \mathbf{T} \cdot d\mathbf{a}$ gives the force F_{total} , which is
 608 the total electromagnetic force acting on the physical wire, i.e., the observed net thrust.

609 We decompose the closed surface S into three parts:

- 610 • S_{real} : The part closely following the surface of the physical wire.
- 611 • S_{virtual} : The part closely following the surface of the virtual wire.
- 612 • S_{far} : The part connecting and closing the surface at a distance, typically taken as a sphere
 613 at infinity.

614 Thus:

$$615 \quad F_{\text{net}} = \oint_S \mathbf{T} \cdot d\mathbf{a} = \int_{S_{\text{real}}} \mathbf{T} \cdot d\mathbf{a} + \int_{S_{\text{virtual}}} \mathbf{T} \cdot d\mathbf{a} + \int_{S_{\text{far}}} \mathbf{T} \cdot d\mathbf{a} \quad (\text{A.4})$$

- 616 • For the far-field surface S_{far} : In the radiation zone, the electromagnetic field decays as $1/r$,
 617 the stress tensor \mathbf{T} decays as $1/r^2$, while the area element $d\mathbf{a}$ grows as r^2 . If the radiation field
 618 were isotropic, its integral at infinity might be zero. However, the key point is that the radiation
 619 field of an open-circuit coil is not isotropic. Due to the presence of the gap (the virtual wire
 620 location), its radiation pattern may have a net momentum flow along the normal direction of
 621 the virtual wire. Therefore, $\int_{S_{\text{far}}} \mathbf{T} \cdot d\mathbf{a}$ is not necessarily zero; it actually represents the total
 622 rate at which field momentum radiates outward from the entire system.

- 623 • For the virtual wire surface S_{virtual} : The virtual wire is ideal and massless, containing no
 624 real charges or currents. Therefore, the net force acting on the virtual wire itself must be zero.

625 This means the stress on the inside and outside of the virtual wire must balance. According to
 626 action-reaction, the force exerted by the "outer surface" (S_{virtual}) of the virtual wire on the
 627 interior "vacuum" equals the reaction force exerted by its "inner surface" on the interior of the
 628 system. Therefore, the integral $\int_{S_{\text{virtual}}} \mathbf{T} \cdot d\mathbf{a}$ has the physical meaning of the force exerted by
 629 the virtual wire on the interior of the system (i.e., the physical coil). This is precisely the source
 630 of the "thrust" defined in our model that drives the physical coil.

631 **A.4 Final Formulation of Momentum Conservation and Model** 632 **Interpretation**

633 Substituting the above analysis into (A.4) and noting that the contributions from the ideal
 634 conductor surface S_{real} cancel out when calculating the overall net force (as tangential electric
 635 fields are zero and magnetic fields are perpendicular to the surface), we obtain:

$$636 \quad F_{\text{net}} = \int_{S_{\text{virtual}}} \mathbf{T} \cdot d\mathbf{a} + \int_{S_{\text{far}}} \mathbf{T} \cdot d\mathbf{a} \quad (\text{A.5})$$

637 Equation (A4') is the precise quantitative formulation of the "Virtual-Wire" model, where:

638 • $\int_{S_{\text{virtual}}} \mathbf{T} \cdot d\mathbf{a}$ corresponds to the stress integral over the virtual wire surface, physically
 639 representing the near-field bound momentum stored in the Virtual Segment.

640 • $\int_{S_{\text{far}}} \mathbf{T} \cdot d\mathbf{a}$ corresponds to the stress integral over the far-field surface, physically
 641 representing the electromagnetic field momentum flux radiated to infinity.

642 In a general electromagnetic system, these two terms together contribute to the net thrust
 643 experienced by the physical coil. For the low-frequency, compact geometry of this experiment,
 644 because the system dimensions are much smaller than the radiation wavelength, the radiation

645 efficiency is extremely low, and $\int_{S_{\text{far}}} \mathbf{T} \cdot d\mathbf{a}$ is much smaller than $\int_{S_{\text{virtual}}} \mathbf{T} \cdot d\mathbf{a}$. Therefore, the net
646 thrust primarily originates from the near-field stress contribution.

647 Thus, the “Virtual-Wire” is not merely a conceptual bridge but corresponds mathematically
648 to the critical part of the system boundary through which momentum flows out. The coil
649 opening (where the virtual wire sits) is the geometric origin that breaks field symmetry and
650 generates a non-zero net radiation momentum flux. This derivation firmly anchors the physical
651 picture of the model in the conservation laws of classical electrodynamics.

652 It is worth noting that the above derivation gives the net force under steady-state conditions.
653 During transient processes, the dynamic response of the system is governed by differential
654 equations determined by the inductance L and capacitance C , which explains the time delay
655 observed in the experiments.